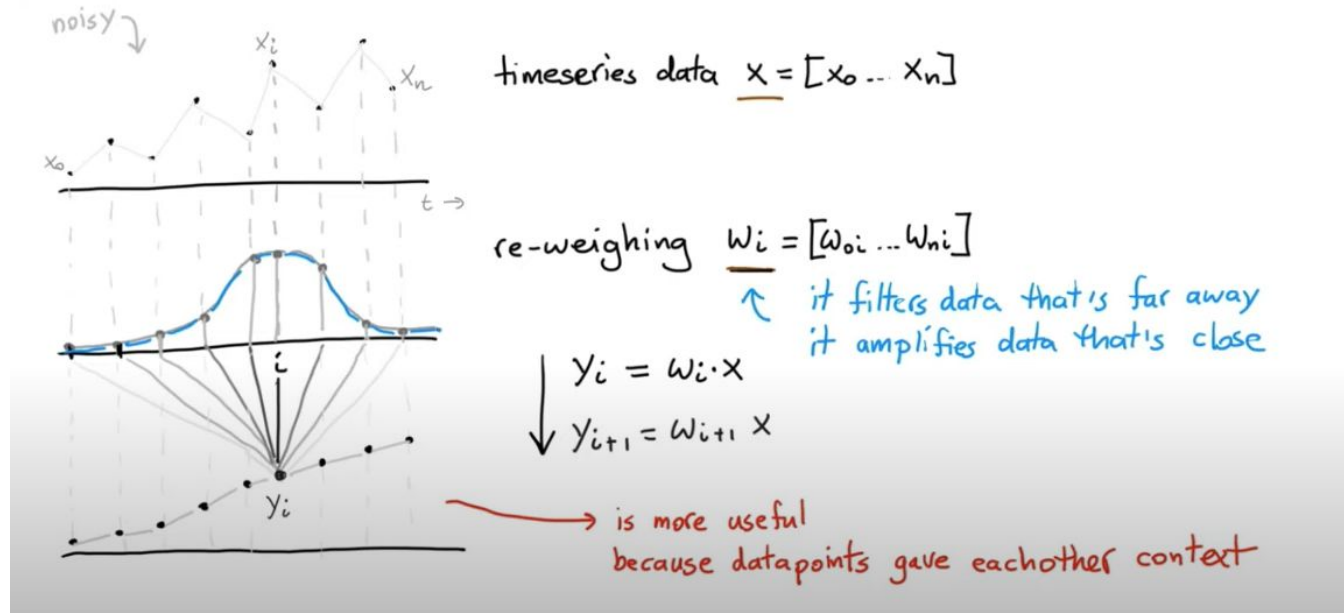


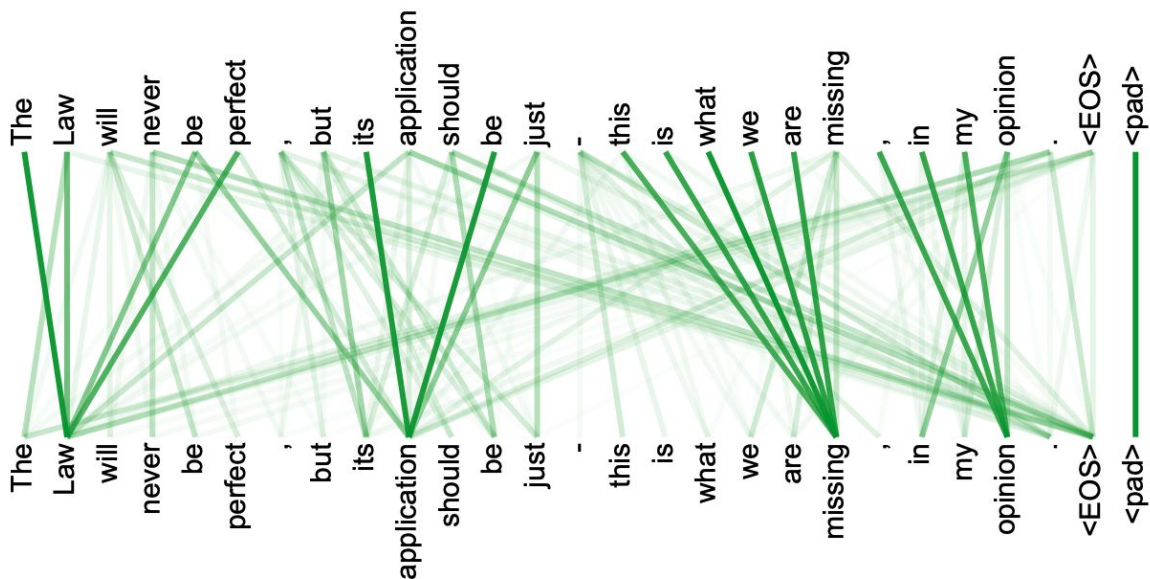
OSCAR: Object-Semantics Aligned Pre-training for Vision-Language Tasks

Presentation by Amun Kharel
CS 6804: Multimodal Vision
Spring 2023
Instructor: Dr. Chris Thomas

Attention Mechanisms

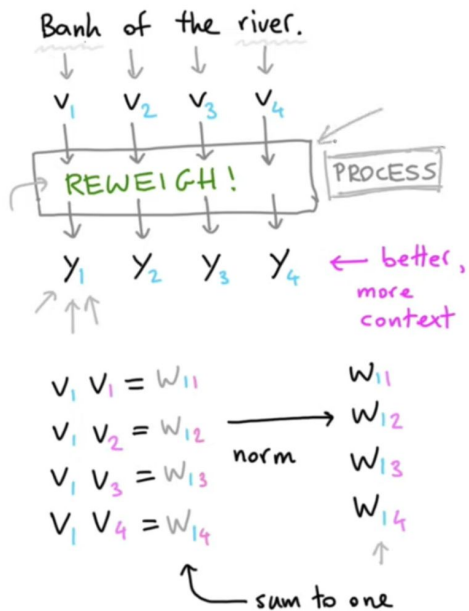


Self-Attention



Ashish Vaswani, Noam Shazeer, Niki Parmar, Jakob Uszkoreit, Llion Jones, Aidan N. Gomez, Lukasz Kaiser, and Illia Polosukhin. 2017. Attention Is All You Need. CoRR abs/1706.03762, (2017). Retrieved from <http://arxiv.org/abs/1706.03762>

