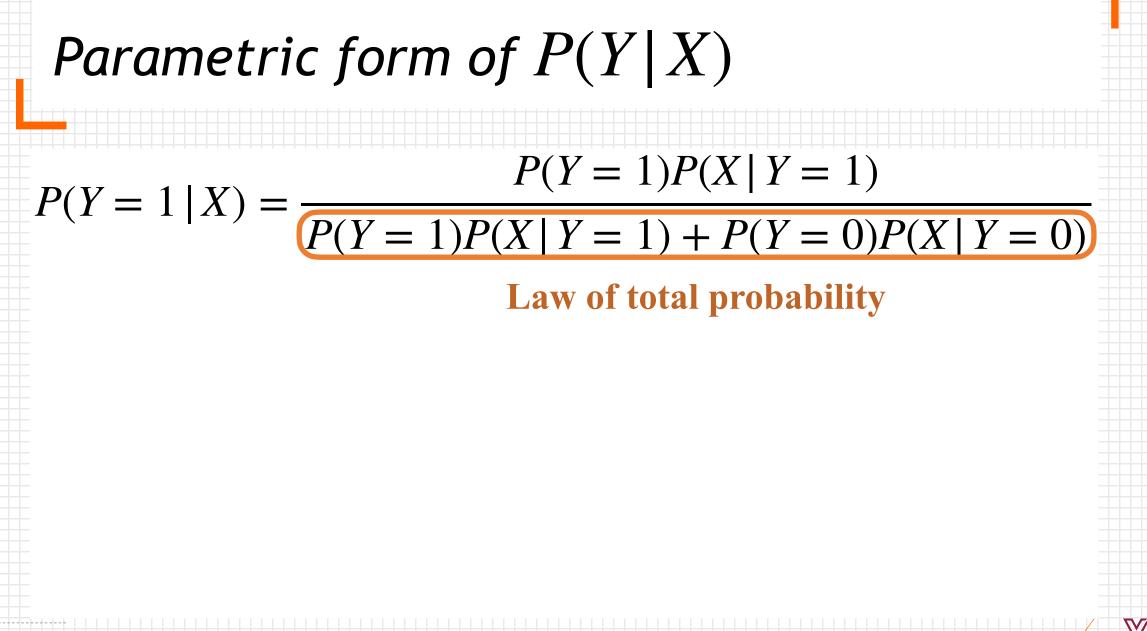


Problem Setting

- Learning $f: X \to Y$
- X is a real-valued vector [X₁, X₂, ..., X_n]
 Y is boolean
- Assume conditional independence given Y
- Model $P(X_i | Y = y_k)$ as Gaussian $\sim \mathcal{N}(\mu_{ik}, \sigma_i)$
- Model P(Y) as Bernoulli $\sim \pi$

• What's the parametric form of P(Y|X)





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Parametric form of
$$P(Y | X)$$

$$P(Y = 1 | X) = \frac{P(Y = 1)P(X | Y = 1)}{P(Y = 1)P(X | Y = 1) + P(Y = 0)P(X | Y = 0)}$$

$$= \frac{1}{1 + \frac{P(Y = 0)P(X | Y = 0)}{P(Y = 1)P(X | Y = 1)}}$$

$$= \frac{1}{1 + exp(\ln \frac{P(Y = 0)P(X | Y = 0)}{P(Y = 1)P(X | Y = 1)})} \ln \text{trick}$$

$$= \frac{1}{1 + exp(\ln \frac{1 - \pi}{\pi} + \sum_{i} \ln \frac{P(X_{i} | Y = 0)}{P(X_{i} | Y = 1)})}$$





 \rightarrow

Continue calculation 1

$$\sum_{i} ln \frac{P(X_i \mid Y = 0)}{P(X_i \mid Y = 1)} =$$

With
$$P(X_i = i | Y = y_k) = \frac{1}{\sqrt{2\pi\sigma_i^2}} e^{-\frac{(x - \mu_{ik})^2}{2\sigma_i^2}}$$



$$P(X_{i} = i | Y = y_{k}) = \frac{1}{\sqrt{2\pi\sigma_{i}^{2}}} e^{-\frac{(x-\mu_{i}y)^{2}}{2\sigma_{i}^{2}}}$$

$$\sum_{i} \ln \frac{P(X_{i} | Y = 0)}{P(X_{i} | Y = 1)} = \sum_{i} \ln \frac{\frac{1}{\sqrt{2\pi\sigma_{i}^{2}}} e^{-\frac{(x-\mu_{i}y)^{2}}{2\sigma_{i}^{2}}}}{\frac{1}{\sqrt{2\pi\sigma_{i}^{2}}} e^{-\frac{(x-\mu_{i}y)^{2}}{2\sigma_{i}^{2}}}}$$

