

CS 4824/ECE 4424: Kernels

Acknowledgement:

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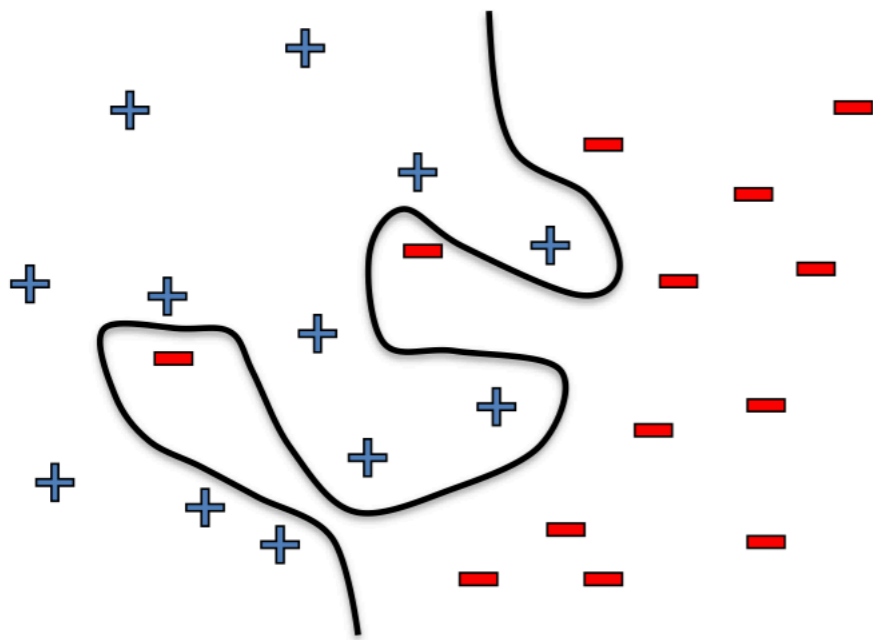
Generalized linear models vs. neural networks

- Generalized linear models (up to ~2010)
 - Fixed basis functions
 - Hypothesis space is limited
 - Easy to optimize (usually convex)
- Neural networks (2010 onwards)
 - Adaptive basis functions
 - Rich hypothesis space
 - Hard to optimize (usually non-convex)

How to extend generalized linear models to have richer hypothesis?

How to generalize linear models for linearly non-separable data?

- Use features of features of features of features....

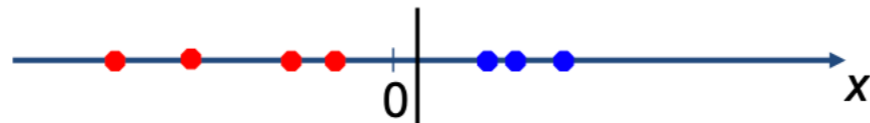


$$\phi(x) = \begin{pmatrix} x_1 \\ \vdots \\ \vdots \\ x_n \\ x_1 x_2 \\ x_2 x_3 \\ \vdots \\ \vdots \\ x_1^2 \\ x_2^2 \\ \vdots \\ \vdots \end{pmatrix}$$

- **Challenge:** Feature space can get really large really quickly!

Non-linear features: 1D input

- Datasets that are linearly separable with some noise work out great:

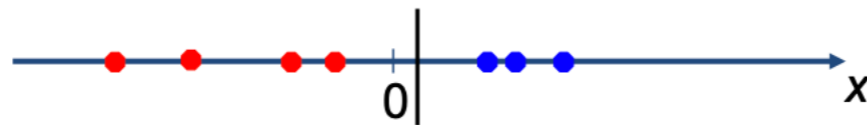


- But what are we going to do if the dataset is just too hard?