Self-Attention

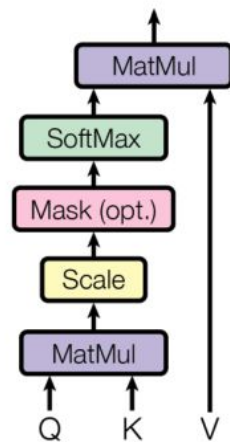


$$w_{11}v_1 + w_{12}v_2 + w_{13}v_3 + w_{14}v_4 = y_1$$

$$w_{21}v_1 + w_{22}v_2 + w_{23}v_3 + w_{24}v_4 = y_2$$

$$w_{31}v_1 + w_{32}v_2 + w_{33}v_3 + w_{34}v_4 = y_3$$

$$w_{41}v_1 + w_{42}v_2 + w_{43}v_3 + w_{44}v_4 = y_4$$

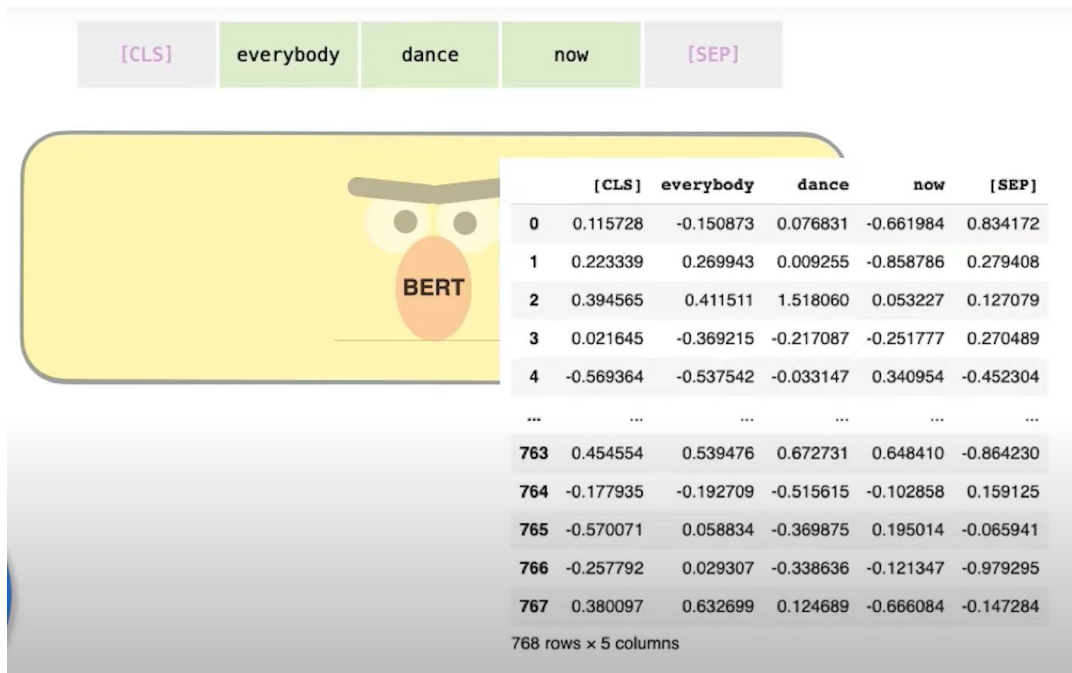


Application of BERT

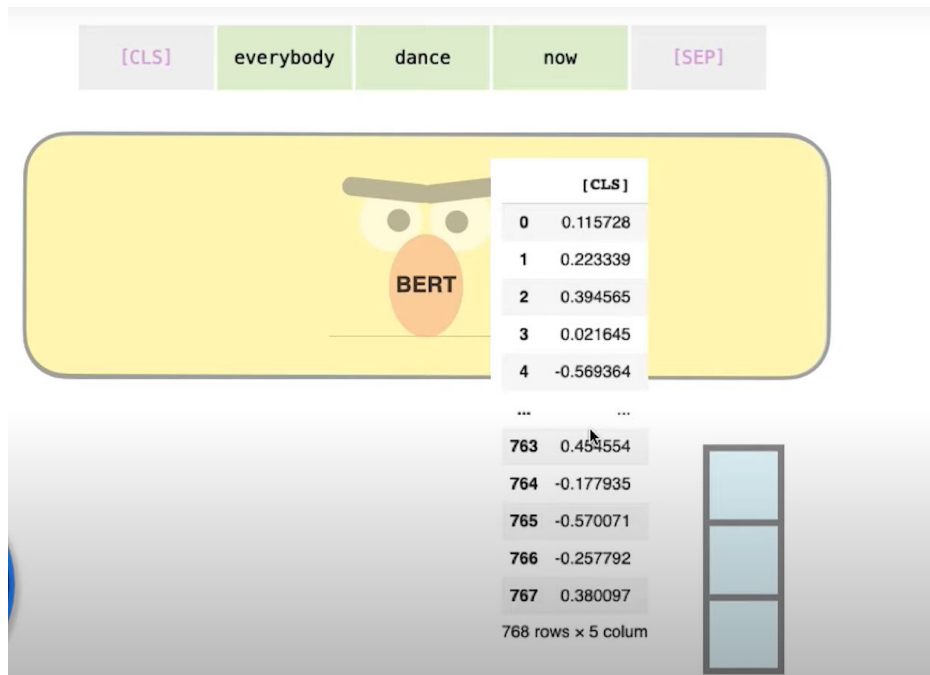


- ❖ Text Encoding
- ❖ Response Selection
- ❖ Text Summarization
- ❖ Question Answering
- ❖ Similarity Retrieval
- ❖ And More...

High-Level Overview of BERT



High-Level Overview of BERT



Simple Search Engine Using BERT



<https://ialammar.github.io/illustrated-bert/>

Hyperion

Dune

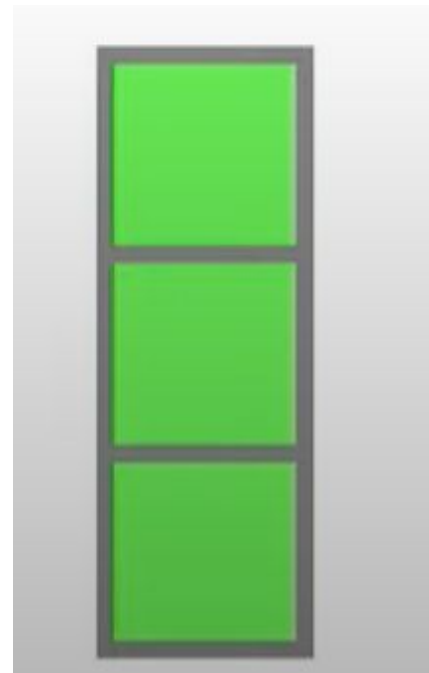
The Matrix

Simple Search Engine Using BERT

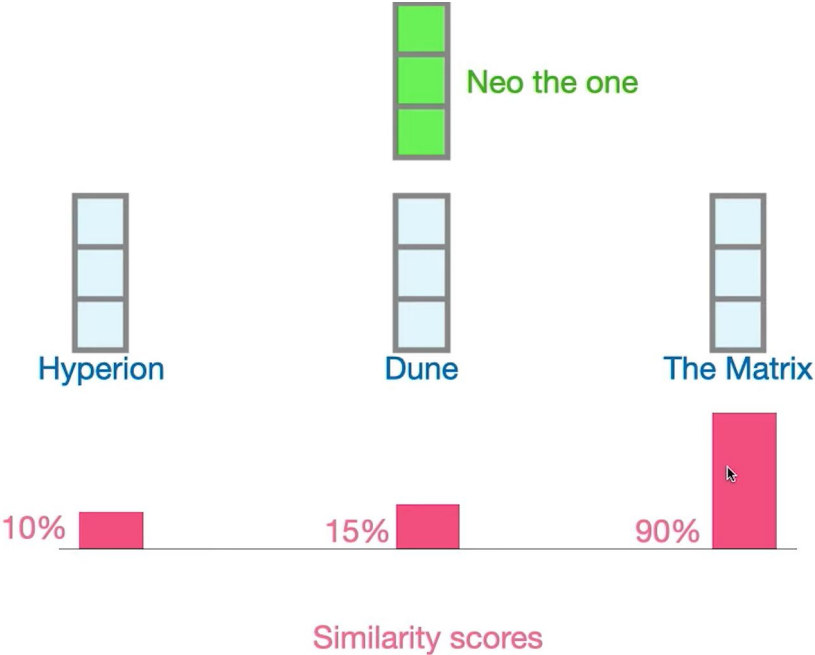
The logo for 'Yougle' is displayed in a multi-colored font: 'Y' is blue, 'o' is red, 'u' is yellow, 'g' is green, and 'l' is red. A small blue arc is positioned to the left of the 'Y', and a small blue underline is under the 'l'.

Yougle

🔍 Neo the one



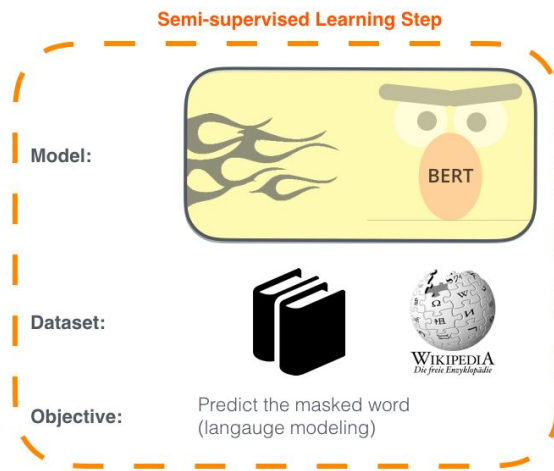
Simple Search Engine Using BERT



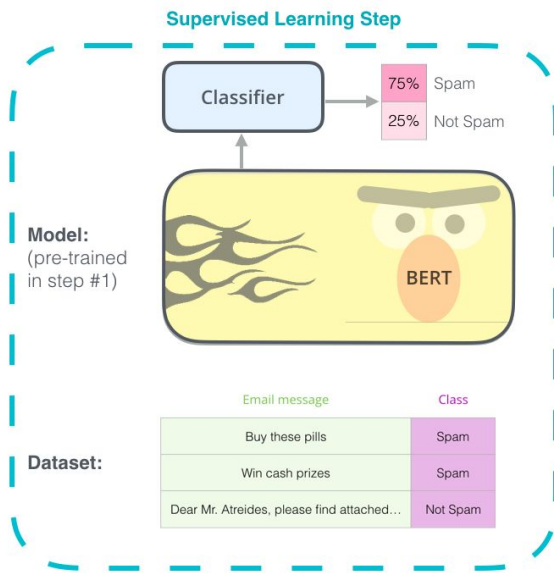
Use Cases of BERT

1 - **Semi-supervised** training on large amounts of text (books, wikipedia..etc).

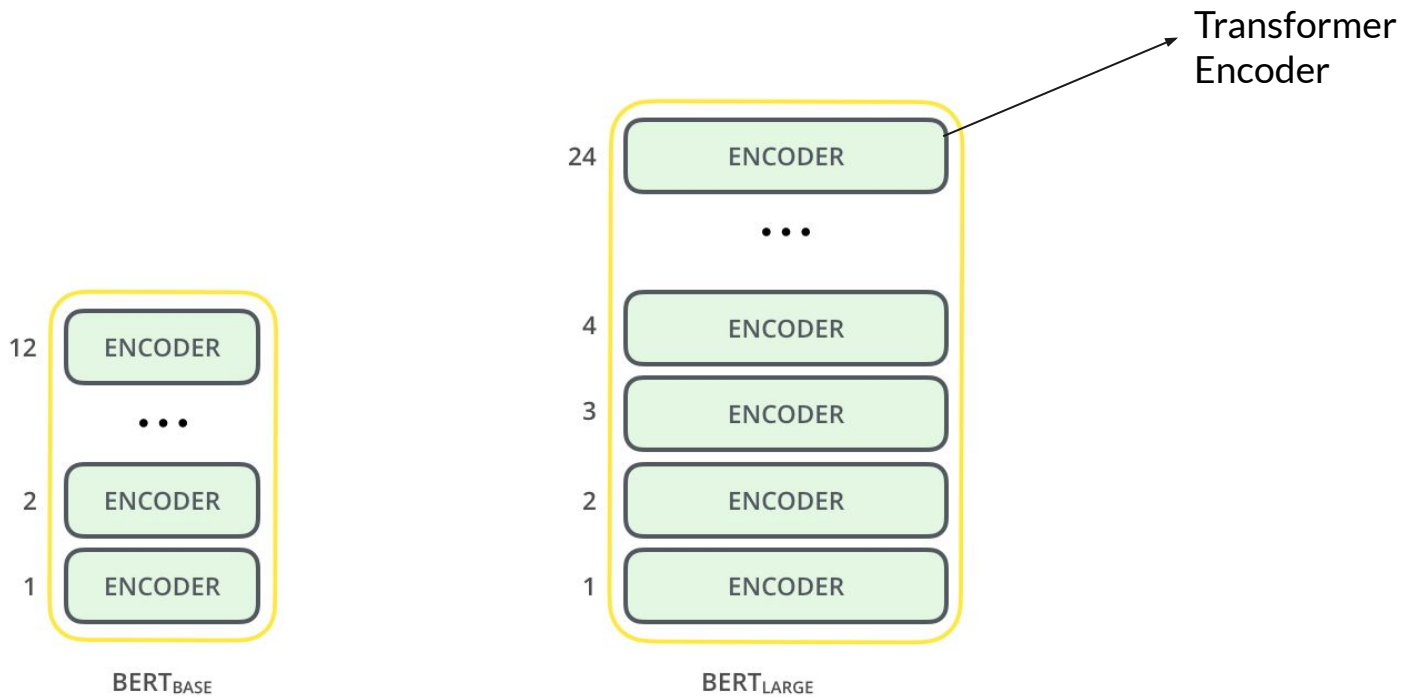
The model is trained on a certain task that enables it to grasp patterns in language. By the end of the training process, BERT has language-processing abilities capable of empowering many models we later need to build and train in a supervised way.



