Locating Faults Through Automated Predicate Switching

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Outline

- Motivation
- Approach
- Key Techniques
- Limitations
- Evaluation
- Conclusion

Motivation

Finding Bugs

- Program output deviates from the expected output
- Program crash

Techniques

Automated debugging techniques – potential state changes searching is expensive

🗆 Idea

- Switch outcome of some predicate at runtime correct erroneous output / eliminate crash – Important information
- Reduce the state search space runtime predicate switching

Motivation Example

- read(a,b);
 c = f(a,b);
- 2. c = 1(a, 0), 3. if c < 5
- 4. then x=a+b
- 5. else x=a-b
- endif
- 7. d = g(a,b);
 8. if d < 5
- 9. then y=a*b
- 10. else y=a/b
- 11. endif
- 12. output(x+y)

Why predicate Switching is a better approach?

- How to compute an output Two parts: Data Part, Select Part
- Data Part: Set of executed instructions which compute data values that are involved in computing output value. <1,4,5,9,10>
- Select Part: Set of predicates and statements that compute values used by the predicates. <1,2,7,3,8>
- > Location of fault code:
 - DP: dynamic data slices are relatively small
- SP: union the full dynamic slices, consider all possible state changes large
- Switching predicate Overcome this problem

Approach

- 5
- Step 1: Examine failing run, determine output deviation between incorrect and correct output, Locate execution instance *I_e* that produces the first erroneous output value.
- Step 2: Rerun program, generate Predicate Trace, perform predicate instance ordering LEFS/PRIOR
- Step 3: Search for a critical predicate, for each predicate instance(P), rerun the program, use instrumented program to switch P's output (only one predicate switch at a time), terminate search when program run succeeds
- Step 4: Based on critical predicate information, use Bidirectional Chop to locate the set of potentially faulty statements.

Predicate Instance Ordering

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- Last Executed First Switched Ordering (LEFS)

Based on the observation: execution of faulty code is often not far away from the fail point

- Prioritization-based Ordering (PRIOR)
 - Partition predicates into high and low priority subsets using failure- Inducing chops algorithm
 - > Arrange the predicate instances in the high priority subset in the order of increasing dependence distance rom the erroneous output
- Reference: N Gupta, H He, X Zhang, R Gupta, "Locating Faulty Code Using Failure-Inducing Chops", ASE 2005

```
1 main(int argc, char *argv[])
                                    Initial Inputs:
                                                  input1 := [1,5,8,2] - \times
2 {
                                                  input2 := [0,0,0,0] - \sqrt{}
3
     int red, green, blue, yellow;
                                    1-minimal failure-inducing inputs:
                                                                   input3 := [1,0,8,2] - \times
4
     int sweet, sour, salty, bitter;
                                                                    input4 : = [0,0,8,2] - \sqrt{5}
5
     int 11
6
                                                                                      argv[1] is different
                                    Incorrect outputs at line 24:
                                                                bitter, sweet, sour
7
     red = atoi (argv[1]);
                                    FwdSlice(input3, argv[1]) = \{7, 12, 13, 16, 17, 18, 21, 22, 24\}
8
     blue = atoi (argv[2]);
                                      Forward slice on argv[1] 🖊
9
     green = atoi (argv[3]);
                                    BwdSlice(input3, bitter@24) = \{7, 9, 12, 14, 15, 16, 17, 18, 21, 22, 24\}
10
     yellow = atoi (argv[4]);
                                    Failure-inducing Chop(input3, argv[1], bitter@24) = {7, 12, 16, 17, 18, 21, 22, 24}
11
                      Error: red = 5*red (
12
     red = 2*red;
     sweet = red*green;
13
                                    BwdSlice(input3, sweet@24) = \{7, 9, 12, 13, 24\}
                                    Failure-inducing Chop(input3, argv[1], sweet@24)={7, 12, 13, 24}
14
     sour = 0:
     i = 0:
15
                                      backward slices on bitter, sweet and sour 🔺
     while (i \leq red)
16
                                    BwdSlice(input3, sour@24)= {7, 9, 12, 14, 15, 16, 17, 18, 24}
                                    Failure-inducing Chop(input3, argv[1], sour@24)= {7, 12, 16, 17, 18, 24}
17
         sour = sour + green;
     i=i+1:
18
                                      Failure-Inducing chops algorithm :
19
                                      1. use the delta debugging algorithm isolate argv[1] as the
20
      salty = blue + yellow;
                                      minimal failure-inducing input difference
21
     vellow = sour + 1;
      bitter = yellow + green;
22
                                      2. Use dynamic slicing to locate fault code
23
24
     printf ("%d %d %d %d\n", bitter,sweet,
             sour,salty);
25
                                      for each of the faulty outputs contains the faulty
26
     return 0;
                                      statement 12
27 }
```

Dynamic Instrumentation

Divide a run into three phases, each phase has its unique instrumentation:

Phase One:

from the beginning of the execution to the predicate instance of interest, instrument a counter at a predicate. When it counts down to 0, it reached the interest predicate instance, enter phase 2.

Phase Two:

Instrument program switch the outcome of the interest predicate instance.

Phase Three:

Dynamic instrumenter – Valgrind cleans up all the instrumentation, complete the program run.