Non-linear features: 1D input

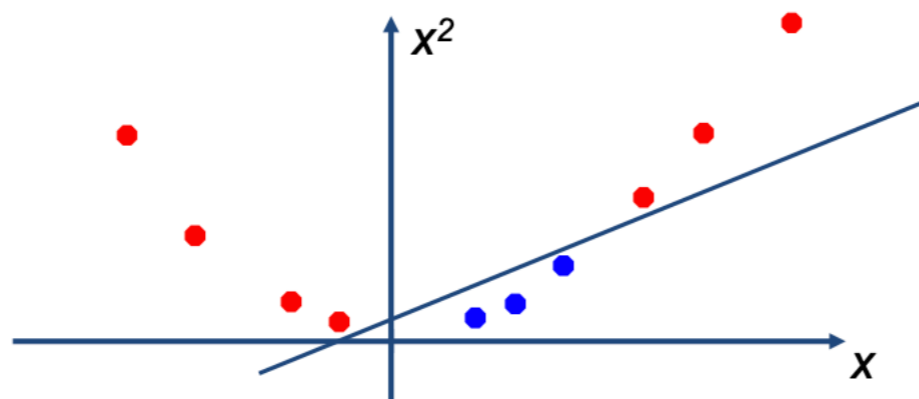
- Datasets that are linearly separable with some noise work out great:



