

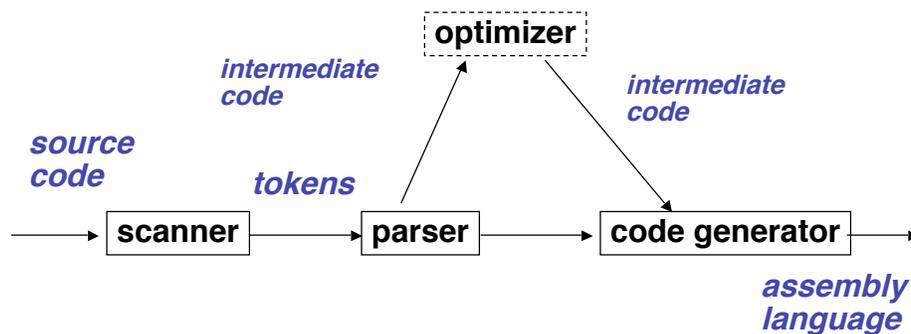
# Machine Independent Compiler Optimization

- What is classical machine independent optimization?
- Control flow graph, basic blocks, local opts
- Control flow abstractions: loops, dominators
- Four classical dataflow problems
  - Reaching definitions
  - Live variables
  - Available expressions
  - Very busy expressions

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# Phases of Compilation



**Optimization is a semantics-preserving transformation**

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## Example

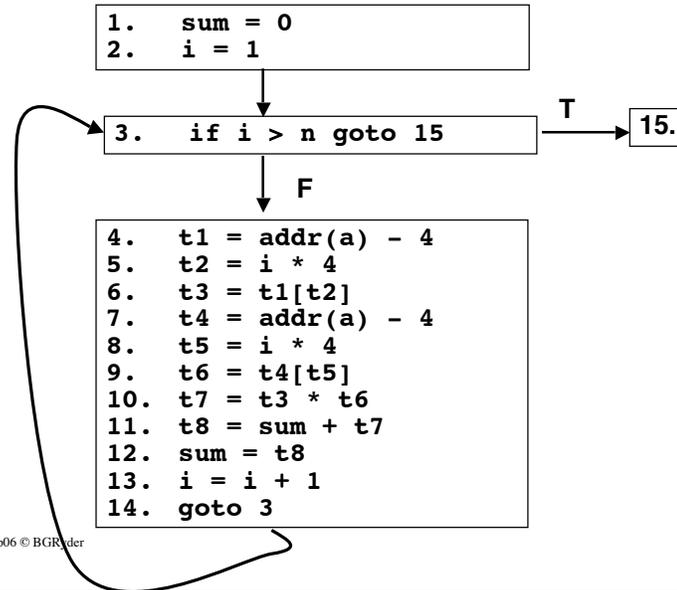
- To define classical optimizations using an example loop from Fortran scientific code
- Opportunities for these optimizations result from table-driven code generation

```
...
sum = 0
do 10 i = 1, n
10 sum = sum + a(i) * a(i)
...
```

## Three Address Code

```
1. sum = 0 }
2. i = 1   }
3. if i > n goto 15 → sum = 0; initialize loop counter
4. t1 = addr(a) - 4 } loop test, check for limit
5. t2 = i * 4 }
6. t3 = t1[t2] } a[i]
7. t4 = addr(a) - 4 }
8. t5 = i * 4 } a[i]
9. t6 = t4[t5] }
10. t7 = t3 * t6 } a[i] * a[i]
11. t8 = sum + t7 }
12. sum = t8 → increment sum
13. i = i + 1 → increment loop counter
14. goto 3
15.
```