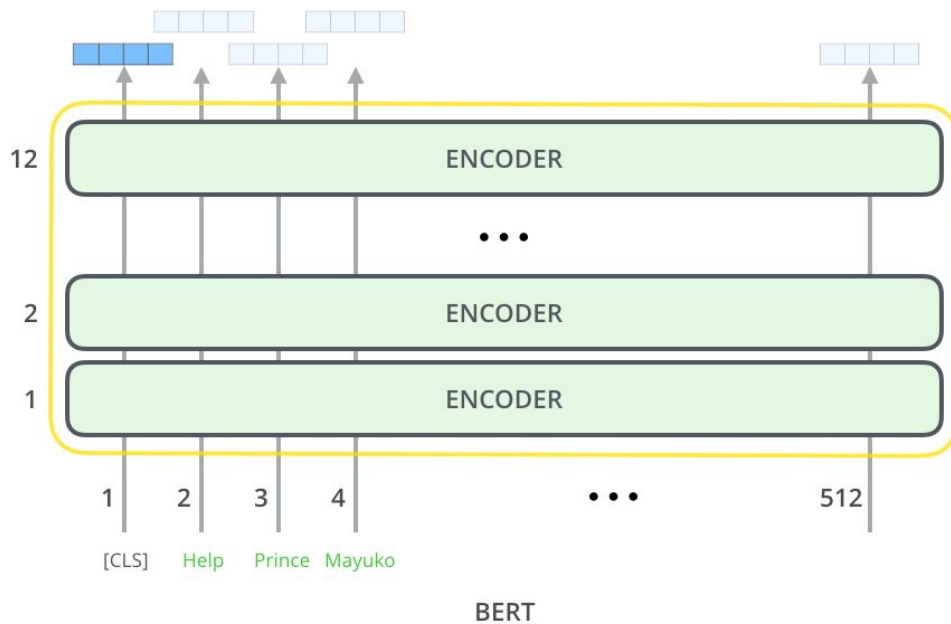
2 - **Supervised** training on a specific task with a labeled dataset.



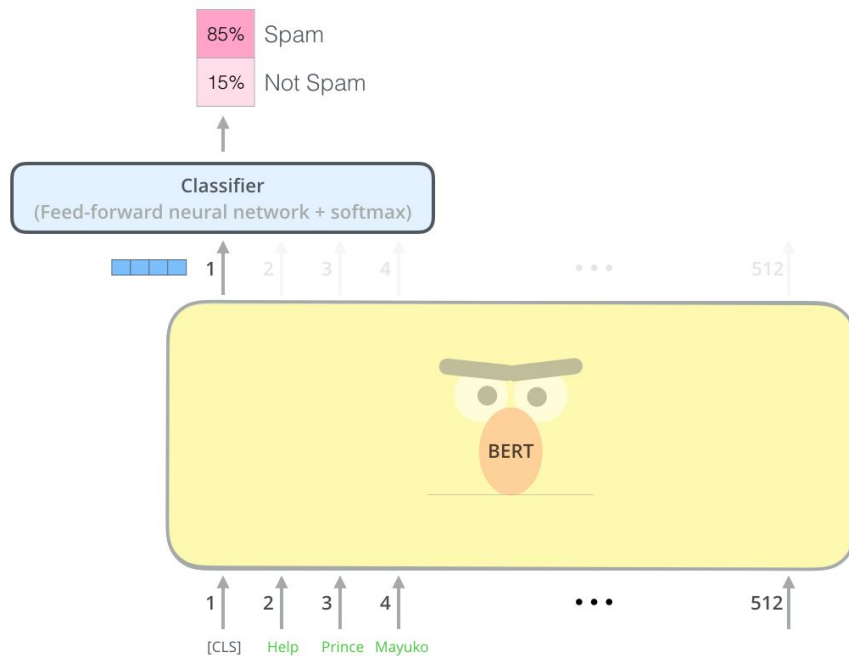
BERT architecture



BERT architecture

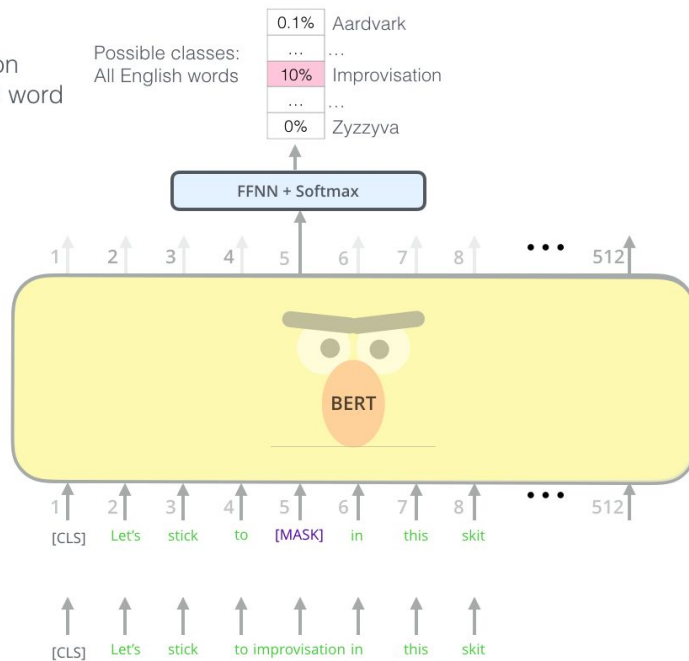


BERT Classifier



BERT: Masked Language Model

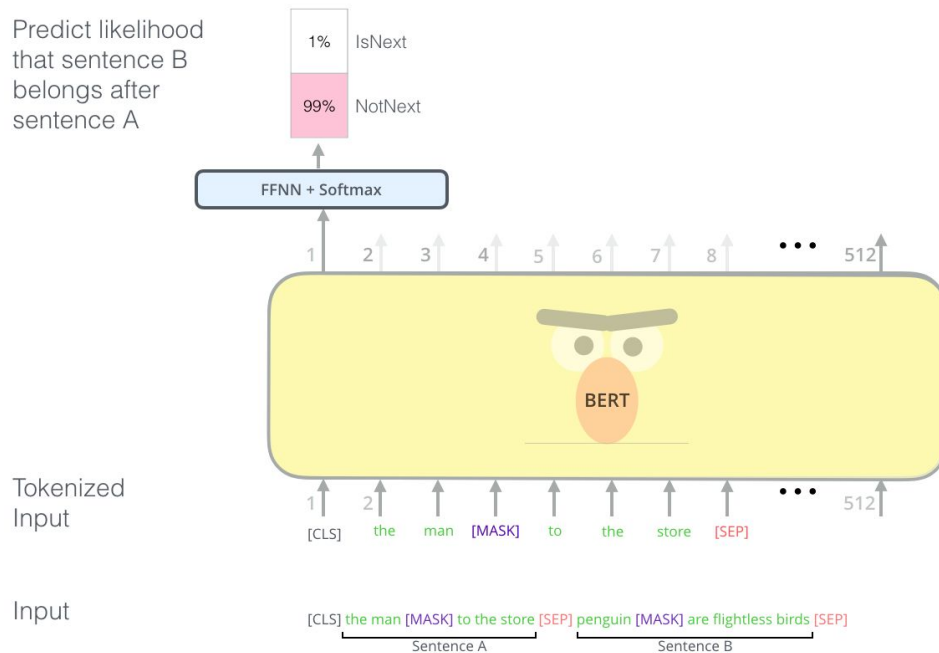
Use the output of the masked word's position to predict the masked word



Randomly mask 15% of tokens

Input

BERT: Next Sentence Prediction



BERT: Question Answering

Super_Bowl_50

The Stanford Question Answering Dataset

Super Bowl 50 was an American football game to determine the champion of the National Football League (NFL) for the 2015 season. The American Football Conference (AFC) champion Denver Broncos defeated the National Football Conference (NFC) champion Carolina Panthers 24–10 to earn their third Super Bowl title. The game was played on February 7, 2016, at Levi's Stadium in the San Francisco Bay Area at Santa Clara, California. As this was the 50th Super Bowl, the league emphasized the "golden anniversary" with various gold-themed initiatives, as well as temporarily suspending the tradition of naming each Super Bowl game with Roman numerals (under which the game would have been known as "Super Bowl L"), so that the logo could prominently feature the Arabic numerals 50.

Which NFL team represented the AFC at Super Bowl 50?

