

# CS 4204 Computer Graphics

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## *Meshes, Vertex Array and Displaylist*

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# Objectives

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***Introduce simple data structures for building polygonal models***

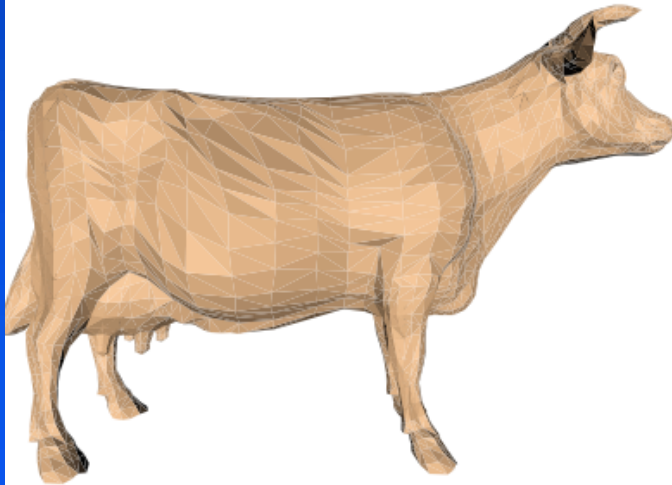
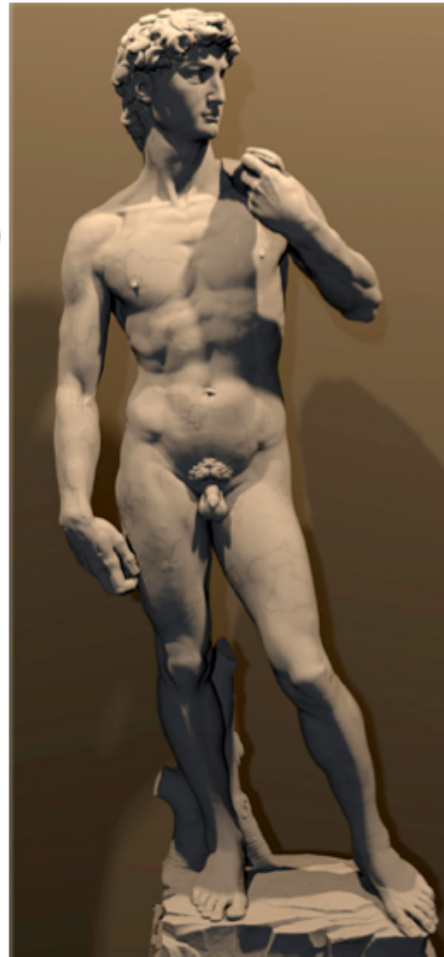
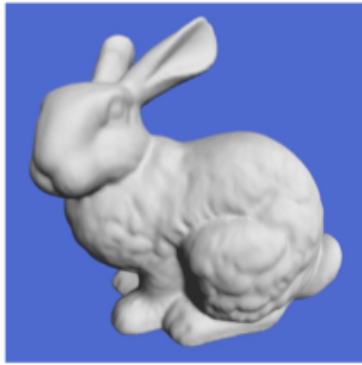
- Vertex lists
- Edge lists

***OpenGL vertex arrays***

***Display List in OpenGL***

***Wavefront OBJ and GLM library (Demo)***

# Mesh (Triangle meshes)



# Why Triangles?

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## *Generality*

- Any planar polygon can be triangulated
- When you give OpenGL a different polygon, it may well end up getting triangulated somewhere in the pipeline