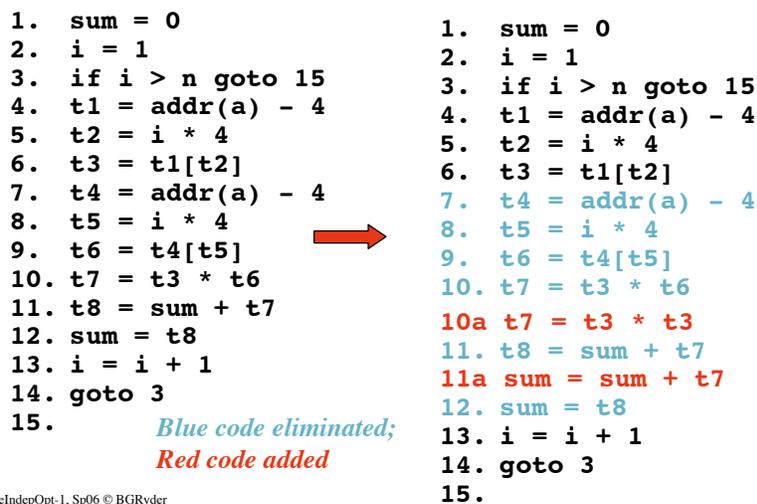
## Control Flow Graph (CFG)



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## Local Common Subexpression Elimination (CSE)



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## Invariant Code Motion

<pre>1. sum = 0 2. i = 1 3. if i &gt; n goto 15 4. t1 = addr(a) - 4 5. t2 = i * 4 6. t3 = t1[t2] 10a t7 = t3 * t3 11a sum = sum + t7 13. i = i + 1 14. goto 3 15.</pre>		<pre>1. sum = 0 2. i = 1 2a t1 = addr(a) - 4 3. if i &gt; n goto 15 4. t1 = addr(a) - 4 5. t2 = i * 4 6. t3 = t1[t2] 10a t7 = t3 * t3 11a sum = sum + t7 13. i = i + 1 14. goto 3 15.</pre>
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## Reduction in Strength

<pre>1. sum = 0 2. i = 1 2a t1 = addr(a) - 4 3. if i &gt; n goto 15 5. t2 = i * 4 6. t3 = t1[t2] 10a t7 = t3 * t3 11a sum = sum + t7 13. i = i + 1 14. goto 3 15.</pre>		<pre>1. sum = 0 2. i = 1 2a t1 = addr(a) - 4 2b t2 = i * 4 3. if i &gt; n goto 15 5. t2 = i * 4 6. t3 = t1[t2] 10a t7 = t3 * t3 11a sum = sum + t7 11b t2 = t2 + 4 13. i = i + 1 14. goto 3 15.</pre>
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## Test Elision and Induction Variable Elimination

<pre>1. sum = 0 2. i = 1 2a t1 = addr(a) - 4 2b t2 = i * 4 3. if i &gt; n goto 15 6. t3 = t1[t2] 10a t7 = t3 * t3 11a sum = sum + t7 11b t2 = t2 + 4 13. i = i + 1 14. goto 3 15</pre>		<pre>1. sum = 0 2. i = 1 2a t1 = addr(a) - 4 2b t2 = i * 4 2c t9 = 4 * n 3. if i &gt; n goto 15 3a if t2 &gt; t9 goto 15 6. t3 = t1[t2] 10a t7 = t3 * t3 11a sum = sum + t7 11b t2 = t2 + 4 13. i = i + 1 14. goto 3a 15</pre>
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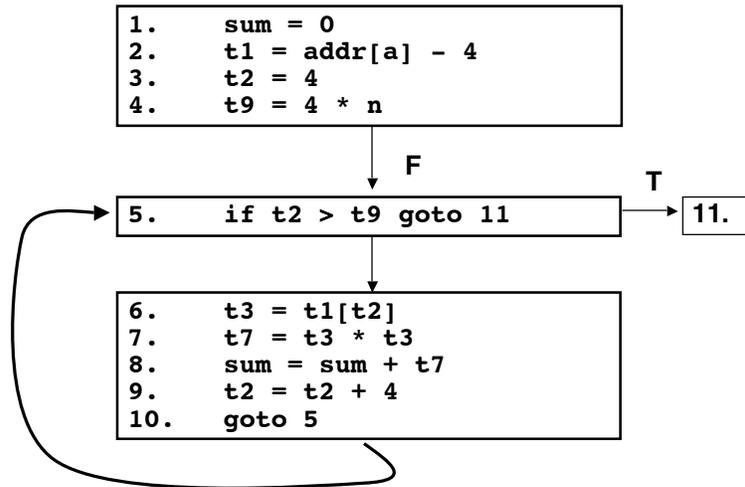
## Constant Propagation and Dead Code Elimination