Ground Truth Answers: Denver Broncos Denver Broncos Denver Broncos

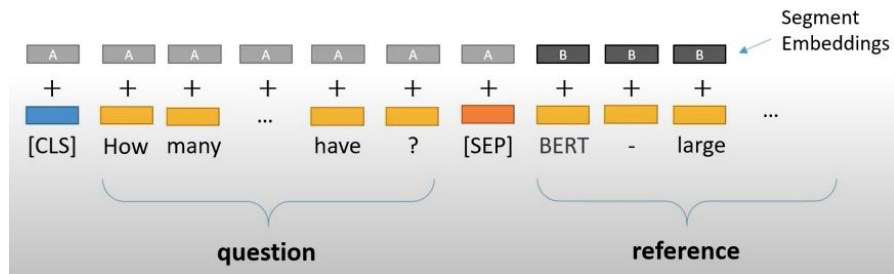
Prediction: Denver Broncos

BERT: Question Answering

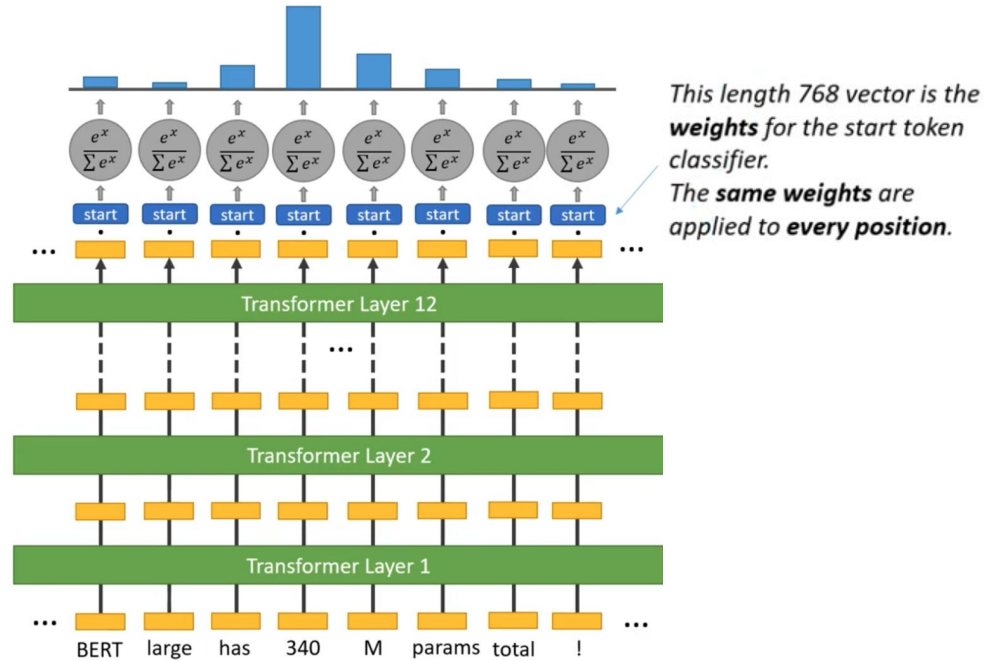
Input Preparation

Question: How many parameters does BERT-large have?

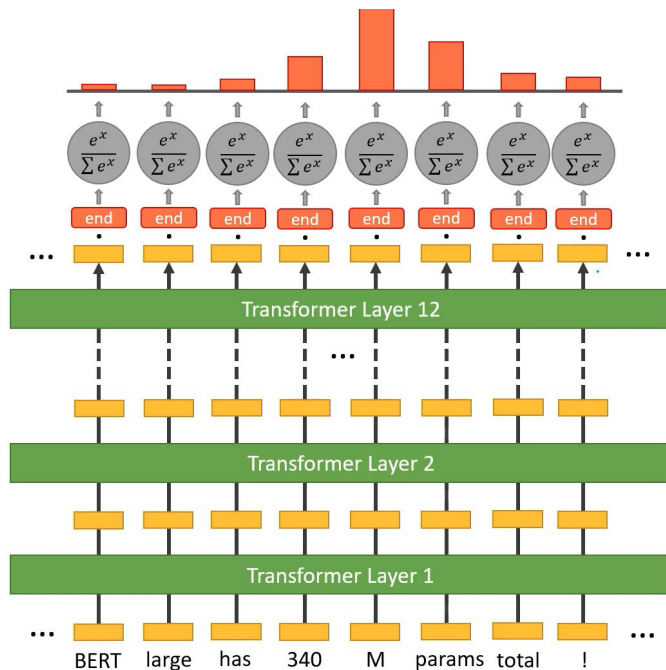
Reference Text: BERT-large is really big... it has 24 layers and an embedding size of 1,024, for a total of 340M parameters! Altogether it is 1.34GB, so expect it to take a couple minutes to download to your Colab instance.



BERT: Question Answering



BERT: Question Answering

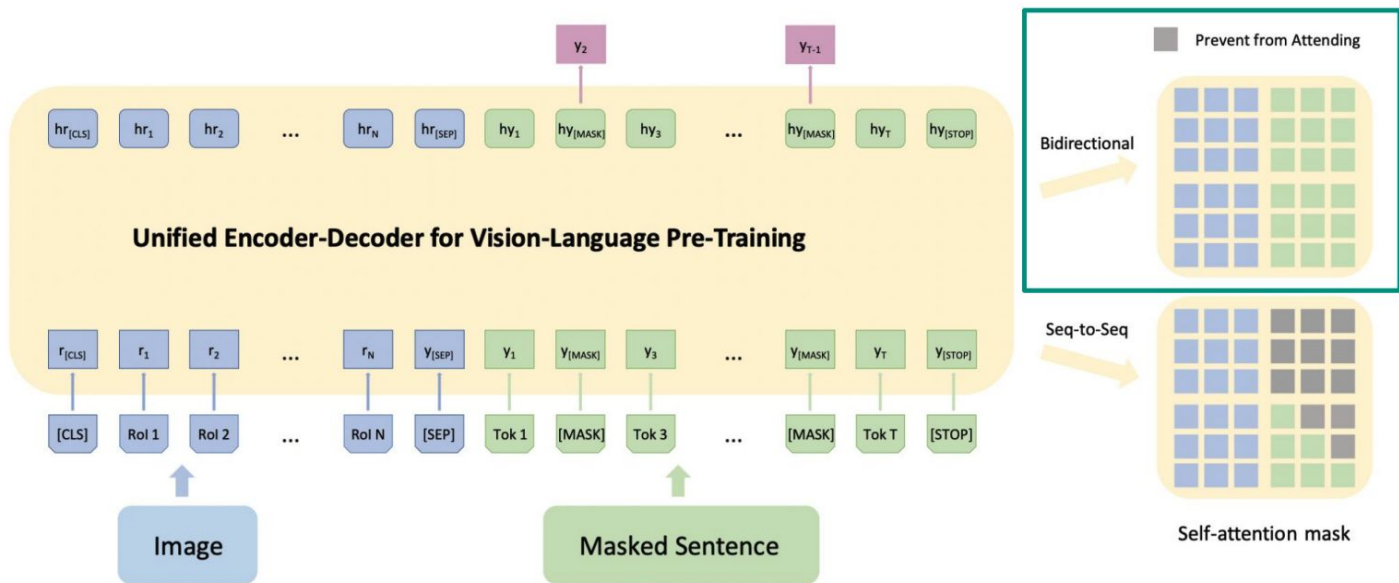


OSCAR: Problem Addressed by Paper

- ❖ Previous work simply concatenate image region features and text features to learn image-text semantic alignments in a brute force manner



OSCAR: Problem Addressed by Paper (Pre-training)



OSCAR: Problem Addressed by Paper

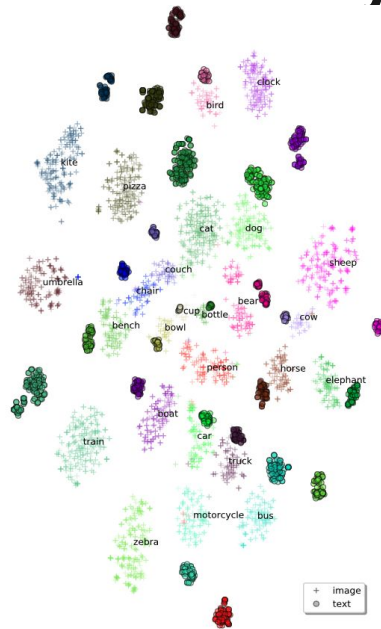


Fig. 2: Feature visualization of baseline (no tags). For several object classes, their text and image features are largely separated (e.g., person, umbrella, zebra). The distance of image features between some objects is too small (e.g., bench, chair, couch).

OSCAR: Solution Offered

- ❖ Word-Tag-Region Triplet

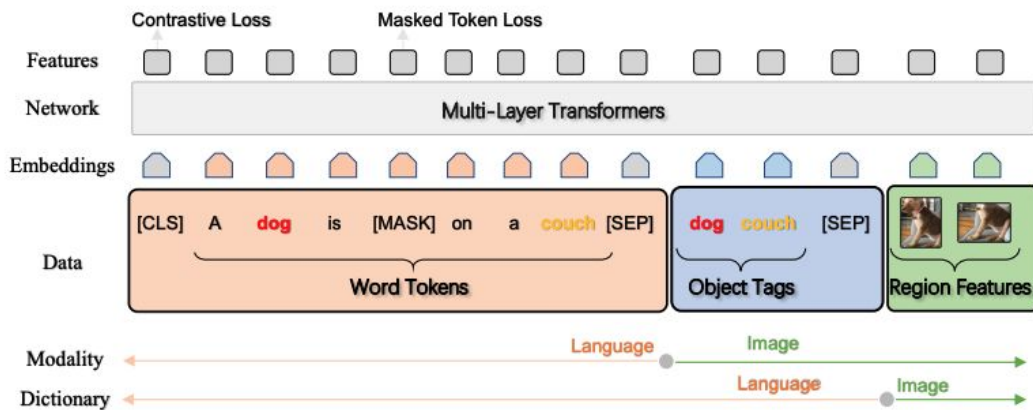


Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020).

Retrieved from <https://arxiv.org/abs/2004.06165>

OSCAR: Solution Offered (Pre-training)

- ❖ Training on Modality View using Contrastive Loss
- ❖ Training on Dictionary View Using Masked Token Loss



Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020).