## *Simplicity*

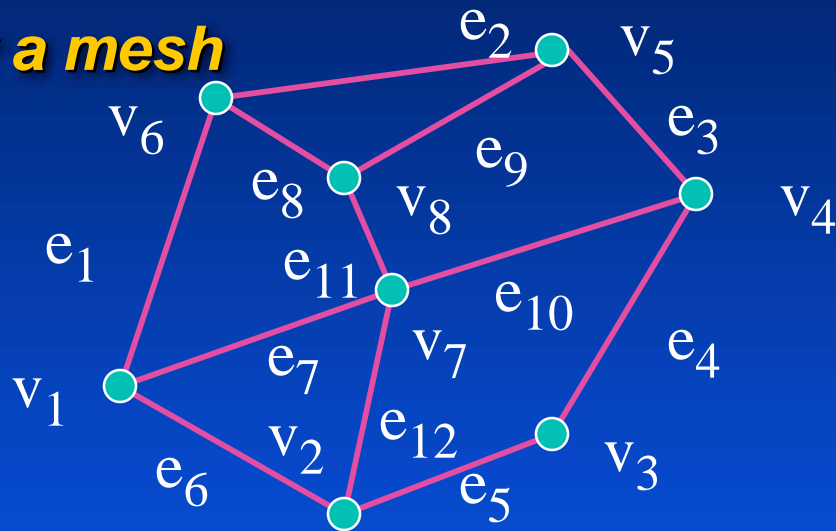
- Triangles have a nice mathematical structure we can exploit
- Impossible to specify a non-planar triangle
- Impossible to specify a non-convex triangle

## *Efficiency*

- By picking a standard primitive, we can design custom graphics hardware to be blisteringly fast
- Convexity makes rasterization much less complex

# Representing a Mesh

**Consider a mesh**



**There are 8 nodes and 12 edges**

- 5 interior polygons
- 6 interior (shared) edges

**Each vertex has a location  $v_i = (x_i, y_i, z_i)$**

# Simple Representation

*Define each polygon by the geometric locations of its vertices*

*Leads to OpenGL code such as*

```
glBegin(GL_POLYGON);  
    glVertex3f(x1, x1, x1);  
    glVertex3f(x6, x6, x6);  
    glVertex3f(x7, x7, x7);  
glEnd();
```

*Inefficient and unstructured*

- Consider moving a vertex to a new location
- Must search for all occurrences



# Geometry vs Topology

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***Generally it is a good idea to look for data structures that separate the geometry from the topology***

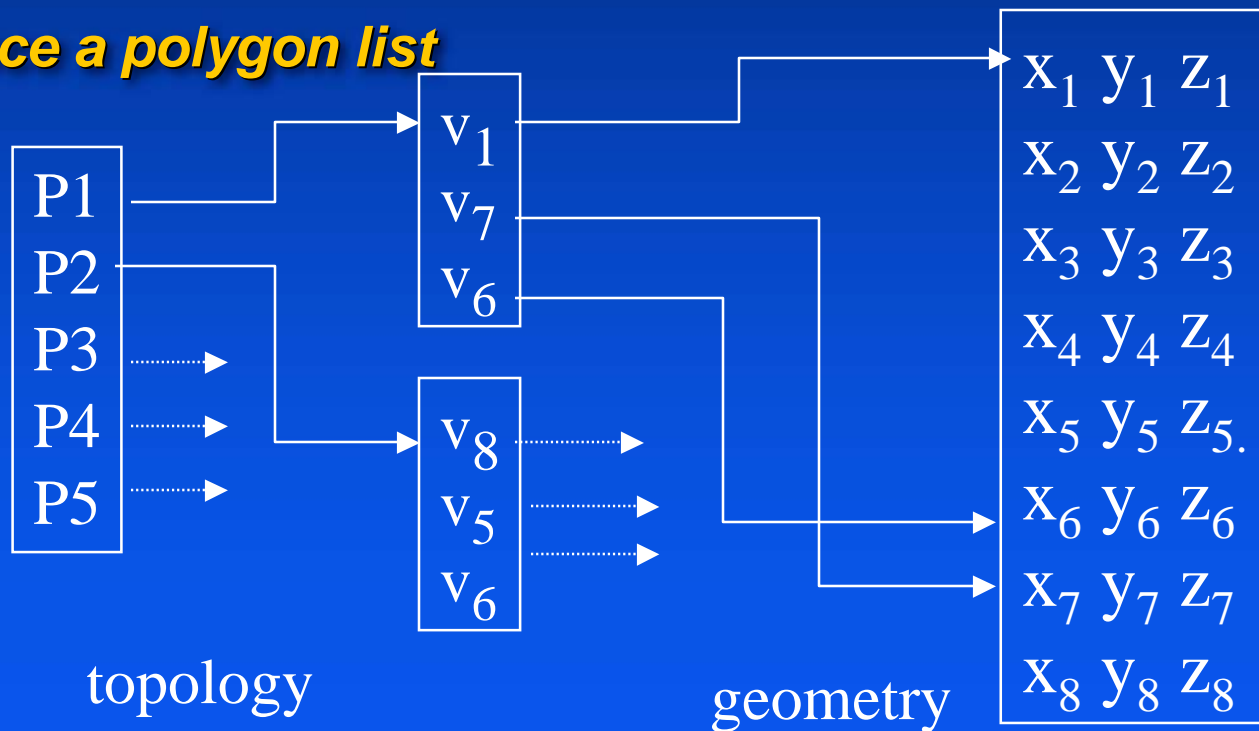
- Geometry: locations of the vertices
- Topology: organization of the vertices and edges
- Example: a polygon is an ordered list of vertices with an edge connecting successive pairs of vertices and the last to the first
- Topology holds even if geometry changes