<pre>1. sum = 0 2. i = 1 2a t1 = addr(a) - 4 2b t2 = i * 4 2c t9 = 4 * n 3a if t2 &gt; t9 goto 15 6. t3 = t1[t2] 10a t7 = t3 * t3 11a sum = sum + t7 11b t2 = t2 + 4 14. goto 3a 15</pre>		<pre>1. sum = 0 2. i = 1 2a t1 = addr(a) - 4 2b t2 = i * 4 2d t2 = 4 2c t9 = 4 * n 3a if t2 &gt; t9 goto 15 6. t3 = t1[t2] 10a t7 = t3 * t3 11a sum = sum + t7 11b t2 = t2 + 4 14. goto 3a 15</pre>
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## New Control Flow Graph



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## How to build CFG?

- Need to find basic blocks and possible branches between them
- Basic block *leader* statements
  - First program statement
  - Targets of conditional or unconditional goto's
  - Any statement following a conditional goto
- For each *leader*  $s$ , construct basic block  $B_s$  as all statements  $t$  reachable from  $s$  through straight-line code
- Eventually, any statements not included in some basic block are unreachable from program entry

*dead code*

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## Leader Statements

```
1. sum = 0    first program statement
2. i = 1
3. if i > n goto 15    conditional goto statement
4. t1 = addr(a) - 4    statement following
5. t2 = i * 4          conditional goto
6. t3 = t1[t2]
7. t4 = addr(a) - 4
8. t5 = i * 4
9. t6 = t4[t5]
10. t7 = t3 * t6
11. t8 = sum + t7
12. sum = t8
13. i = i + 1
14. goto 3
15.          branch
           target
```

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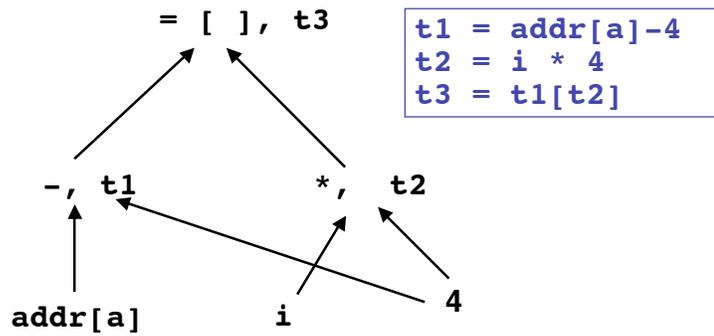
## Local CSE

- Accomplished while translating into three address code
- For each statement, form expression DAGs (for operand sharing)
  - Operands are children of operator nodes
  - Operand nodes can be used by more than one operator node
  - Intermediate results that must be stored cause creation of compiler temporaries
  - Multiple labels on same node mean CSE

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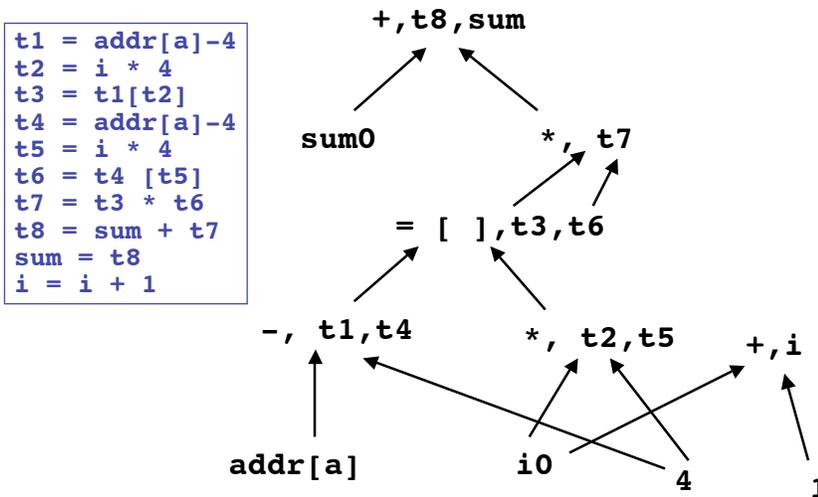
## Expression DAG construction