Retrieved from <https://arxiv.org/abs/2004.06165>

OSCAR: Solution Offered (Fine-tuning)

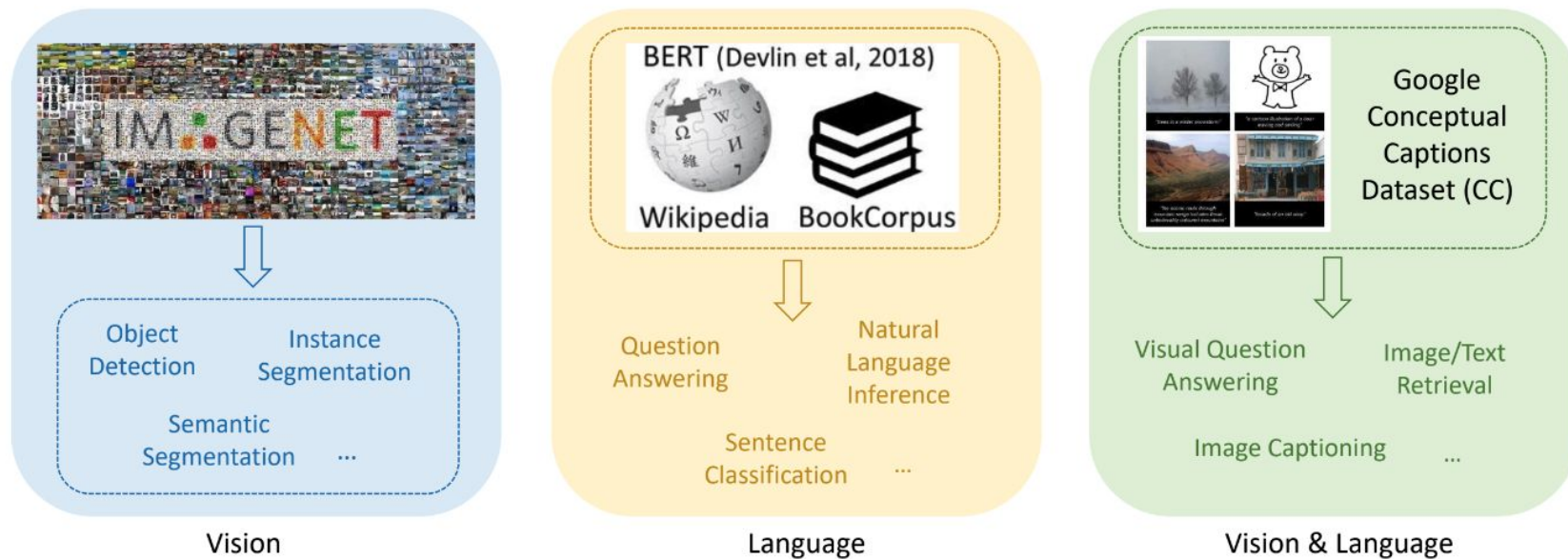
Understanding

- VQA
- GQA
- NLVR2
- Image-Text Retrieval
- Text-Image Retrieval






Generation

- Image Captioning
- Novel Object Captioning

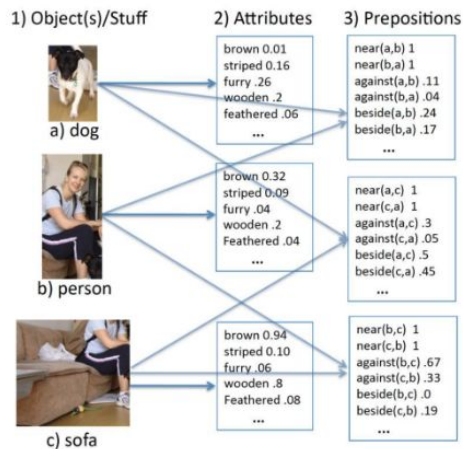
Motivation: Pre-training



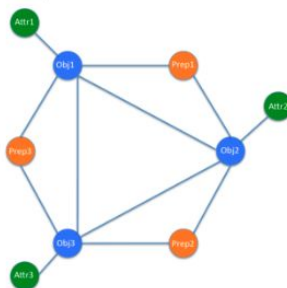
Motivation: Vision Language Tasks

	Text-to-Image Retrieval	Image-to-Text Retrieval	VQA	Image Captioning	Text-to-Image Generation
Input	Query: A couple of zebra walking across a dirt road. <div style="border: 1px solid black; border-radius: 15px; padding: 5px; width: fit-content; margin: 10px auto;">A pool of images.</div>	Query:  <div style="border: 1px solid black; border-radius: 15px; padding: 5px; width: fit-content; margin: 10px auto;">A pool of texts.</div>	Image:  Q: why did the zebra cross the road?	Image: 	Text: A couple of zebra walking across a dirt road.
Output		A couple of zebra walking across a dirt road.	A: to get to the other side (Selected from a pool of 3,129 answers in VQAv2)	A couple of zebra walking across a dirt road.	
	Understanding	Understanding	Understanding	Generation	Generation

Related Works: Image Captioning Evolution (Traditional)



4) Constructed CRF



6) Generated Sentences

This is a photograph of one person and one brown sofa and one dog. The person is against the brown sofa. And the dog is near the person, and beside the brown sofa.

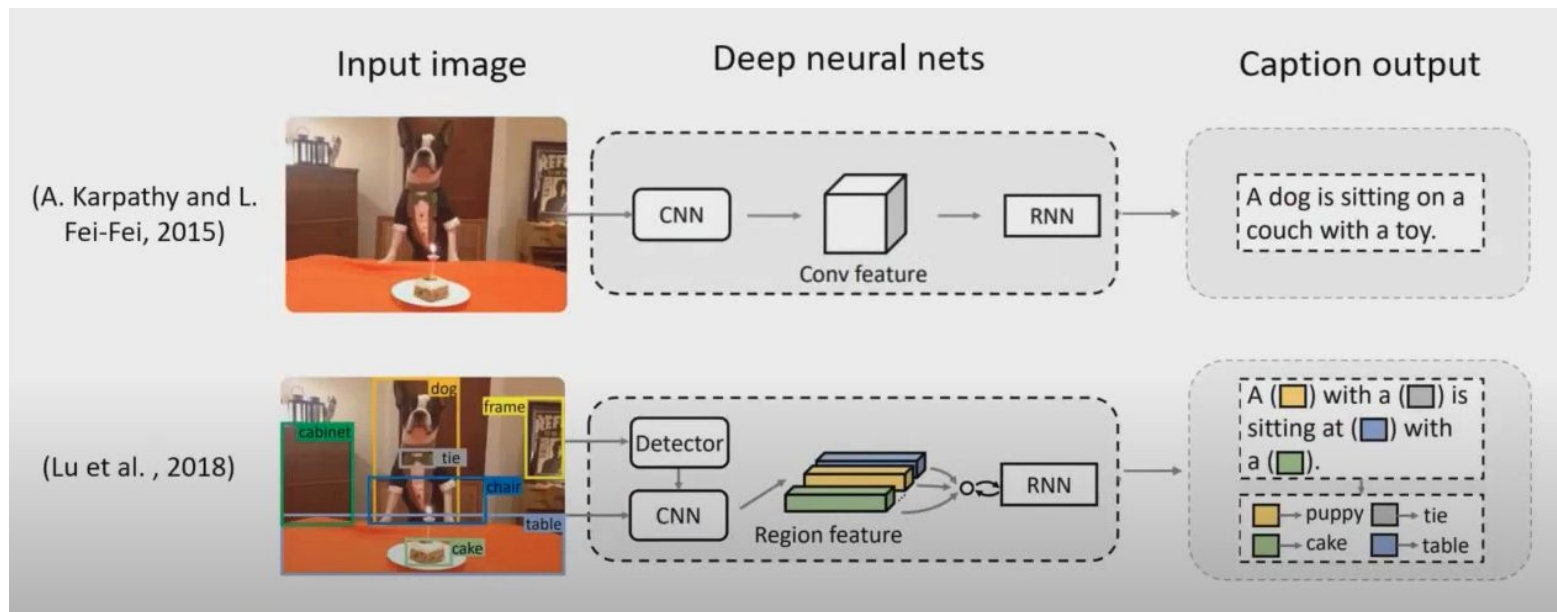
5) Predicted Labeling

```
<<null_person_b>,against,<brown_sofa_c>>
<<null_dog_a>,near,<null_person_b>>
<<null_dog_a>,beside,<brown_sofa_c>>
```

Using templates

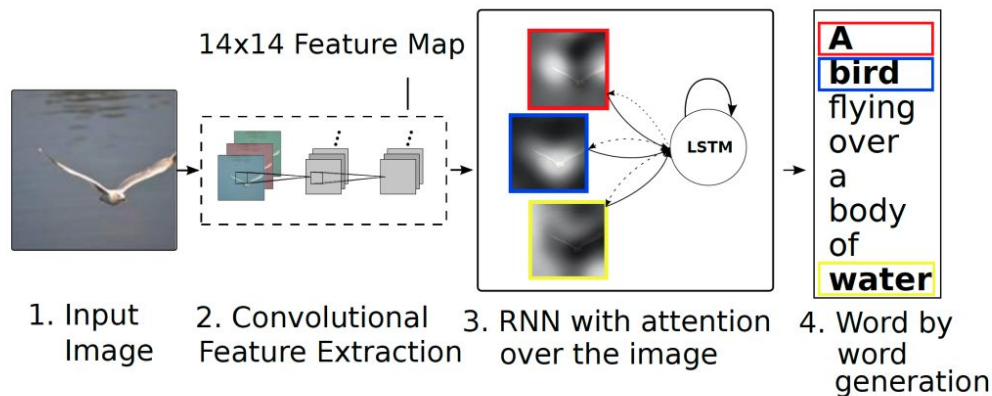
Baby Talk: Understanding and Generating Image Descriptions. Kulkarni et al., CVPR, 2011

Related Works: Image Captioning Evolution (RNNs)



