Simulation Modeling

- Imitation of the operation of a real-world process or system over time
- Objective: to collect data as if a real system were being observed
- Data collected from the simulation are used to estimate the performance/dependability measures of the system

Discrete Event Simulation

- modeling of the system as it evolves over time by a representation in which the state variables change only at a countable number of points in time
- terminology:
 - <u>simulation clock</u>: a variable that gives the current value of the simulated time
 - <u>event</u>: an instantaneous occurrence which may change the state of the system

Simulation Terminology

- <u>event list</u>: a list (data structure) consisting of event records with each record containing the time of occurrence of a particular event, e.g., the arrival time, the departure time of a client
- <u>timing routine</u>: a subroutine which determines and removes the most imminent event record from the event list and advances the simulation clock to the time when the corresponding event is to occur
- <u>event routine</u>: a subroutine which updates the state of the system when a particular type of event occurs
 - one event routine for each type of event

Event Scheduling

- Determine the number of event types in the system, e.g., 1: arrival, 2: request for service, 3: service completion, 4: timer, etc.
- Place one or more initial event records in the event list, each containing

– event time, event type, customer class, etc.

- Determine the most imminent event in the event list (by the timing routine) in a loop until a specified stopping rule is satisfied
 - update the simulation clock when an event record is removed from the event list

Event Scheduling (cont.)

- Pass the control to the event routine corresponding to the event type
- Update the state of the system
- Gather the statistics if necessary
- Report the simulation results when the simulation is completed
 - For example
 - the average response time per client
 - the loss probability of calls
 - the system throughput
 - the average number of clients served over a time period

Simulation using smpl

- In the smpl view of systems, there are three types of entities:
 - resources: facilities
 - smpl provides functions to define, request, release and preempt (queueing) facilities
 - <u>tokens</u>: active entities of the systems, e.g., tasks, users (indistinguishable or distinguishable)
 - <u>events</u>: a change of state of any system entity is an event
 - smpl provides functions for scheduling and for selecting events in the order of event occurrence time

Structure of An smpl Program

Initialization routine;

timing control routine to select the most imminent event
from the event list (event clock is updated implicitly)
{
 event type 1: event routine for event type 1;
 event type 2: event routine for event type 2;

```
event type n: event routine for event type n;
}
```

statistics reporting routine;

Initialization Routine

```
smpl(m, s)
int m=0; /* always 0 */
char *s;
```

smpl provides seeds for 15 streams for generating random numbers. To collect a set of 15 sample values of a particular performance measure, one can invoke smpl() 15 times:

```
loop: repeat 15 times
{
    smpl(0, "hw1");
    }
One can also use stream(1), stream(2), etc. to specify the
stream number to be used in a simulation run
```

Facility Definition and Control

fd = facility(s, n)
char *s;
int n; /* # of servers */
=> define a queueing server with "n" servers;
smpl automatically manages enqueueing/dequeueing activities

```
r = request(fd_id, token_id, pri)
int fd_id; int token_id; int pri;
=> request a server of facility "fd_id" be reserved for the token
designated by "token_id" with priority "pri" (higher is better)
```

r=0: facility is reserved

r=1: facility is busy and the request is blocked in the queue ordered on priority

Facility Definition and Control

r = preempt(fd_id, tkn_id, pri)

int fd_id, tkn_id, pri;

=> same as request() except that it will preempt the server if it is busy serving a task with priority < "pri"

=> the event record corresponding to the preempted token (for the service completion event) is removed from the event list and a queue entry with the residual time is created

r=0: facility is reserved

r=1: facility is busy and the request is blocked in the queue ordered on priority

release(fd_id, tkn_id)
int fd_id; int tkn_id;

create an event of the same type and put it in the event list

=> release the facility and if the queue is not empty, reschedule an event with the event occurrence time at NOW for a blocked task, and reschedule an event with the event occurrence time at NOW+ the residual time for a preempted task.

Scheduling Events

schedule(event_id, te, tkn_id)

int event_id;

real te; /* time interval relative to the current time */

int tkn_id;

=> schedule the event with id "event_id" to occur at NOW+te

=> this essentially inserts an event record with the event occurrence time NOW+te into the event list

=> part of the information in the event record is event_id, tkn_id and the event occurrence time NOW+te

Example: schedule(2, 0.0, token_id) => schedule event type #2 associated with token id "token id" to

occur NOW

Timing Routine

cause(event_id, tkn_id)
int *event_id;

int *tkn_id;

=> remove the most imminent event from the event list and automatically advance the simulation clock to the event occurrence time

=> return the event number (type) and token id to the caller

Typically in the smpl program, we use a select statement on the event_id returned, so as to transfer the control to the appropriate event routine.