# Vertex Lists

*Put the geometry in an array*

*Use pointers from the vertices into this array*

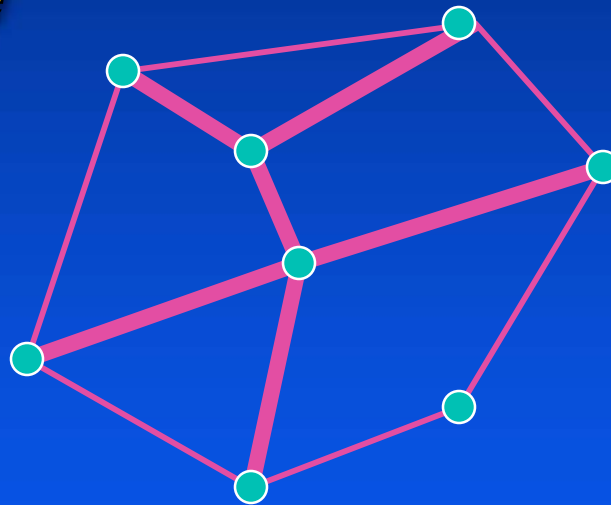
*Introduce a polygon list*





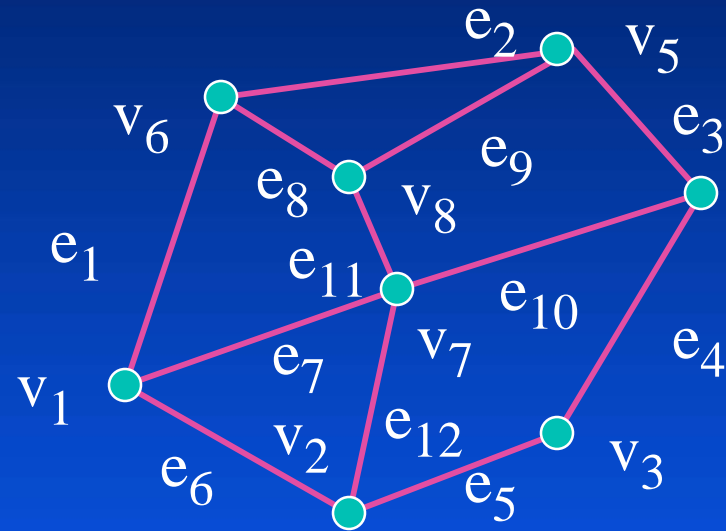
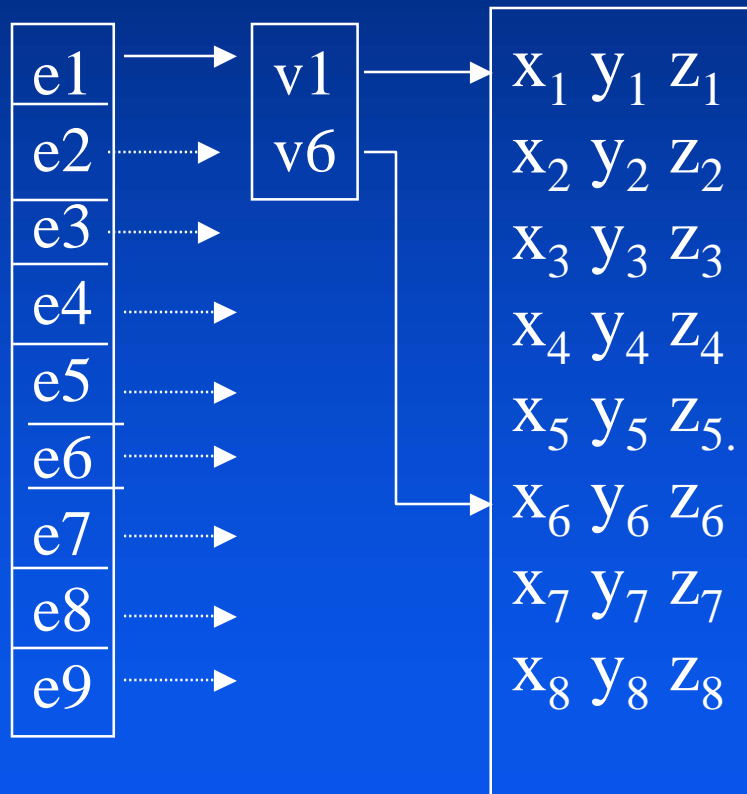
# Shared Edges