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## Expression DAG construction



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## DAG construction

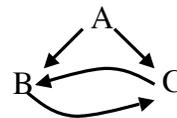
- How to add a subexpression into a partially constructed DAG?  $A = B + C$
- Is there a node already for  $B + C$ ?
  - If so, add A to its list of labels
  - If not,
    - Is there a node labeled B already? If not, create a leaf labeled B
    - Is there a node labeled C already? If not, create a leaf labeled C
  - Create a node labeled A for + with left child B and right child C

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## Flow of Control Abstractions

- **Dominator** A node  $x$  *dominates* a node  $y$  if and only if all paths from the control flow graph (CFG) entry node to  $y$  pass through  $x$ .
- **(Natural) Loop** Let  $(y,x)$  be a CFG edge such that  $x$  dominates  $y$ . Then all nodes on paths from  $x$  to  $y$  are in the loop defined by  $(y,x)$ .
  - $(y,x)$  is called a *back edge*
  - For *reducible* graphs, the set of back edges is unique
  - CFG is reducible if each loop can be entered through a single node
  - *Irreducible* means contains a subgraph

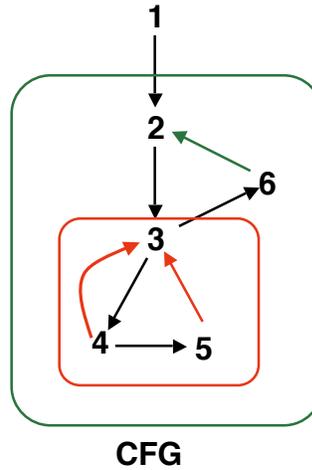


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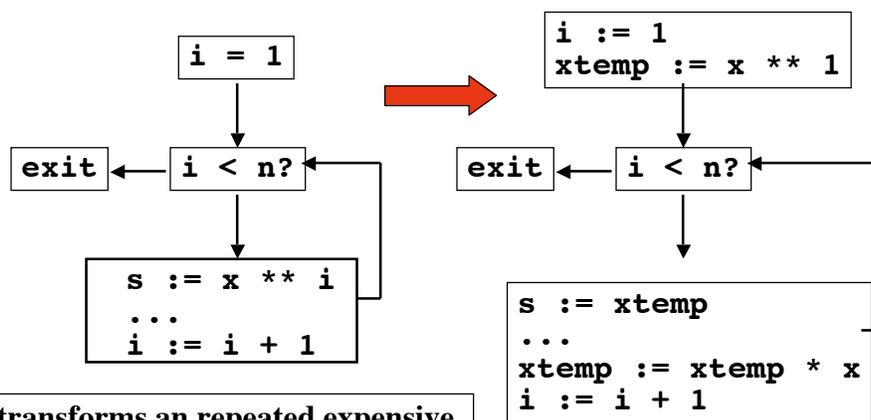
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# Loops

**Back edges:** (5,3), (4,3), (6,2)  
**Loop (5,3) = {3, 4, 5}**  
**Loop (4,3) = {3, 4}** } combined  
**Loop (6,2) = {2, 3, 4, 5, 6}**



# General Step in Strength Reduction



transforms an repeated expensive operation into a less expensive one

## General Code Motion

```
n := 1; k := 0; m := 3; read x;
while n ≤ 10 do
  if 2 + x < 5 then k := 5;
  if 3 + k = 3 then m := m + 2;
  n := n + k + m;
endwhile;
```

definitions within loop are barriers to code motion

## General Code Motion

```
n := 1; k := 0; m := 3; read x;
if 2 + x < 5 then k := 5; //move first
t1 := 3 + k = 3 //move second
while n ≤ 10 do
  if 2 + x < 5 then k := 5;
  if 3 + k = 3 then m := m + 2;
  if t1 then m := m + 2;
  n := n + k + m;
endwhile;
```

Why can't we move any  
more code out of the loop?