Canceling Events

cancel(event_id)
int event_id;
=> search the event list and remove the first event with the event
number = event_id

Get Current Simulation Time

t = real time()

=> return the current simulation clock value

=> real is a predefined type; it is the same as double in C

Status Functions

n= int inq(fd);

=> returning # of tokens currently in queue (not including the ones in service)

```
r = int status(fd)
=> r=0: facility is free; r=1: facility is busy
```

```
u = real U(fd)
=> mean # of tokens in service
```

n = real Lq(fd)
=> mean # of tokens in queue excluding the ones in service

b = real B(fd) => mean busy period = accumulated busy time/release counts 14

Random Variate Generation (rand.c)

r = real drand48(); /* available on UNIX machines */
=> return r in the range of (0,1)

```
r = real expntl(x)
```

double x;

=> return an exponentially distributed sample value with mean x

```
r = real uniform(a,b)
double a,b; => return a real number r in the range of (a,b)
```

```
k = int random(i,j)
int i, j; => return an integer k in the range of (i,j)
```

r = real normal(x,s)
=> return a normally distributed sample value with mean x and
standard deviation s
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Traces and Debugging

trace(n)

int n;

=> generate trace messages when a facility is defined, requested, or released, or whenever an event is scheduled or caused

n=0: trace is off

n=1: free-running, i.e., trace messages are generated continuously

- n=2: screen by screen running (press any key to resume tracing)
- n=3: message by message running (press any key to resume)

M/M/1 smpl program

```
#include "smpl.h"
main()
                                           case 2: /* request server */
real Ta=200, Ts=100, te=200000;
int customer=1, event, server;
smpl(0, "M/M/1 Queue");
server = facility("server",1);
schedule(1, 0.0, customer);
                                                  break;
while (time() < te)
  cause(&event, &customer);
  switch(event)
                                           report();
                                           }
    case 1: /* arrival */
     schedule(2,0.0, customer);
     schedule(1, expntl(Ta), customer);
     break;
```

if (request(server, customer,0)==0) schedule(3, expntl(Ts), customer); break; case 3: /* completion */ release(server, customer);

Confidence Interval and Level

- Suppose we collect N sample values Y₁, Y₂, ..., Y_N from N simulation runs
- sample mean $Y = (Y_1 + Y_2 + ... + Y_N)/N$
- true mean is μ
- Define 1- α as the probability that the absolute value of the difference between Y and μ is equal to or less than H $\}$ Confidence interval half-width

- that is, prob[Y-H
$$\leq \mu \leq Y+H$$
] = 1- α
Confidence interval Confidence 18

Confidence Interval and Level (cont.)

When Y₁, Y₂, ..., Y_N are independent random variables from a normal distribution with the mean μ, H is defined by H = t_{α/2;N-1}* σ/sqrt(N) where t is the student's t distribution and σ² is the sample variance given by σ² = Σ_i (Y_i - Y)² /(N-1) (and thus σ is the standard deviation).

Batch Mean Analysis by smpl



- Use a batch size m around 2000 observations to collect a sample value Y_i to justify the normal distribution assumption (by central limit theorem).
- Delete d = 0.1 m initial observations
- Collect k = 10 batches and compute the confidence interval half-width H
- If the desired accuracy has not been reached, collect another batch and compute H again. Repeat as necessary.

BMA: stat.c and bmeans.c

- Based on 95% confidence level ($\alpha = 0.05$) with 10% confidence accuracy (H/Y = 10%)
- The following three routines are provided:
- init_bm(d, m): d is number of initial observations to be discarded and m is the number of observations to collect one sample Y_i
- obs(y): y is the observation value generated out of a simulation run
 - if the returning value is 1, it means that the required confidence level and accuracy have been reached; otherwise, need to continue calling this function obs(y)
- civals(Y, H, k): Y, H and k are passed in by reference. This function returns the final result. 21

M/M/1 smpl program with BMA

```
#include "smpl.h"
#define TOKENS 1000
#define TRUE 1
#define FALSE 0
```

```
main()
```

```
case 1: /* arrival */
        ts[customer] = time();
        schedule(2,0.0, customer);
        if (++tk id >= TOKENS) tk id=0;
        schedule(1,expntl(Ta),tk id);
        break:
case 2: /* request server */
        if (request(server, customer,0)==0)
         schedule(3,expntl(Ts),customer);
        break;
case 3: /* release server */
        release(server, customer);
        if (obs(time()-ts[customer]) == 1)
          cont = FALSE:
        break:
   } /* end while */
civals(&mean, &hw, &nb);
printf("Y=%f; H=%f after %d batches\n",
      mean, hw, nb);
                                     22
}
```

Bmeans.c

#include "smpl.h"
#include "stat.c"

```
static int d,k,m,n;
static real smy,smY,smY2,Y, h;
```

```
init bm(m0,mb)
 int m0,mb;
  { /* set deletion amount & batch size */
   d=m0; m=mb; smy=smY=smY2=0.0;
   k=n=0;
obs(y)
real y;
   int r=0; real var;
   if (d) then \{d--; return(r);\}
   smy+=y; n++;
   if (n==m) then
   { /* batch complete: update sums & counts */
    smy/=n; smY+=smy; smY2+=smy*smy; k++;
```

```
printf("batch %2d mean = %.3f",k,smy);
  smy=0.0; n=0; /* reset batch variables */
  if (k \ge 10) then
  { /* compute grand mean & half width */
        Y = smY/k; var = (smY2-k*Y*Y)/(k-1);
        h=T(0.025,k-1)*sqrt(var/k);
        printf(", rel. HW = \%.3f",h/Y);
        if (h/Y \le 0.1) then r=1;
   }
      printf("\n");
  return(r);
civals(mean,hw,nb)
 real *mean,*hw; int *nb;
  { /* return batch means analysis results */
   *mean=Y; *hw=h; *nb=k;
```