*Vertex lists will draw filled polygons correctly but if we draw the polygon by its edges, shared edges are drawn twice*



*Can store mesh by edge list*

# Edge List



Note polygons are not represented

# Modeling a Cube

Model a color cube for rotating cube program

Define global arrays for vertices and colors

```
GLfloat vertices[][3] = {{-1.0,-1.0,-1.0},{1.0,-1.0,-1.0},  
{1.0,1.0,-1.0}, {-1.0,1.0,-1.0}, {-1.0,-1.0,1.0},  
{1.0,-1.0,1.0}, {1.0,1.0,1.0}, {-1.0,1.0,1.0}};
```

```
GLfloat colors[][3] = {{0.0,0.0,0.0},{1.0,0.0,0.0},  
{1.0,1.0,0.0}, {0.0,1.0,0.0}, {0.0,0.0,1.0},  
{1.0,0.0,1.0}, {1.0,1.0,1.0}, {0.0,1.0,1.0}};
```

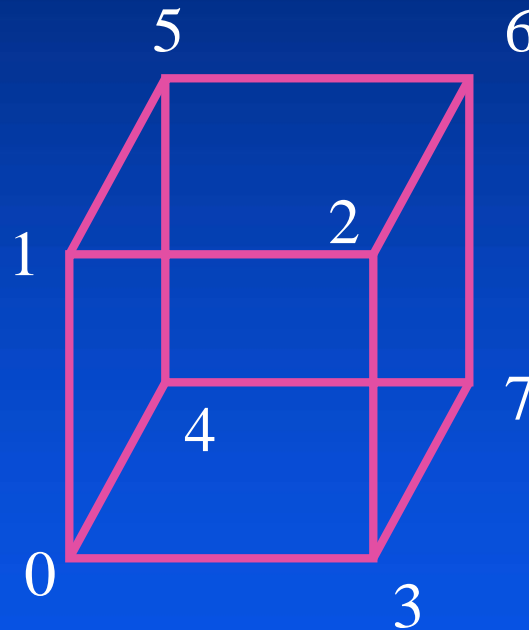
# Drawing a polygon from a list of indices

***Draw a quadrilateral from a list of indices into the array `vertices` and use color corresponding to first index***

```
void polygon(int a, int b, int c
, int d)
{
    glBegin(GL_POLYGON);
        glColor3fv(colors[a]);
        glVertex3fv(vertices[a]);
        glVertex3fv(vertices[b]);
        glVertex3fv(vertices[c]);
        glVertex3fv(vertices[d]);
    glEnd();
}
```

# Draw cube from faces

```
void colorcube( )  
{  
    polygon(0,3,2,1);  
    polygon(2,3,7,6);  
    polygon(0,4,7,3);  
    polygon(1,2,6,5);  
    polygon(4,5,6,7);  
    polygon(0,1,5,4);  
}
```