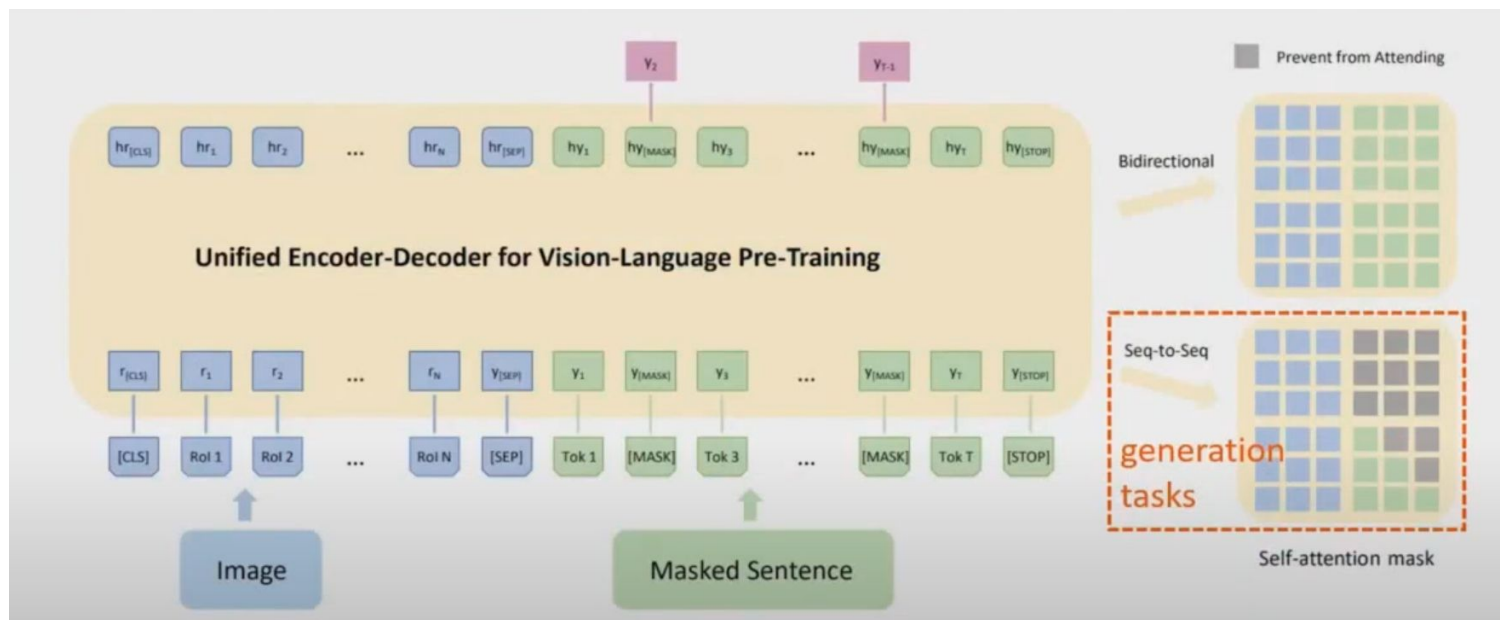
Related Works: Image Captioning Evolution (Attention)

Image Captioning with Attention



Show, Attend and Tell: Neural Image Caption Generation with Visual Attention. Xu et al., PMLR, 2015.

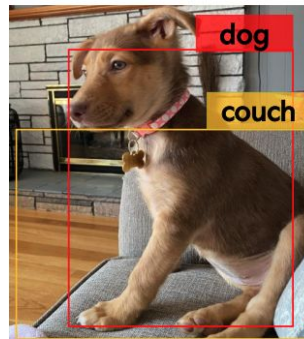
Related Works: Image Captioning Evolution (Current)



<https://www.microsoft.com/en-us/research/publication/oscar-object-semantics-aligned-pre-training-for-vision-language-tasks/>

Problem with the Current Work

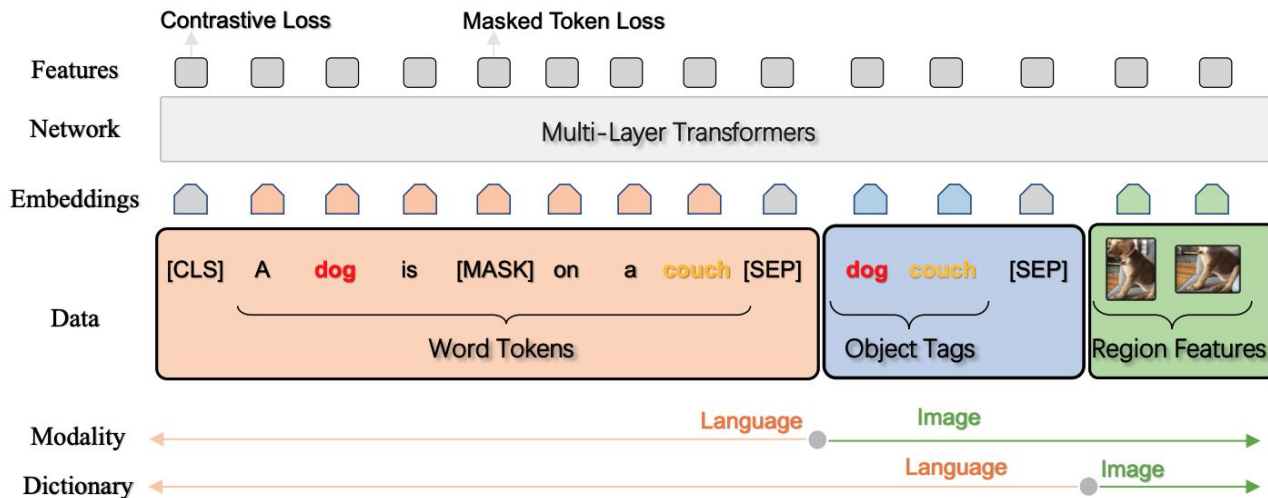
- ❖ Ambiguity
 - Visual Region features are extracted from over-sampled regions via object detectors
 - Overlaps among image regions at different positions
- ❖ Lack of grounding
 - No label alignments between regions or objects in an image and words or phrase in text
 - Solution: Salient objects in both image and its paired text (anchor points)



A **dog** is sitting on a **couch**

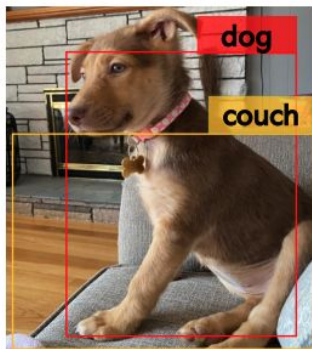
Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020). Retrieved from <https://arxiv.org/abs/2004.06165>

OSCAR's Approach



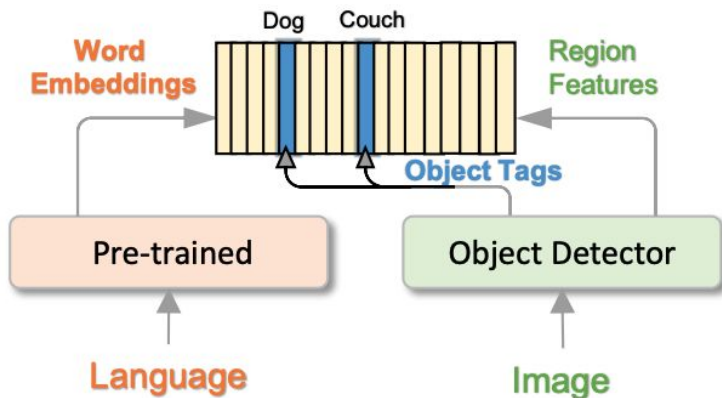
Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020). Retrieved from <https://arxiv.org/abs/2004.06165>

OSCAR's Approach

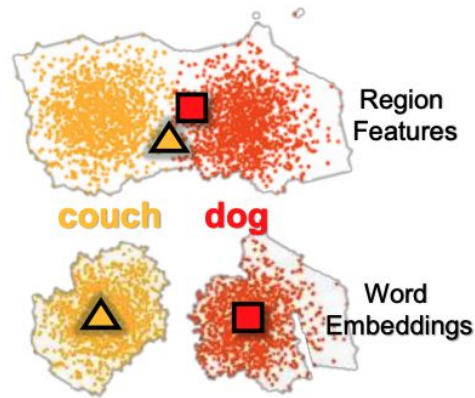


A **dog** is sitting on a **couch**

(a) Image-text pair



(b) Objects as anchor points



(c) Semantics spaces

OSCAR's Approach (Generation of v and q)



<https://www.microsoft.com/en-us/research/publication/oscar-object-semantics-aligned-pre-training-for-vision-language-tasks/>

OSCAR's Approach (Pre-training Objective)

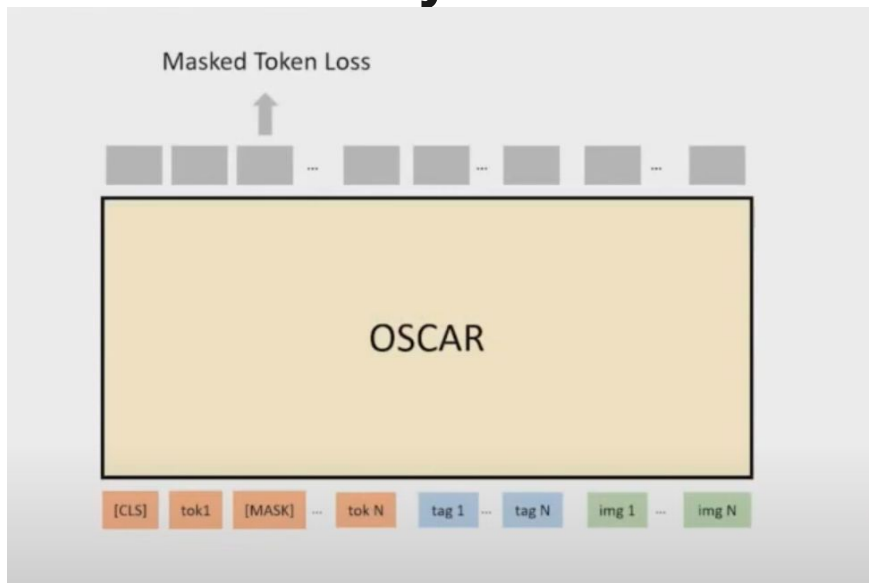
$$x \triangleq [\underbrace{w}_{\text{language}}, \underbrace{q, v}_{\text{image}}] = [\underbrace{w, q}_{\text{language}}, \underbrace{v}_{\text{image}}] \triangleq x'$$

Modality View (Contrastive Loss)

Dictionary View (Masked Token Loss)

Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020). Retrieved from <https://arxiv.org/abs/2004.06165>

OSCAR's Approach (Dictionary View)



$$\mathcal{L}_{\text{MTL}} = -\mathbb{E}_{(\mathbf{v}, \mathbf{h}) \sim \mathcal{D}} \log p(h_i | \mathbf{h}_{\setminus i}, \mathbf{v})$$

<https://www.microsoft.com/en-us/research/publication/oscar-object-semantics-aligned-pre-training-for-visual-language-tasks/>

OSCAR's Approach (Modality View)

$$\mathcal{L}_C = -\mathbb{E}_{(\mathbf{h}', \mathbf{w}) \sim \mathcal{D}} \log p(y | f(\mathbf{h}', \mathbf{w})).$$

a contrastive loss for the modality view, which measures the model's capability of distinguishing an original triple and its "polluted" version (that is, where an original object tag is replaced with a randomly sampled one).