$$= \sum_{i} \ln e^{-\frac{(x-\mu_{i}y)^{2}}{2\sigma_{i}^{2}}} - \frac{(x-\mu_{i}y)^{2}}{2\sigma_{i}^{2}}}{\frac{1}{2\sigma_{i}^{2}}}$$

$$= \sum_{i} -\frac{(x^{2} - 2x\mu_{i0} + \mu_{i0}^{2}) - (x^{2} - 2x\mu_{i1} + \mu_{i1}^{2})}{2\sigma_{i}^{2}}}$$

$$= \sum_{i} \frac{2(\mu_{i1} - \mu_{i0})x_{i} + \mu_{i1}^{2} - \mu_{i0}^{2}}{2\sigma_{i}^{2}}} = \sum_{i} \frac{\mu_{i1} - \mu_{i0}}{2\sigma_{i}^{2}} x_{i} + \frac{\mu_{i1}^{2} - \mu_{i0}^{2}}{2\sigma_{i}^{2}}}{\frac{2\sigma_{i}^{2}}{2\sigma_{i}^{2}}}$$

$$w_{i}x_{i}$$
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$$\begin{aligned} & \mathcal{C} ontinue \ calculation \ 3 \\ & P(Y=1|X) = \frac{P(Y=1)P(X|Y=1)}{P(Y=1)P(X|Y=1) + P(Y=0)P(X|Y=0)} \\ & = \frac{1}{1 + exp(ln\frac{1-\pi}{\pi} + \sum_{i} \frac{\mu_{i1}^{2} - \mu_{i0}^{2}}{2a_{i}^{2}} + \sum_{i} \frac{\mu_{i1} - \mu_{i0}}{a_{i}^{2}} x_{i})} \\ & = \frac{1}{1 + exp(w_{0} + \sum_{i=1}^{n} w_{i}x_{i})} \end{aligned}$$

$$\begin{aligned} & \text{Optionally add } x_{0} = 1 \text{ to incoporate } w_{0} \text{ into the sum} \end{aligned}$$

$$& \text{Where } \begin{cases} w_{0} \ = \ln \frac{1-\pi}{\pi} + \sum_{i} \frac{\mu_{i1}^{2} - \mu_{i0}^{2}}{2a_{i}^{2}} \\ w_{i} \ = \frac{\mu_{i1} - \mu_{i0}}{a_{i}^{2}} \end{cases}$$

VIRGINIA TECH.

 \rightarrow

Obtain Y directly from X with Parameters

$$P(Y = 1 | X) = \frac{1}{1 + exp(w_0 + \sum_{i=1}^{n} w_i x_i)}$$

$$\Rightarrow P(Y = 0 | X) = \frac{exp(w_0 + \sum_{i=1}^{n} w_i x_i)}{1 + exp(w_0 + \sum_{i=1}^{n} w_i x_i)}$$

$$\Rightarrow \frac{P(Y = 0 | X)}{P(Y = 1 | X)} = exp(w_0 + \sum_{i=1}^{n} w_i x_i) \quad \text{Compared with } 1$$

$$\Rightarrow ln \frac{P(Y = 0 | X)}{P(Y = 1 | X)} = w_0 + \sum_{i=1}^{n} w_i x_i \quad \text{Compared with } 0$$





Predict Y | X in Short

Calculate $w_0 + \sum_{i=1}^{i} w_i x_i$, predict Y = 0 if the result value is greater than 0, otherwise predict Y = 1

Logistic Regression (Generalized)

Let's extend Y to contain more discrete values

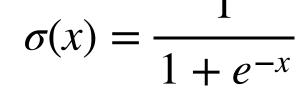
- Previously $Y \in \{0,1\}$, now $Y \in \{y_1, y_2, ..., y_R\}$
- Learn R 1 sets of weights