Note that vertices are ordered so that we obtain correct outward facing normals

# Efficiency

*The weakness of our approach is that we are building the model in the application and must do many function calls to draw the cube*

*Drawing a cube by its faces in the most straightforward way requires*

- 6 `glBegin`, 6 `glEnd`
- 6 `glColor`
- 24 `glVertex`
- More if we use texture and lighting



# Vertex Arrays

*OpenGL provides a facility called vertex arrays that allows us to store array data in the implementation*

*Six types of arrays supported*

- Vertices
- Colors
- Color indices
- Normals
- Texture coordinates
- Edge flags

*We will need only colors and vertices*

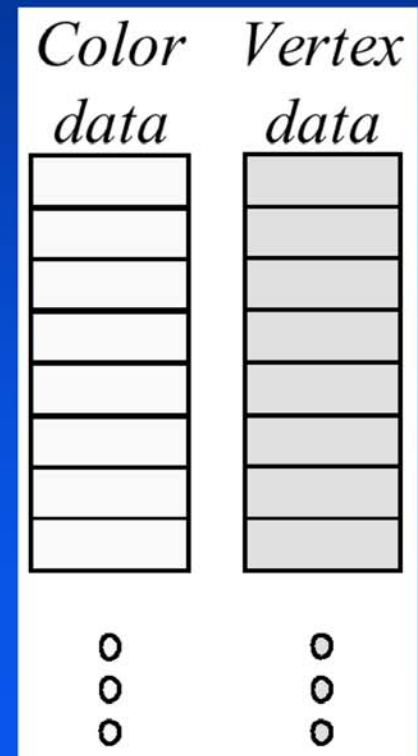
# Vertex Arrays

**Pass arrays of vertices, colors, etc to OpenGL in a large chunk**

```
glVertexPointer(3, GL_FLOAT, 0, coords)
glColorPointer(4, GL_FLOAT, 0, colors)
glEnableClientState(GL_VERTEX_ARRAY)
glEnableClientState(GL_COLOR_ARRAY)
glDrawArrays(GL_TRIANGLE_STRIP, 0, numVerts);
```

**All active arrays are used in rendering**

- On: glEnableClientState()
- Off: glDisableClientState()



# Vertex Arrays

***Vertex Arrays allow vertices, and their attributes to be specified in chunks,***

- Not sending single vertices/attributes one call at a time.

***Three methods for rendering using vertex arrays:***

- `glDrawArrays()`: render specified primitive type by processing  $nV$  consecutive elements from enabled arrays.
- `glDrawElements()`: indirect indexing of data elements in the enabled arrays. (shared data elements specified once in the arrays, but accessed numerous times)
- `glArrayElement()`: processes a single set of data elements from all activated arrays. As compared to the two above, must appear between a `glBegin()/glEnd()` pair.

# Vertex Arrays

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*glDrawArrays(): draw a sequence*

*glDrawElements(): methodically hop around*

*glArrayElement(): randomly hop around*

*glInterleavedArrays(): advanced call*

- can specify several vertex arrays at once.
- also enables and disables the appropriate arrays

*Read Chapter 2 in Redbook for details of using vertex array*

# Initialization

*Using the same color and vertex data, first we enable*

```
glEnableClientState(GL_COLOR_ARRAY);
```

```
glEnableClientState(GL_VERTEX_ARRAY);
```

*Identify location of arrays*

```
glVertexPointer(3, GL_FLOAT, 0, vertices);
```

3d arrays

stored as floats

data contiguous

data array

```
glColorPointer(3, GL_FLOAT, 0, colors);
```



# Mapping indices to faces

- ***Form an array of face indices***

```
GLubyte cubeIndices[24] = {0,3,2,1,2,3,7,6  
    0,4,7,3,1,2,6,5,4,5,6,7,0,1,5,4};
```

- ***Each successive four indices describe a face of the cube***

- ***Draw through `glDrawElements` which replaces all `glVertex` and `glColor` calls in the display callback***



# Drawing the cube

## Method 1:

```
for(i=0; i<6; i++) glDrawElements(GL_POLYGON, 4,  
                                GL_UNSIGNED_BYTE, &cubeIndices[4*i]);
```

what to draw      number of indices

format of index data

start of index data

## Method 2:

```
glDrawElements(GL_QUADS, 24,  
              GL_UNSIGNED_BYTE, cubeIndices);
```

Draws cube with 1 function call!!