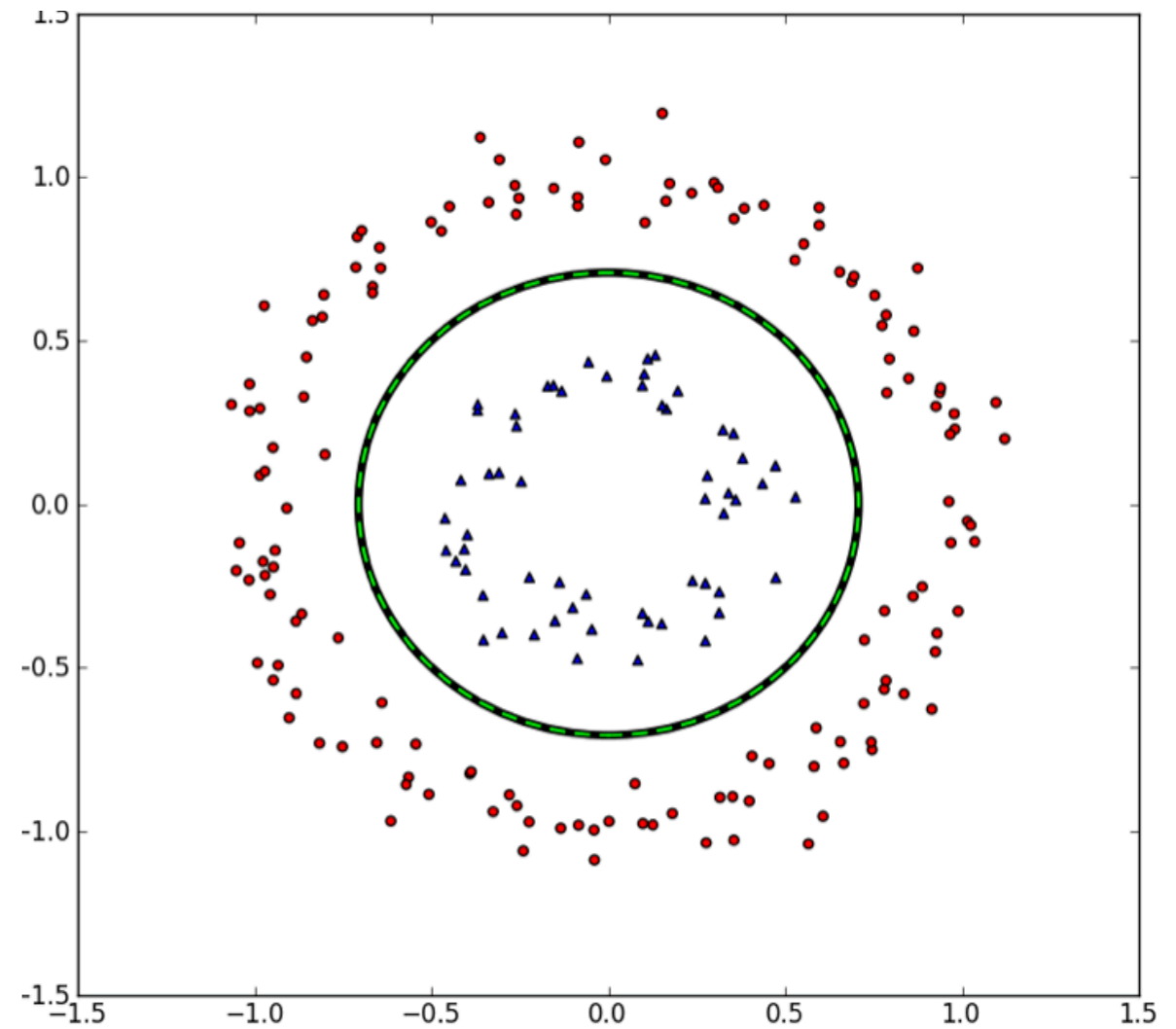
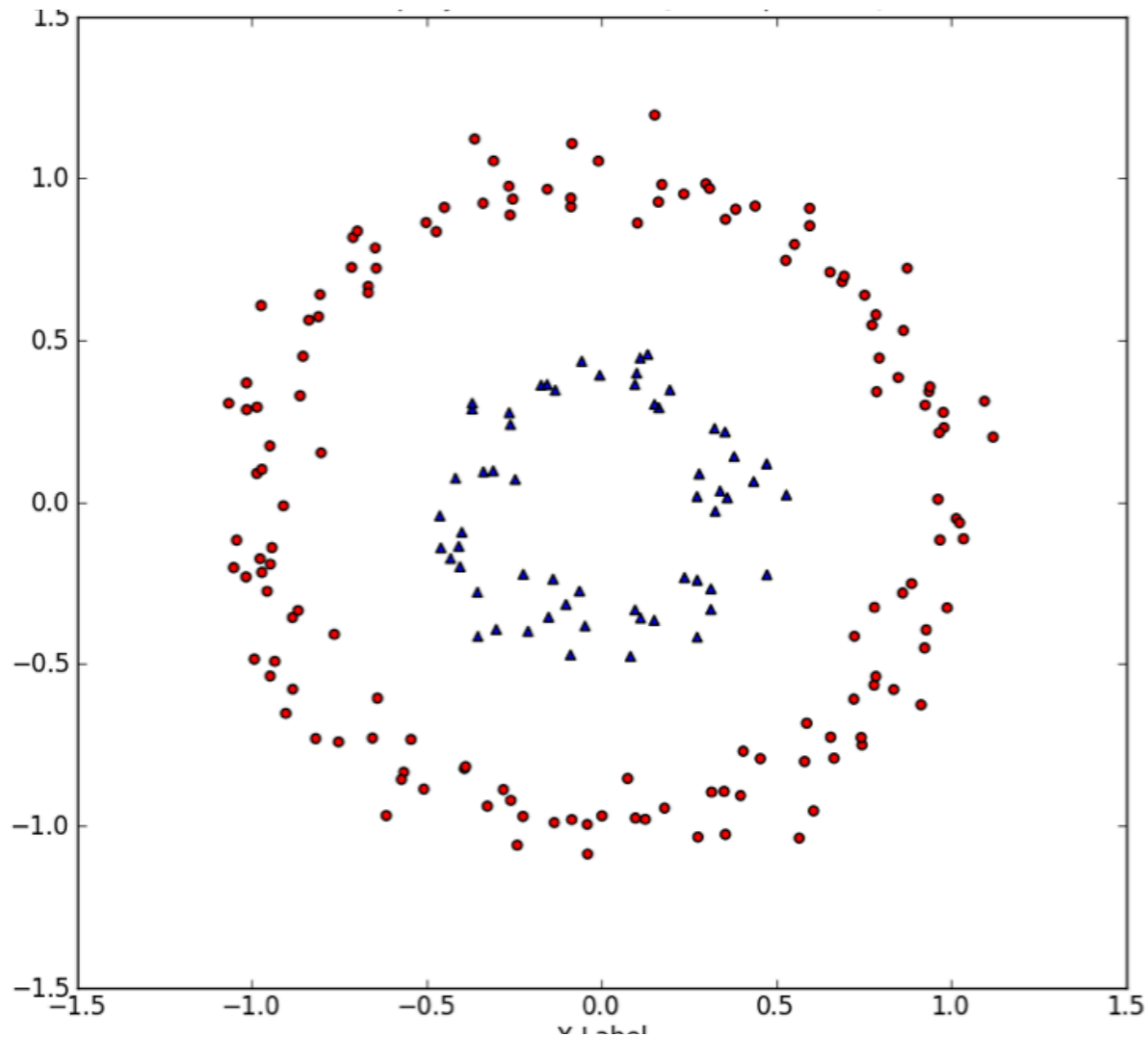
- But what are we going to do if the dataset is just too hard?