## Program Analysis

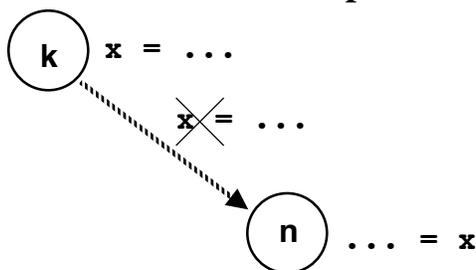
- **Performed at compile-time, deriving something about semantics of program**
- **Termed *flow analysis***
  - *Control flow analysis* reveals possible execution paths
    - Cannot tell actual feasibility of path. Why not?
  - *Dataflow analysis* determines information about modification, preservation, and use of data entities in a program

## Four Classical Data Flow Problems

- **Reaching definitions, Live uses of variables, Available expressions, Very Busy Expressions**
- **Def-use and Use-def chains, built from Reach and Live, used for many optimizations**
- **Avail enables global common subexpression elimination**
- **VeryB was used for conservative code motion**

## Reaching Definitions

- **Definition** A statement which may change the value of a variable
- A definition of a variable  $x$  at node  $k$  reaches node  $n$  if there is a definition-clear path from  $k$  to  $n$ .

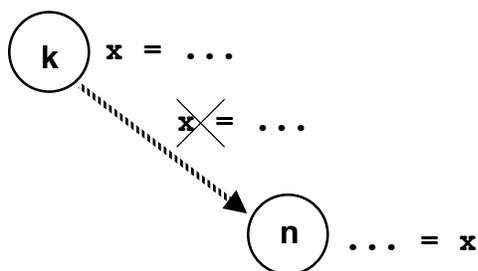


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## Live Uses of Variables

- **Use Appearance** of a variable as an operand of a 3 address statement
- A use of a variable  $x$  at node  $n$  is *live on exit* from node  $k$  if there is a definition-clear path for  $x$  from  $k$  to  $n$ .

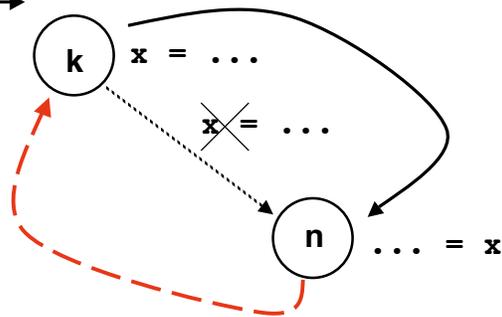


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## Def-use Relations

- **Use-def chain** links an use to a definition that reaches that use  $\dashrightarrow$
- **Def-use chain** links a definition to an use that it reaches  $\rightarrow$



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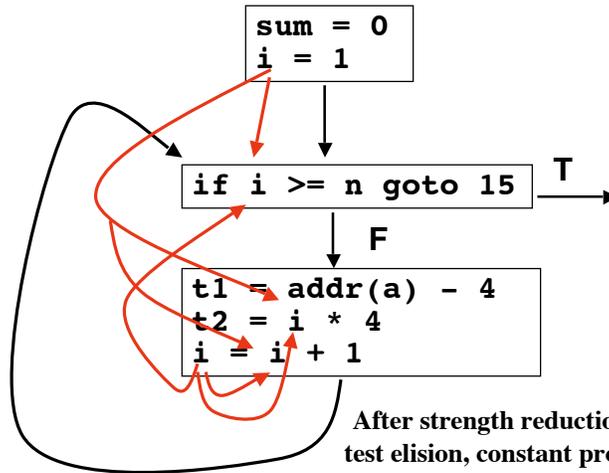
## Optimizations Enabled by Def-use

- **Dead code elimination (Def-use)**
- **Code motion (Use-def)**
- **Strength reduction (Use-def)**
- **Test elision (Use-def)**
- **Constant propagation (Use-def)**
- **Copy propagation (Def-use)**