# Immediate Mode vs Display Lists

## *Immediate Mode Graphics*

- Primitives are sent to pipeline and display right away
- No memory of graphical entities

## *Display Listed Graphics*

- Primitives placed in display lists
- Display lists kept on graphics server
- Can be redisplayed with different state
- Can be shared among OpenGL graphics contexts (in X windows, use the `glXCreateContext()` routine)

# Immediate Mode vs Retained Mode

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*In immediate mode, primitives (vertices, pixels) flow through the system and produce images. These data are lost. New images are created by reexecuting the display function and regenerating the primitives.*

*In retained mode, the primitives are stored in a display list (in “compiled” form). Images can be recreated by “executing” the display list. Even without a network between the server and client, display lists should be more efficient than repeated executions of the display function.*



# Display Lists

## **Creating a display list**

```
GLuint id;
void init( void )
{
    id = glGenLists( 1 );
    glNewList( id, GL_COMPILE );
    /* other OpenGL routines */
    glEndList();
}
```

## **Call a created list**

```
void display( void )
{
    glCallList( id );
}
```

Instead of `GL_COMPILE`, `glNewList` also accepts constant `GL_COMPILE_AND_EXECUTE`, which both creates and executes a display list.

If a new list is created with the same identifying number as an existing display list, the old list is replaced with the new calls. No error occurs.

# Display Lists

## ***Not all OpenGL routines can be stored in display lists***

- If there is an attempt to store any of these routines in a display list, the routine is executed in immediate mode. No error occurs.

## ***State changes persist, even after a display list is finished***

## ***Display lists can call other display lists***

## ***Display lists are not editable, but can fake it***

- make a list (A) which calls other lists (B, C, and D)
- delete and replace B, C, and D, as needed



# Some Routines That Cannot be Stored in a Display List

Some routines cannot be stored in a display list. Here are some of them:

all `glGet*` routines

`glIs*` routines (e.g., `glIsEnabled`, `glIsList`, `glIsTexture`)

`glGenLists`            `glDeleteLists`            `glFeedbackBuffer`

`glSelectBuffer`    `glRenderMode`            `glVertexPointer`

`glNormalPointer`   `glColorPointer`    `glIndexPointer`

`glReadPixels`        `glPixelStore`            `glGenTextures`

`glTexCoordPointer`                    `glEdgeFlagPointer`

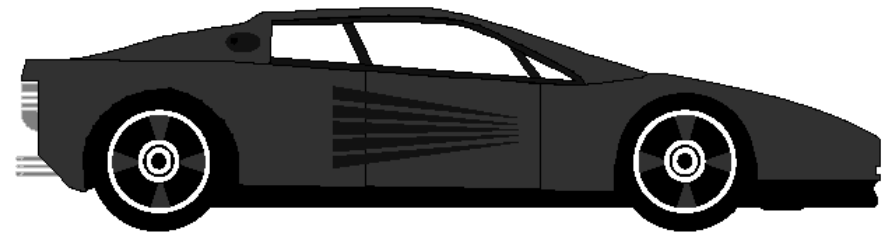
`glEnableClientState`                    `glDisableClientState`

`glDeleteTextures`                    `glAreTexturesResident`

`glFlush`                    `glFinish`

# An Example

```
glNewList( CAR, GL_COMPILE );  
    glCallList( CHASSIS );  
    glTranslatef( ... );  
    glCallList( WHEEL );  
    glTranslatef( ... );  
    glCallList( WHEEL );  
    ...  
glEndList();
```



# Why use Display lists or Vertex Arrays?

***May provide better performance than immediate mode rendering***

- Both are principally performance enhancements. On some systems, they may provide better performance than immediate mode because of reduced function call overhead or better data organization
  - *format data for better memory access*
- Display lists can also be used to group similar sets of OpenGL commands, like multiple calls to `glMaterial()` to set up the parameters for a particular object

***Display lists can be shared between multiple OGL contexts***

- reduce memory usage or multi-context applications