OSCAR's Approach (Full Pre-training Objective)



$$\mathcal{L}_{\text{Pre-training}} = \mathcal{L}_{\text{MTL}} + \mathcal{L}_{\text{C}}.$$

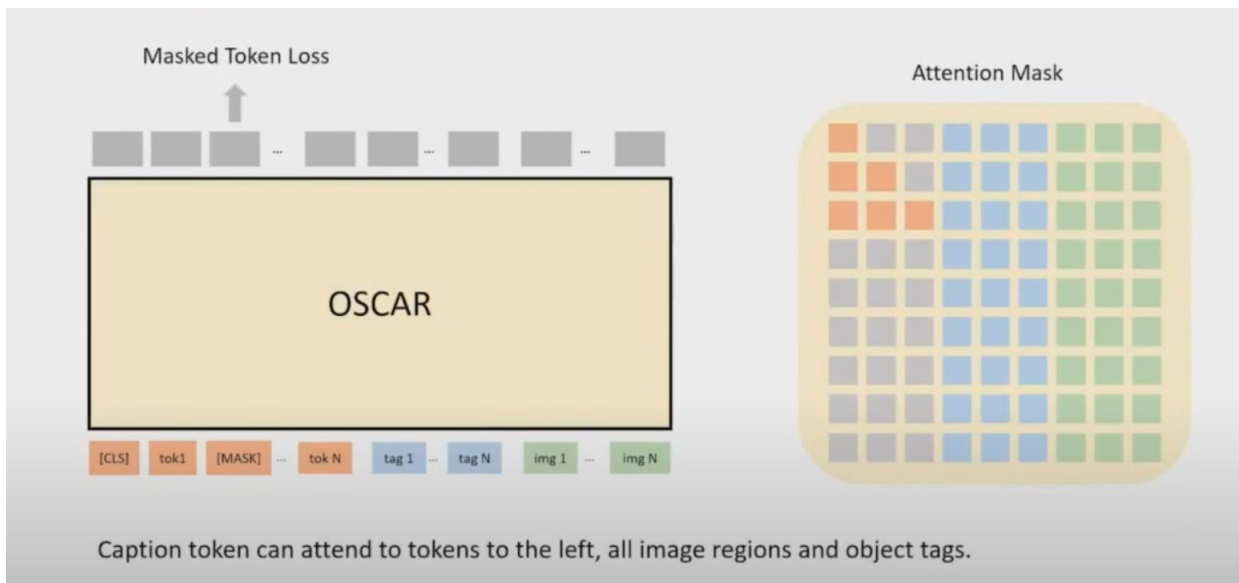
Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020). Retrieved from <https://arxiv.org/abs/2004.06165>

OSCAR's Approach (Implementation Details)

- ❖ Two model variants as OSCAR Base (H = 768) and OSCAR Large (H = 1024)
- ❖ Adam Optimizer
- ❖ OSCAR Base trained for at least 1.0 M steps with learning rate $5e^{-5}$ and batch size 768
- ❖ OSCAR Large trained for at least 900k steps with learning rate $1e^{-5}$ and batch size 512
- ❖ Sequence length of discrete token h and region features v are 35 and 50 respectively

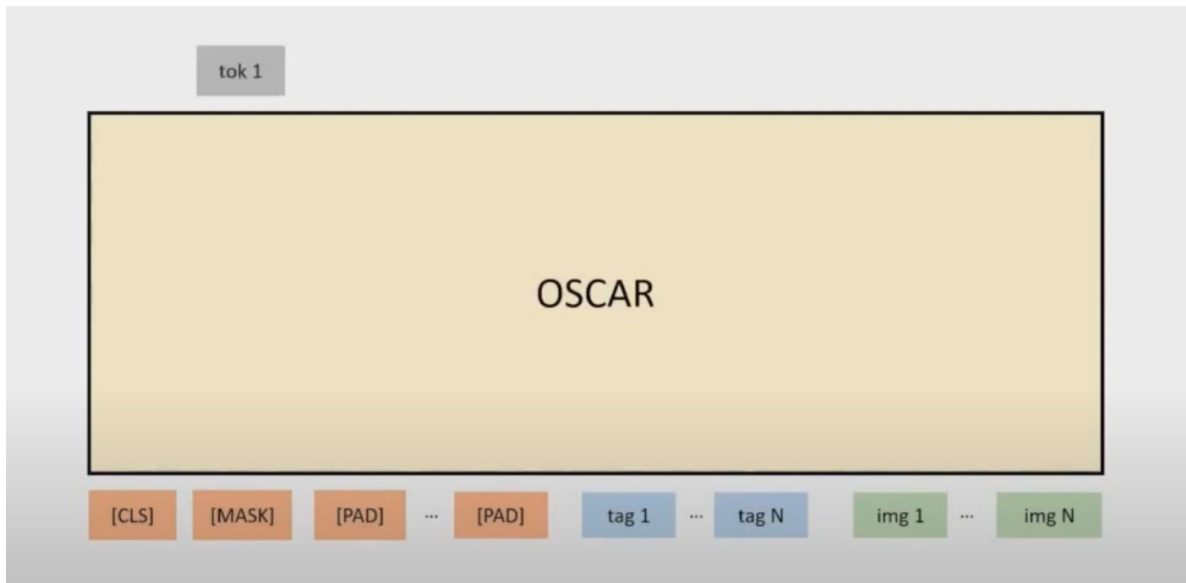
Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020). Retrieved from <https://arxiv.org/abs/2004.06165>

OSCAR's Fine-tuning (Image Captioning)



<https://www.microsoft.com/en-us/research/publication/oscar-object-semantics-aligned-pre-training-for-vision-language-tasks/>

OSCAR's Fine-tuning (Image Captioning Inference)



<https://www.microsoft.com/en-us/research/publication/oscar-object-semantics-aligned-pre-training-for-vision-language-tasks/>

OSCAR's Fine-tuning (Image Text Retrieval)

- ❖ There are two tasks Image Retrieval and Text Retrieval
- ❖ Binary Classification problem using CLS
- ❖ Randomly pick different image-text pair and predict if they are aligned or not
- ❖ During Test, probability score is used to rank the given image-text pairs of a query

Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020). Retrieved from <https://arxiv.org/abs/2004.06165>

OSCAR's Fine-tuning (Visual Question Answering)



- ❖ Model needs to answer using Natural Language questions based on image
- ❖ Image and question is given to select answer from multi-choice list
- ❖ Concatenate question, object tags and region features
- ❖ CLS output is fed for linear classifier for multi-label classification
- ❖ Fine-tune model based on cross-entropy loss
- ❖ Simply use Softmax function for prediction

Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020). Retrieved from <https://arxiv.org/abs/2004.06165>

Experimental Results and Analysis

Task	Image Retrieval			Text Retrieval			Image Captioning				NoCaps		VQA	NLVR2
	R@1	R@5	R@10	R@1	R@5	R@10	B@4	M	C	S	C	S	test-std	test-P
SoTA _S	39.2	68.0	81.3	56.6	84.5	92.0	38.9	29.2	129.8	22.4	61.5	9.2	70.90	53.50
SoTA _B	48.4	76.7	85.9	63.3	87.0	93.1	39.5	29.3	129.3	23.2	73.1	11.2	72.54	78.87
SoTA _L	51.7	78.4	86.9	66.6	89.4	94.3	—	—	—	—	—	—	73.40	79.50
OSCAR _B	54.0	80.8	88.5	70.0	91.1	95.5	40.5	29.7	137.6	22.8	78.8	11.7	73.44	78.36
OSCAR _L	57.5	82.8	89.8	73.5	92.2	96.0	41.7	30.6	140.0	24.5	80.9	11.3	73.82	80.37
Δ	5.8 \uparrow	4.4 \uparrow	2.9 \uparrow	6.9 \uparrow	2.8 \uparrow	1.7 \uparrow	2.2 \uparrow	1.3 \uparrow	10.7 \uparrow	1.3 \uparrow	7.8 \uparrow	0.5 \uparrow	0.42 \uparrow	0.87 \uparrow

Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020). Retrieved from <https://arxiv.org/abs/2004.06165>

Experimental Results and Analysis

Method	Size	Text Retrieval			Image Retrieval			Text Retrieval			Image Retrieval		
		R@1	R@5	R@10	R@1	R@5	R@10	R@1	R@5	R@10	R@1	R@5	R@10
		1K Test Set						5K Test Set					
DVSA [14]	-	38.4	69.9	80.5	27.4	60.2	74.8	-	-	-	-	-	-
VSE++ [7]	-	64.7	-	95.9	52.0	-	92.0	41.3	-	81.2	30.3	-	72.4
DPC [46]	-	65.6	89.8	95.5	47.1	79.9	90.0	41.2	70.5	81.1	25.3	53.4	66.4
CAMP [42]	-	72.3	94.8	98.3	58.5	87.9	95.0	50.1	82.1	89.7	39.0	68.9	80.2
SCAN [18]	-	72.7	94.8	98.4	58.8	88.4	94.8	50.4	82.2	90.0	38.6	69.3	80.4
SCG [33]	-	76.6	96.3	99.2	61.4	88.9	95.1	56.6	84.5	92.0	39.2	68.0	81.3
PFAN [41]	-	76.5	96.3	99.0	61.6	89.6	95.2	-	-	-	-	-	-
Unicoder-VL [19]	B	84.3	97.3	99.3	69.7	93.5	97.2	62.3	87.1	92.8	46.7	76.0	85.3
12-in-1 [24]	B	-	-	-	65.2	91.0	96.2	-	-	-	-	-	-
UNITER [5]	B	-	-	-	-	-	-	63.3	87.0	93.1	48.4	76.7	85.9
UNITER [5]	L	-	-	-	-	-	-	66.6	89.4	94.3	51.7	78.4	86.9
OSCAR	B	88.4	99.1	99.8	75.7	95.2	98.3	70.0	91.1	95.5	54.0	80.8	88.5
	L	89.8	98.8	99.7	78.2	95.8	98.3	73.5	92.2	96.0	57.5	82.8	89.8

(a) Image-text retrieval

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Experimental Results and Analysis