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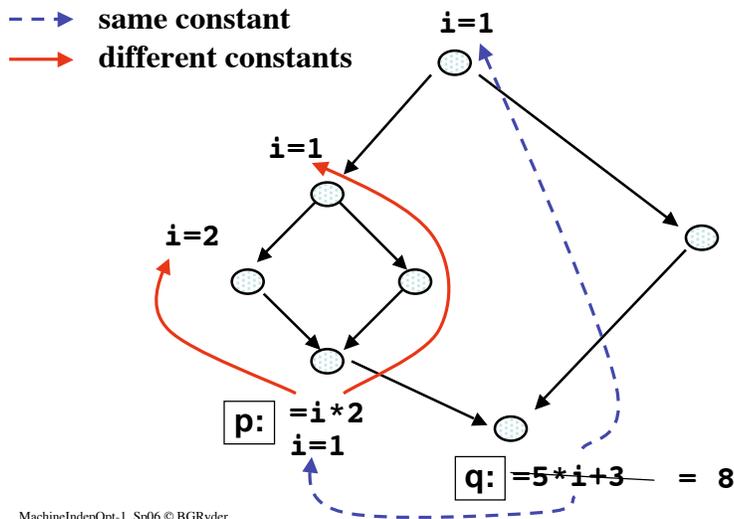
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## Dead Code Elimination



After strength reduction, test elision, constant propagation the def-use links for  $i=1$  disappear and it becomes dead code.

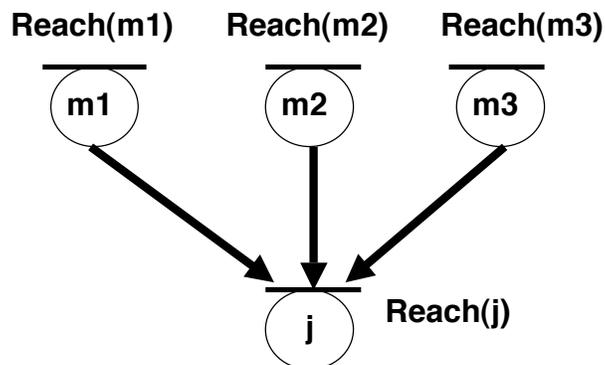
## Constant Propagation



## Classical Dataflow Problems

- How to formulate analysis from CFG to dataflow equations?
- *Forward* and *backward* dataflow problems
- *May* and *must* dataflow problems

## Reaching Definitions



forward, may  
dataflow problem

## Reaching Definitions Equations

$$\text{Reach}(j) = \bigcup_{m \in \text{Pred}(j)} \{ \text{Reach}(m) \cap \text{pres}(m) \cup \text{dgen}(m) \}$$

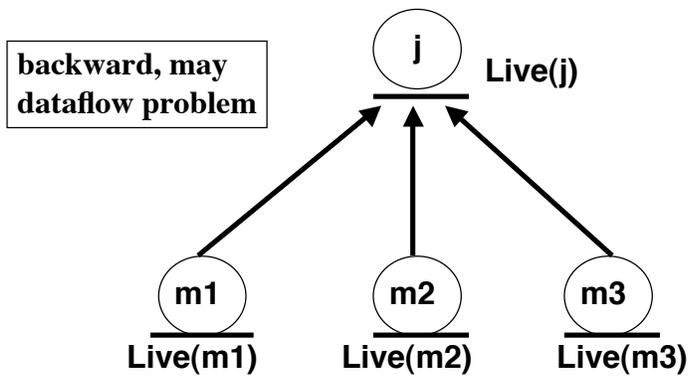
where:

$\text{pres}(m)$  is the set of defs preserved through node  $m$

$\text{dgen}(m)$  is the set of defs generated at node  $m$

$\text{Pred}(j)$  is the set of immediate predecessors of node  $j$

## Live Uses of Variables



## Live Uses Equations

$$\text{Live}(j) = \bigcup_{m \in \text{Succ}(j)} \{ \text{Live}(m) \cap \text{pres}(m) \cup \text{ugen}(m) \}$$

where

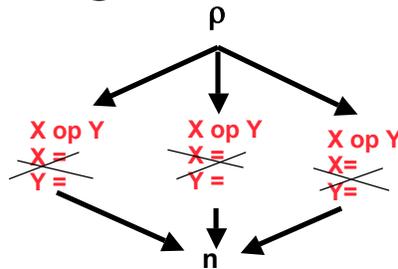
$\text{pres}(m)$  is the set of uses preserved through node  $m$   
(these will correspond to variables whose defs are preserved)