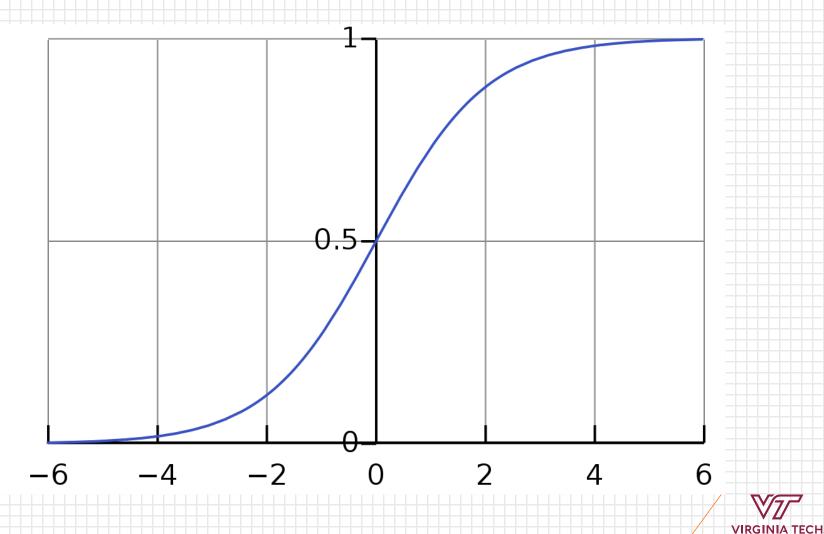
For
$$k < R$$
: $P(Y = y_k | X) = \frac{exp(w_{k0} + \sum_{i=1}^{n} w_{ki}x_i)}{1 + \sum_{j=1}^{R-1} exp(w_{j0} + \sum_{i=1}^{n} w_{ji}x_i)}$
For $k = R$: $P(Y = y_k | X) = \frac{1}{1 + \sum_{j=1}^{R-1} exp(w_{j0} + \sum_{i=1}^{n} w_{ji}x_i)}$

-or
$$k = R$$
: $P(Y = y_k | X) = \frac{1}{1 + \sum_{j=1}^{R-1} exp(w_{j0} + \sum_{i=1}^{n} w_{ji}x_i)}$



Logistic Function





Logistic Regression with MLE

- MLE?
- We have *L* training samples $\{(X^1, Y^1), \dots, (X^L, Y^L)\}$ $W_{MLE} = \operatorname{argmax}_W P((X^1, Y^1), \dots, (X^L, Y^L) | W)$ $= \operatorname{argmax}_W \prod_l P((X^l, Y^l) | W)$
- Have W to generate pairs of (X, Y)?



Logistic Regression MCLE

Maximum Conditional Likelihood Estimation (MCLE)

X is also conditioned

 $W_{MCLE} = \operatorname{argmax}_{W} \prod_{l} P(Y^{l} | X^{l}, W)$



Estimate MCLE

$$W_{MCLE} = \operatorname{argmax}_{W} \prod_{l} P(Y^{l} | X^{l}, W)$$

• We are selecting good W (independent variable) to get highest $\prod_{l} P(Y^{l} | X^{l}, W)$ (dependent variable) A function of W

• Again, assume Y is Boolean

$$f(W) = \ln \prod_{l} P(Y^{l} | X^{l}, W) = \sum_{l} \ln P(Y^{l} | X^{l}, W)$$



Express MCLE as a Function of W

$$f(W) = \sum_{l} \ln P(Y^{l} | X^{l}, W)$$

$$P(Y = 0 | X, W) = \frac{1}{1 + exp(w_{0} + \sum_{i=1}^{n} w_{i}x_{i})}$$
With
$$P(Y = 1 | X, W) = \frac{exp(w_{0} + \sum_{i=1}^{n} w_{i}x_{i})}{1 + exp(w_{0} + \sum_{i=1}^{n} w_{i}x_{i})}$$

$$f(W) = \sum_{l} Y^{l} \ln P(Y^{l} = 1 | X^{l}, W) + (1 - Y^{l}) \ln P(Y^{l} = 0 | X^{l}, W)$$

$$= \sum_{l} Y^{l} \ln \frac{P(Y^{l} = 1 | X^{l}, W)}{P(Y^{l} = 0 | X^{l}, W)} + \ln P(Y^{l} = 0 | X^{l}, W)$$

$$= \sum_{l} Y^{l}(w_{0} + \sum_{i}^{n} w_{i}X_{i}^{l}) - \ln(1 + exp(w_{0} + \sum_{i}^{n} w_{i}X_{i}^{l}))$$

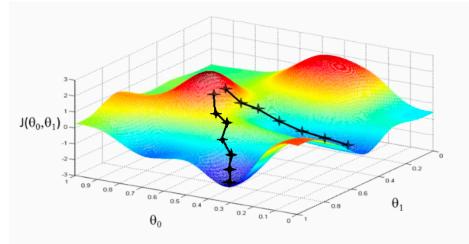
Now we are taking the form and W is conditioned

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Gradient Ascent

Gradient $\nabla f(\vec{w}) = \left[\frac{\partial f}{\partial w_0}, \frac{\partial f}{\partial w_1}, \dots, \frac{\partial f}{\partial w_n}\right]$, is a vector • Parameter training rule: $\vec{w}^{(t+1)} \leftarrow \vec{w}^{(t)} + \eta \nabla f(\vec{w})$ View from one feature dimension $\Delta w_i = \eta \frac{\partial f}{\partial w_i}$



• Questions: What does η imply? What if we have a big η value.