Method	ViLBERT	VL-BERT	VisualBERT	LXMERT	12-in-1	UNITER _B	UNITER _L	OSCAR _B	OSCAR _L
Test-dev	70.63	70.50	70.80	72.42	73.15	72.27	73.24	73.16	73.61
Test-std	70.92	70.83	71.00	72.54	–	72.46	73.40	73.44	73.82

(b) VQA

Method	MAC	VisualBERT	LXMERT	12-in-1	UNITER _B	UNITER _L	OSCAR _B	OSCAR _L
Dev	50.8	67.40	74.90	–	77.14	78.40	78.07	79.12
Test-P	51.4	67.00	74.50	78.87	77.87	79.50	78.36	80.37

(c) NLVR2

Method	Test-dev	Test-std
LXMERT [39]	60.00	60.33
MMN [4]	–	60.83
12-in-1 [24]	–	60.65
NSM [12]	–	63.17
OSCAR _B	61.19	61.23
OSCAR _B *	61.58	61.62

(d) GQA

Method	cross-entropy optimization				CIDEr optimization			
	B@4	M	C	S	B@4	M	C	S
BUTD [2]	36.2	27.0	113.5	20.3	36.3	27.7	120.1	21.4
VLP [47]	36.5	28.4	117.7	21.3	39.5	29.3	129.3	23.2
AoANet [11]	37.2	28.4	119.8	21.3	38.9	29.2	129.8	22.4
OSCAR _B	36.5	30.3	123.7	23.1	40.5	29.7	137.6	22.8
OSCAR _L	37.4	30.7	127.8	23.5	41.7	30.6	140.0	24.5

(e) Image captioning on COCO

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Experimental Results and Analysis

Method	in-domain		near-domain		out-of-domain		overall	
	CIDEr	SPICE	CIDEr	SPICE	CIDEr	SPICE	CIDEr	SPICE
UpDown [1]	78.1	11.6	57.7	10.3	31.3	8.3	55.3	10.1
UpDown + CBS [1]	80.0	12.0	73.6	11.3	66.4	9.7	73.1	11.1
UpDown + ELMo + CBS [1]	79.3	12.4	73.8	11.4	71.7	9.9	74.3	11.2
OSCAR _B	79.6	12.3	66.1	11.5	45.3	9.7	63.8	11.2
OSCAR _B + CBS	80.0	12.1	80.4	12.2	75.3	10.6	79.3	11.9
OSCAR _B + SCST + CBS	83.4	12.0	81.6	12.0	77.6	10.6	81.1	11.7
OSCAR _L	79.9	12.4	68.2	11.8	45.1	9.4	65.2	11.4
OSCAR _L + CBS	78.8	12.2	78.9	12.1	77.4	10.5	78.6	11.8
OSCAR _L + SCST + CBS	85.4	11.9	84.0	11.7	80.3	10.0	83.4	11.4

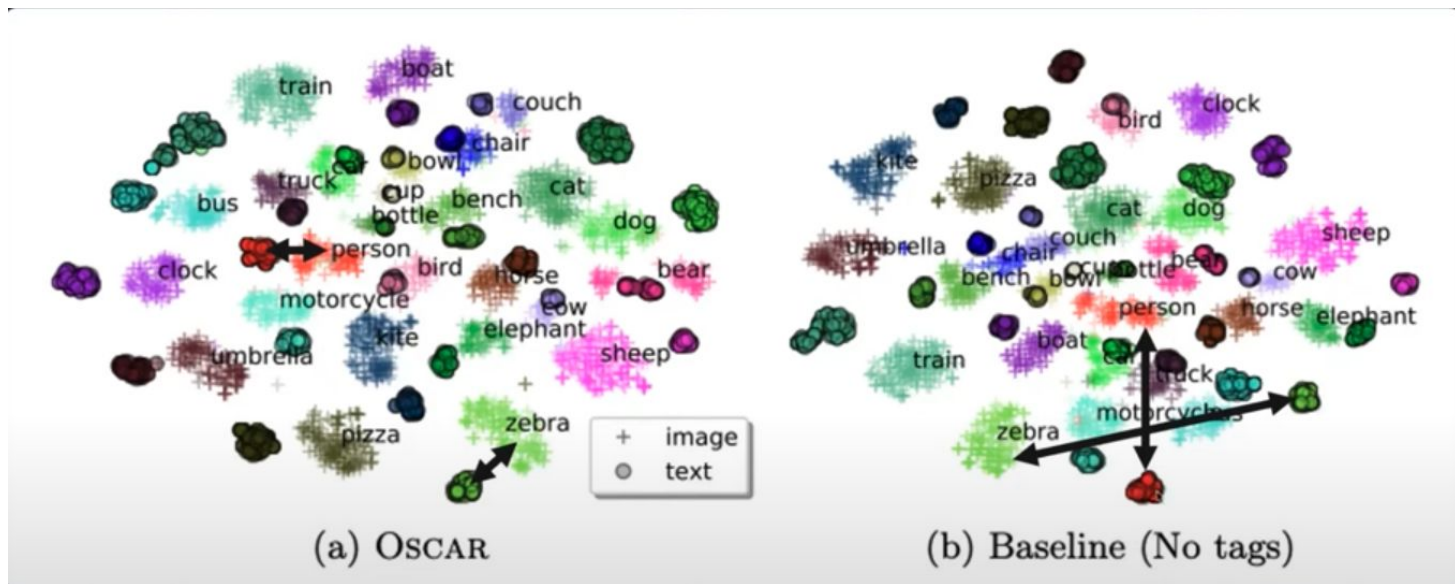
(f) Evaluation on NoCaps Val. Models are trained on COCO only without pre-training.

CBS- Constrained Beam Search

SCST- Self-Critical Sequence Training

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Qualitative Studies



Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020). Retrieved from <https://arxiv.org/abs/2004.06165>

Qualitative Studies



Oscar: a small **train** on a city **street** with **people** near by .

Baseline: a **train** that is sitting on the side of the road .

GT: a small **train** on a city **street** with **people** near by .

A black and red small **train** in shopping area.

A group of **people** near a small railroad **train** in a mall .

Tags: sign, tree, sidewalk, **train**, woman, person, trees, **street**, bus, stairs, store, man, balcony, building, **people**



Oscar: a red **rose** and white **flowers** in a **vase** .

Baseline: a **vase** filled with red and white **flowers** .

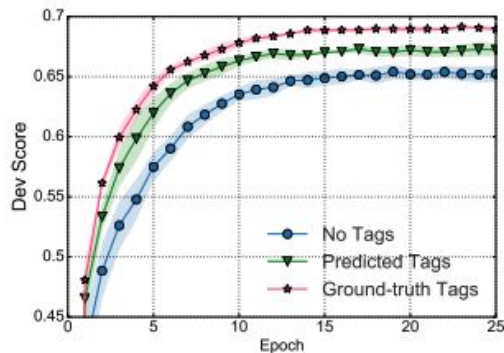
GT: A red **rose** in a glass **vase** on a **table**

beautiful red **rose** and white **flowers** are in a **vase** .

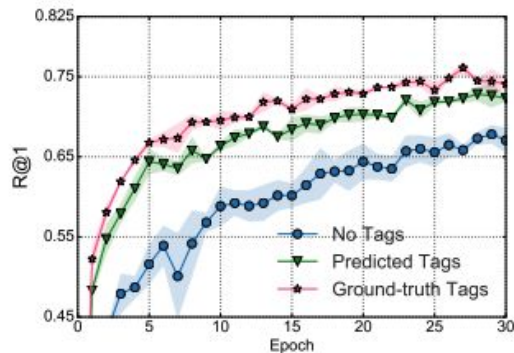
The **bouquet** has one red **rose** in it.

Tags: leaf, **bouquet**, **flowers**, stem, **table**, **rose**, flower, leaves, **vase**, plant

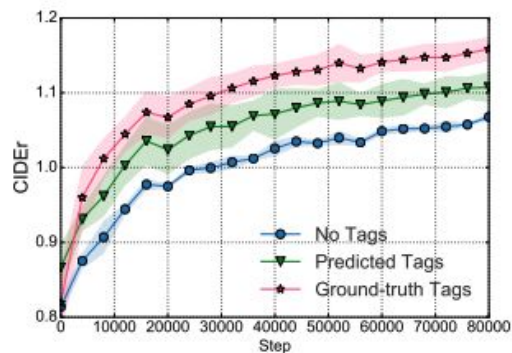
Ablation Analysis



(a) VQA



(b) Image Retrieval R@1



(c) Image Captioning

Xiujun Li, Xi Yin, Chunyuan Li, Pengchuan Zhang, Xiaowei Hu, Lei Zhang, Lijuan Wang, Houdong Hu, Li Dong, Furu Wei, Yejin Choi, and Jianfeng Gao. 2020. Oscar: Object-Semantics Aligned Pre-training for Vision-Language Tasks. CoRR abs/2004.06165, (2020). Retrieved from <https://arxiv.org/abs/2004.06165>

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- ❖ Techniques used in OSCAR for training and fine-tuning are similar to BERT. This makes it easier to come up with ideas to finetune for different V+L tasks. It is also easier to find documentation of BERT since it has good documentation on the internet

Key Weaknesses



- ❖ In the Real-world images contain several novel objects unseen in training. Without ground-truth our model may not work well

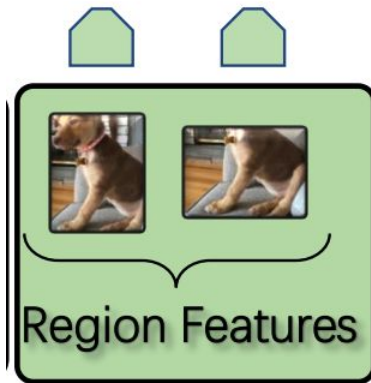
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- ❖ In the Real-world images contain several novel objects unseen in training. Without ground-truth our model may not work well
- ❖ Collecting the image-caption training pairs can be very expensive process to train our model
- ❖ There is still a lot of overlap between different image regions passed to the model. We can add attention mechanism to the images passed to the model for better accuracy.



Future Work/ Open Research Questions



- ❖ Design a model that is able to caption novel/unseen objects while performing VL Tasks
- ❖ Train this model while attention on the image region so that we can further minimize ambiguity of the model.