$\text{ugen}(m)$  is the set of uses generated at node  $m$

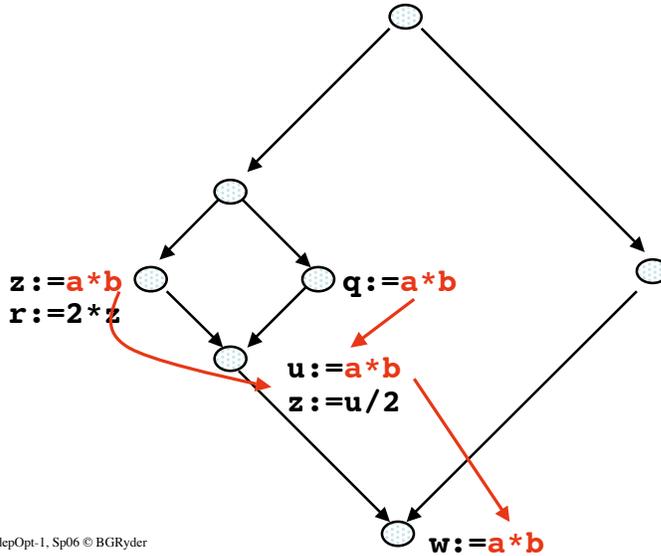
$\text{succ}(j)$  is the set of immediate successors of node  $j$

## Available Expressions

- An expression  $X \text{ op } Y$  is *available* at program point  $n$  if EVERY path from program entry to  $n$  evaluates  $X \text{ op } Y$ , and after every evaluation prior to reaching  $n$ , there are NO subsequent assignments to  $X$  or  $Y$ .



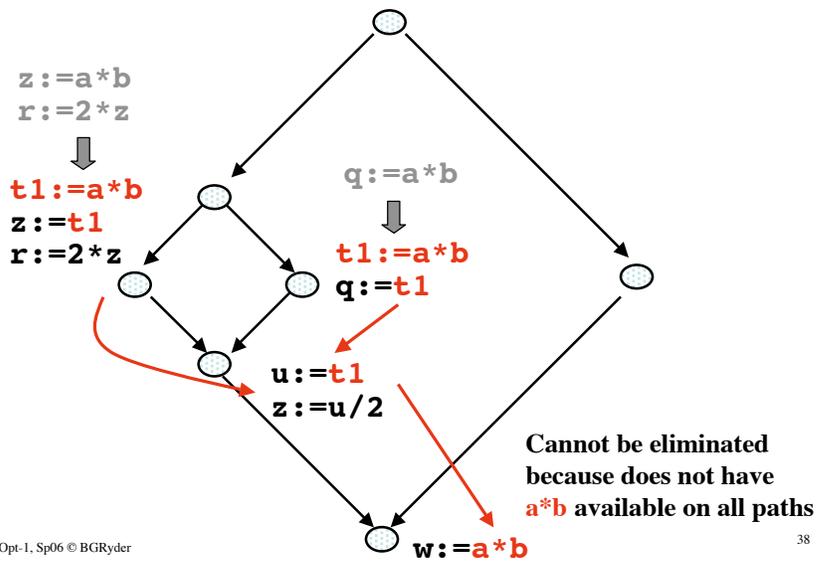
## Global Common Subexpressions



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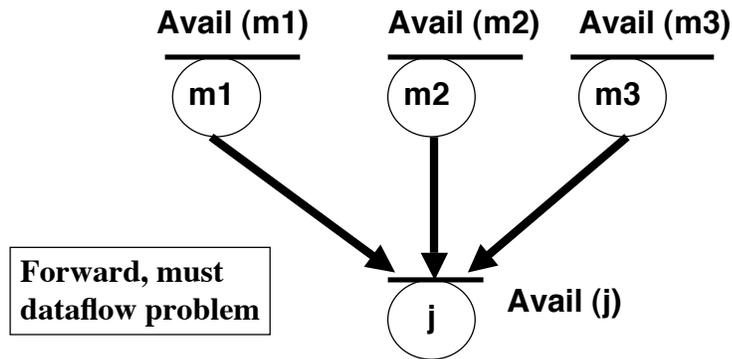
## Global CSE