- How about... mapping data to a higher-dimensional space:



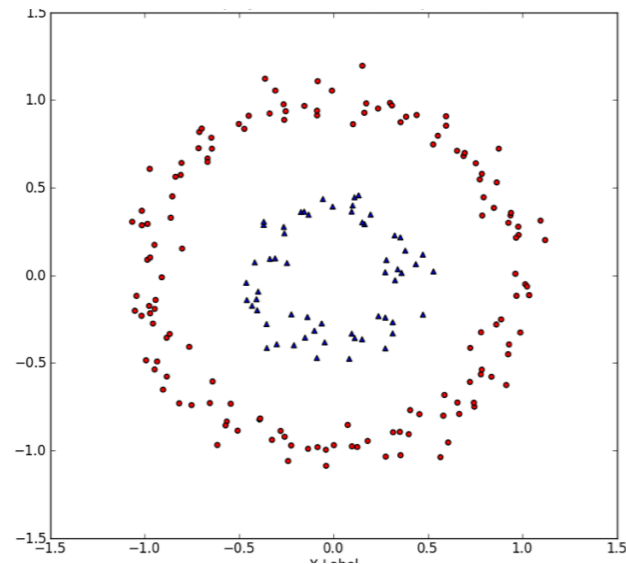
Mapping to higher dimensional space



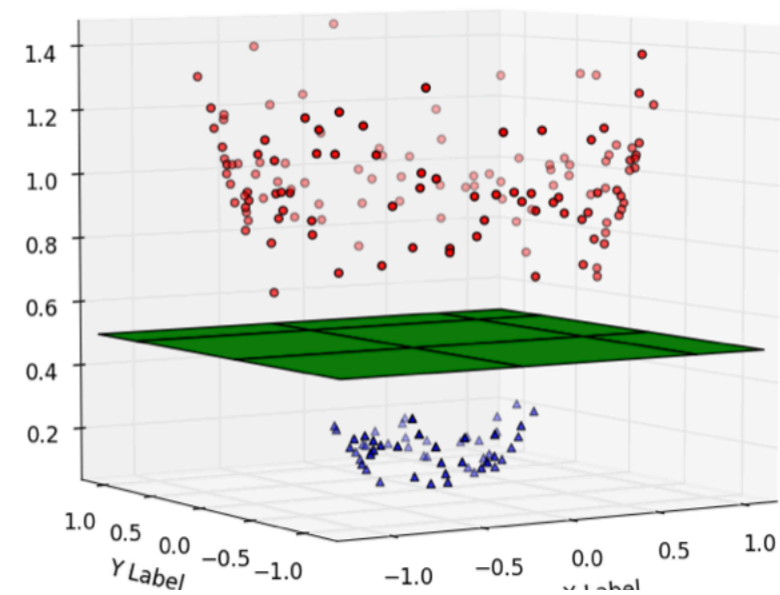
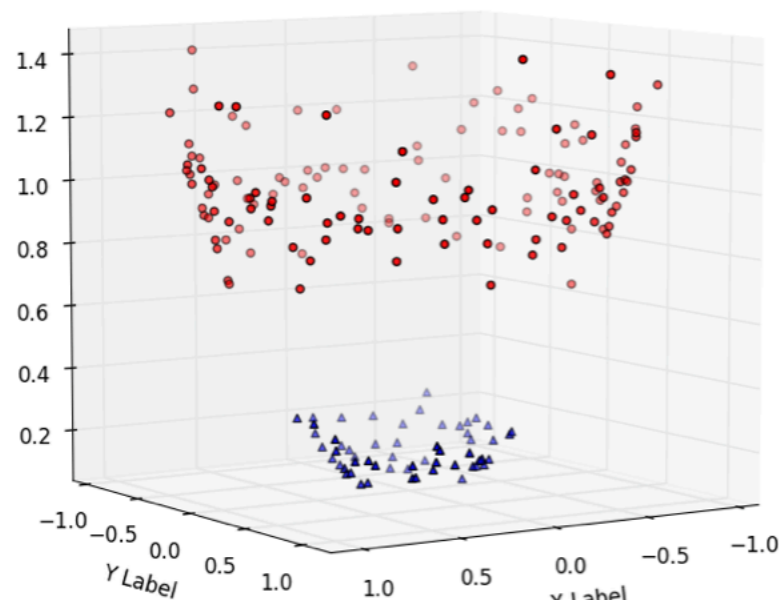
Linearly non-separable