MCLE via Gradient Ascent

$$f(W) = \sum_{l} Y^{l}(w_{0} + \sum_{i}^{n} w_{i}X_{i}^{l}) - \ln(1 + exp(w_{0} + \sum_{i}^{n} w_{i}X_{i}^{l}))$$

$$\frac{\partial f(W)}{\partial w_{i}} = \sum_{l} X_{i}^{l}(Y^{l} - \hat{P}(Y^{l} = 1 | X^{l}, W))$$

• Gradient ascent algorithm: iterate until $\Delta w_i < \epsilon$ $\forall i: w \leftarrow w \perp v \sum Y^l(Y^l - \hat{P}(Y^l - 1 \mid Y^l \mid W))$

$$\forall i: w_i \leftarrow w_i + \eta \sum_l X_i^i (Y^i - P(Y^i = 1 \mid X^i, W))$$

- Incorporate w_0 with an assumed $X_0 = 1$
- η is a hyperparameter: step size



Demo of Searching Best \boldsymbol{W}

https://yihui.org/animation/example/grad-desc/

https://blog.skz.dev/gradient-descent

Batch v.s. Stochastic Gradient

- Batch gradient: use the entire training set D

- Repeat until $\Delta w < \epsilon$

Compute the gradient:
$$\nabla f_D(\vec{w}) = \left[\frac{\partial f_D}{\partial w_0}, \frac{\partial f_D}{\partial w_1}, \dots, \frac{\partial f_D}{\partial w_n}\right]$$

• Update parameters: $\overrightarrow{w}^{(t+1)} \leftarrow \overrightarrow{w}^{(t)} + \eta \nabla f_D(\overrightarrow{w})$

• Stochastic gradient: use a single sample $d \in D$ at a time

- Repeat until $\Delta w < \epsilon$
 - Randomly Choose with replacement a training sample $d \in D$
 - Compute the gradient: $\nabla f_d(\vec{w}) = \left[\frac{\partial f_d}{\partial w_0}, \frac{\partial f_d}{\partial w_1}, \dots, \frac{\partial f_d}{\partial w_n}\right]$
 - Update parameters: $\vec{w}^{(t+1)} \leftarrow \vec{w}^{(t)} + \eta \nabla f_d(\vec{w})$
- Which do we pick when |D| is large?



Hyperparameters in Gradient-based Optimization

Epoch:

- An epoch referes to a full pass over the dataset
- Each sample is used to update parameters once
- The number of epochs is the number of full passes
- Can work together with an early stopping strategy

Batch size:

- Batch size is the number of samples processed when the model is updated
- An epoch can contain one or more batches
- For example, 10 training samples, 2 epochs, batch size as 4
 - 1st epoch
 - Ist iteration: a batch containg sample [1,2,3,4]
 - 2st iteration: a batch containg sample [5,6,7,8]
 - 3st iteration: a batch containg sample [9,10]
 - 2st epoch
 - Ist iteration: a batch containg sample [1,2,3,4]
 - 2st iteration: a batch containg sample [5,6,7,8]
 - 3st iteration: a batch containg sample [9,10]

Conduct experiments to decide hyperparameters





M(C)LE is good, what about MAP?

Choose a prior

$$W_{MAP} = \operatorname{argmax}_{W} P(W) \prod_{l} P(Y^{l} | X^{l}, W)$$

Assume Gaussian prior: $W \sim \mathcal{N}(0, \sigma I)$

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Weight Update with MAP

 $W_{MAP} = \operatorname{argmax}_{W} P(W) \prod_{l} P(Y^{l} | X^{l}, W)$

$$w_i \leftarrow w_i - \eta \lambda w_i + \eta \sum_l X_i^l (Y^l - \hat{P}(Y^l = 1 | X^l, W))$$

Regularization term

- Avoids overfitting especially for sparse data
- Keeps weights near zero with prior



Naïve Bayes v.s. Logistic Regression

- Naïve Bayes
 - Assumption on P(X | Y), P(Y)
 - Estimates parameters of P(X | Y), P(Y) from training data
 - Use Bayes rule to calculate P(Y|X)
- Logistic Regression
 - Assumption on P(Y|X)
 - Estimates parameters of P(Y|X) directly from training data