Limitations

Cannot handle complex bugs in the program – require switching multiple predicate instances

Cannot handle significant bugs – some functionality is missing from the program

Evaluation

Program	Found	Where Which		False +ves		
flex 2.5.319(a)	yes	gen.c @ 1813	0	0		
flex 2.5.319(b)	no	search failed				
flex 2.5.319(c)	no	search failed				
grep 2.5	yes	grep.c @ 532	0	0		
grep 2.5.1 (a)	yes	search.c @ 549	0	0		
grep 2.5.1 (b)	no	search failed				
grep 2.5.1 (c)	yes	dfa.c @ 2854	2	0		
make 3.80 (a)	yes	read.c @ 6162	143	1		
make 3.80 (b)	yes	remake.c @ 652	1	0		
bc-1.06	yes	storage.c @ 176	9	0		
tar-1.13.25	yes	prepargs.c @ 81	0	0		
tidy	yes	parser.c @ 3496	0	0		
s-flex-v4	yes	flex.c @ 2978	0	0		
s-flex-v5	no	search failed – error in DP				
s-flex-v6	no	search failed – error in DP				
s-flex-v7	yes	flex.c @ 9171	0	0		
s-flex-v8	yes	flex.c @ 11833	0	0		
s-flex-v9	yes	flex.c @ 5046	0	0		
s-flex-v10	yes	flex.c @ 2687	1	0		
s-flex-v11	yes	flex.c @ 3559	0	0		

Successful/Failed Searches

Where:

file name + source line number at which the switched predicate can be found

Which:

dynamic instance of the predicate that was switched

False +ves:

the number of dynamic predicate switches searched

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Program	PRIOR	
flex 2.5.319(a)	2.51 sec	
flex 2.5.319(b)	search failed (364 min)	
flex 2.5.319(c)	search failed (274 min)	
grep 2.5	8.83 sec	
grep 2.5.1 (a)	2.59 sec	
grep 2.5.1 (b)	search failed (4 min 28 sec)	
grep 2.5.1 (c)	4.46 sec	
make 3.80 (a)	26.92 sec	
make 3.80 (b)	30 min 37 sec	
bc-1.06	0.49 sec	
tar-1.13.25	2.83 sec	
tidy	0.90 sec	
s-flex-v4	8.76 sec	
s-flex-v5	search failed (96 min 20 sec)	
s-flex-v6	search failed (3 min 56 sec)	
s-flex-v7	3.34 sec	
s-flex-v8	34.35 sec	
s-flex-v9	34.51 sec	
s-flex-v10	2.76 sec	
s-flex-v11	2.56 sec	

Search time taken by PRIOR to locate the predicate instance switch

Locate potentially faulty code





Bidirectional Slice:

- the critical predicate outcome was wrong due to incorrect values used in its computation. backward slice of the critical predicate.
- changing the critical predicate outcome avoids the program crash forward slice of the critical predicate captures the code causing the crash.

failure-inducing chop:

- backward slice of an incorrect output value
- forward slice of the failure-inducing input difference

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-							
Program	EXEC	BIS (%EXEC)	F1Chop (%EXEC)	B1Chop (%EXEC)	Where		
flex 2.5.319(a)	1871	225 (12.03%)	256 (13.68%)	27 (1.44%)	Pred.		
flex 2.5.319(b)	2198	-	102 (4.64%)	102 (4.64%)	-		
flex 2.5.319(c)	2053	-	5 (0.24%)	5 (0.24%)	-		
grep 2.5	1157	88 (7.61%)	731 (63.18%)	86 (7.43%)	Down		
grep 2.5.1 (a)	509	111 (21.81%)	32 (6.29%)	25 (4.91%)	Down		
grep 2.5.1 (b)	1123	-	599 (53.34%)	599 (53.34%)	-		
grep 2.5.1 (c)	1338	453 (33.86%)	12 (0.90%)	12 (0.90%)	Up		
make 3.80 (a)	2277	1372 (60.25%)	739 (32.45%)	739 (32.45%)	Up		
make 3.80 (b)	2740	1436 (52.41%)	1104 (40.29%)	1051 (38.36%)	Up		
bc-1.06	636	267 (41.98%)	102 (16.03%)	102 (16.03%)	Up		
tar-1.13.25	445	117 (26.29%)	103 (23.15%)	45 (10.11%)	Down		
tidy	1519	541 (35.62%)	164 (10.80%)	161 (10.60%)	Up		
s-flex-v4	1631	37 (2.27%)	7 (0.43%)	7 (0.43%)	Pred.		
s-flex-v5	1882	-	544 (28.91%)	544 (28.91%)	-		
s-flex-v6	424	-	156 (36.79%)	156 (36.79%)	-		
s-flex-v7	2045	836 (40.88%)	63 (3.08%)	63 (3.08%)	Up		
s-flex-v8	610	280 (45.90%)	-	280 (45.90%)	Pred.		
s-flex-v9	1396	230 (16.48%)	112 (8.02%)	112 (8.02%)	Pred.		
s-flex-v10	1683	640 (38.03%)	574 (34.11%)	574 (34.11%)	Miss		
s-flex-v11	1749	27 (1.54%)	102 (5.83%)	27 (1.54%)	Up		

Location of fault code

Sizes of Bidirectional Slice / Failure-Inducing Chop / Bidirectional Chop

Conclusions

- Critical predicates be very often located in many real reported faulty programs
- They provide valuable clues to the cause of the failure and hence assist in fault location.

Questions?

Thanks!