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## Available Expressions



## Available Expressions Equations

$$\text{Avail}(j) = \bigcap_{m \in \text{Pred}(j)} \{ \text{Avail}(m) \cap \text{epres}(m) \cup \text{egen}(m) \}$$

where:

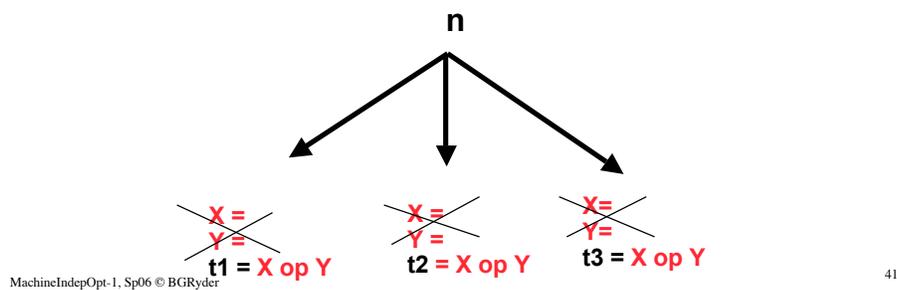
**epres(m)** is the set of expressions preserved through node  $m$

**egen(m)** is the set of (downwards exposed) expressions generated at node  $m$

**pred(j)** is the set of immediate predecessors of node  $j$

## Very Busy Expressions

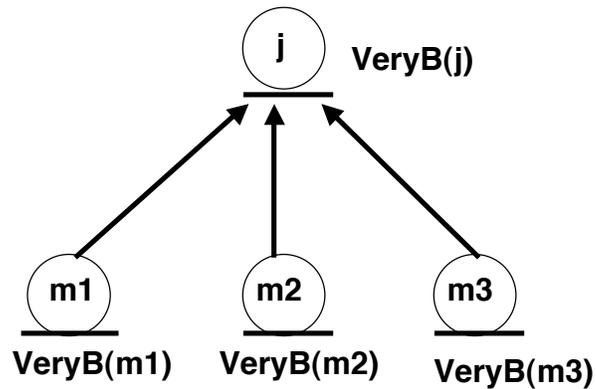
- An expression **X op Y** is very busy at program point  $n$ , if along EVERY path from  $n$ , we come to a computation of **X op Y** BEFORE any redefinition of **X** or **Y**.



## Code Hoisting

- **SAFETY:** Assume  $X \text{ op } Y$  is in  $\text{VeryB}(n)$  and  $n$  dominates all expression calculations that are hoisting candidates  $p$ .
- For every  $X \text{ op } Y$  at program point  $p$ , trace backwards from  $p$  to  $n$  to ensure there is a path from  $n \rightarrow p$  without any definitions of  $X$ ,  $Y$ ,  $X \text{ op } Y$
- Hoist (Calculate  $t = X \text{ op } Y$ ) at exit of node  $n$ ; change candidate calculations from  $s = X \text{ op } Y$  to  $s = t$ .
- **PROFITABILITY:** Check that copy propagation can eliminate all copies introduced in the previous step. If not, undo the hoist.

## Very Busy Expressions



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## Very Busy Equations

$$\text{VeryB}(j) = \bigcap_{m \in \text{Succ}(j)} \{ \text{VeryB}(m) \cap \text{epres}(m) \cup \text{vgen}(m) \}$$

where:

**epres(m)** is the set of expressions preserved through node  $m$

**vgen(m)** is the set of (upwards exposed) expressions generated at node  $m$

**succ(j)** is the set of immediate successors of node  $j$

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## Dataflow Problems

	<b>May Problems</b>	<b>Must Problems</b>
<b>Forward Problems</b>	<b>Reaching Defs</b>	<b>Available Exprs</b>
<b>Backward Problems</b>	<b>Live Uses of Variables</b>	<b>Very Busy Expressions</b>