Mapping to higher dimensional space

Mapping to higher dimensional space



Map to 3D



Linearly separable

Mapping to higher dimensional space

Higher dimensional space

Input feature space



\mathbf{x}



Polynomial of degree d



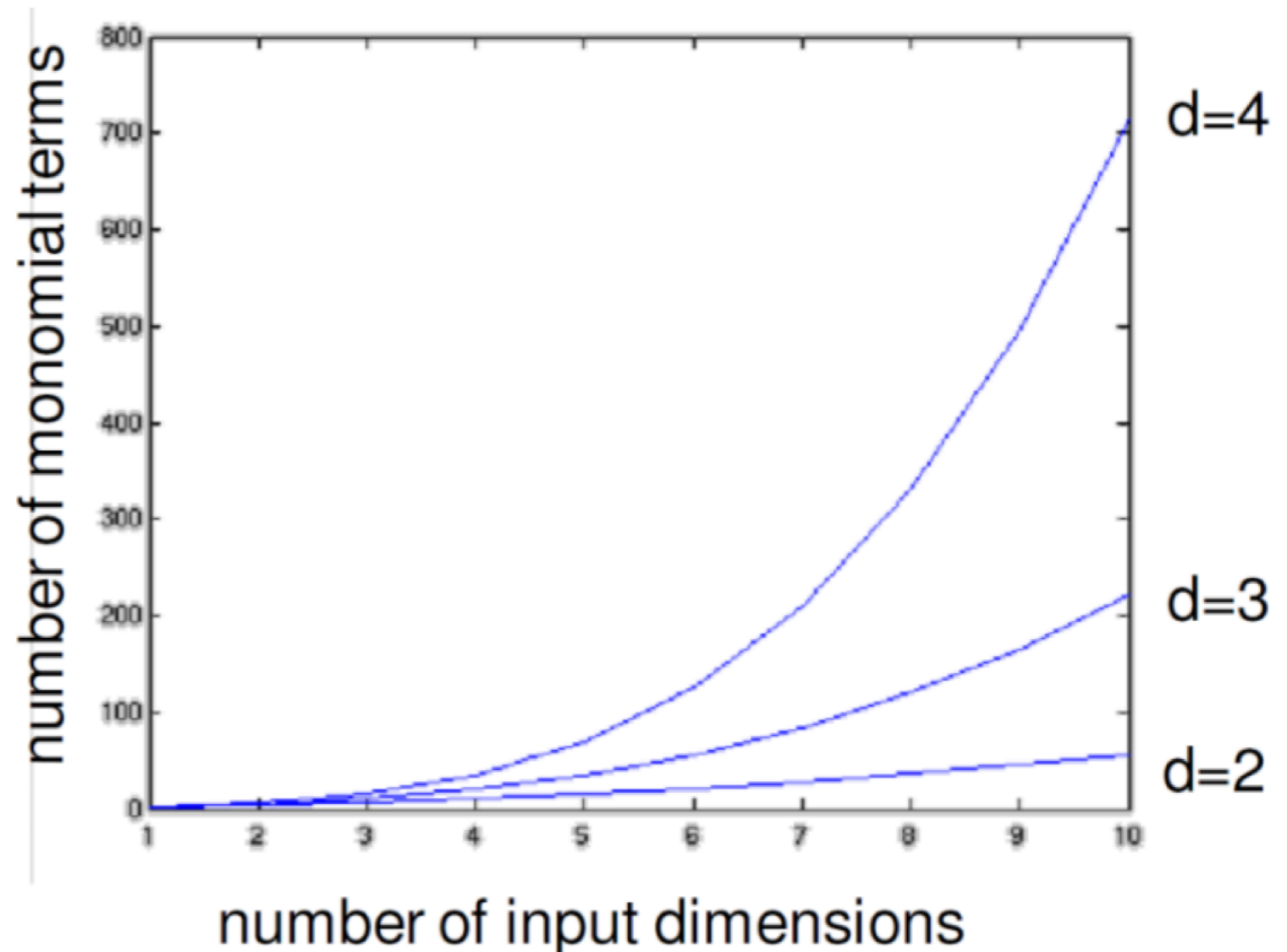
$\mathbf{w} \cdot \phi(\mathbf{x})$

What can go wrong?

$\phi(\mathbf{x})$

Higher order polynomials

- Number of terms = $\binom{d+m-1}{d} = \frac{(d+m-1)!}{d!(m-1)!}$
- where m = dimension of input features; d = degree of polynomial
- Grows fast!
 - $m = 100, d = 6$
 - ~1.6 billion terms



Feature Mappings

- **Pros:** can help turn non-linear classification problem into linear problem
- **Cons:** “feature explosion” creates issues when training linear classifier in new feature space
 - More computationally expensive to train
 - More training examples needed to avoid overfitting

Kernel Methods

- Goal: keep advantages of linear models, but make them capture non-linear patterns in data!
- **How?**
 - By mapping data to higher dimensions where it exhibits linear patterns
 - **By rewriting linear models so that the mapping never needs to be explicitly computed**

The Kernel Trick

- Rewrite learning algorithms so they only depend on **dot products between two examples**
- Replace dot product $\phi(\mathbf{x}) \cdot \phi(\mathbf{z})$
by **kernel function $k(\mathbf{x}, \mathbf{z})$**
which computes the dot product **implicitly**

Example of Kernel function

- Consider two examples $\mathbf{x} = \{x_1, x_2\}$ and $\mathbf{z} = \{z_1, z_2\}$
- Let's assume we are given a function k (kernel) that takes as inputs \mathbf{x} and \mathbf{z}
- **Cool!** taking a dot product and an exponential gives same results as mapping into high dimensional space and then taking dot product
- The above k **implicitly** defines a mapping ϕ to a higher dimensional space

Kernel function

Input space

Feature space
(higher dimension)

- But, it isn't obvious yet how we will incorporate it into actual learning algorithms.

We will do that next...

“Kernelizing” learning algorithms

- **Key idea:** map to higher dimensional space
 - If \mathbf{x} is in \mathbb{R}^n , then $\phi(\mathbf{x})$ is in \mathbb{R}^m for $m > n$
 - We can now learn feature weights \mathbf{w} in \mathbb{R}^m and
 - predict y by computing $\mathbf{w} \cdot \phi(\mathbf{x})$
 - Linear function in the higher dimensional space will be non-linear in the original space

Question to think about...

How can we “Kernelize” perceptron learning algorithm?