

# Turning CARTwheels: An Alternating Algorithm for Mining Redescriptions

Naren Ramakrishnan\*, Deepth Kumar\*, Bud Mishra†, Malcolm Potts#, and Richard F. Helm#

\*Department of Computer Science, Virginia Tech, VA 24061

†Courant Institute of Mathematical Sciences, New York University, NY 10003

#Department of Biochemistry, Virginia Tech, VA 24061

Contact: naren@cs.vt.edu

## ABSTRACT

We present an unusual algorithm involving classification trees—CARTwheels—where two trees are grown in opposite directions so that they are joined at their leaves. This approach finds application in a new data mining task we formulate, called *redescription mining*. A redescription is a shift-of-vocabulary, or a different way of communicating information about a given subset of data; the goal of redescription mining is to find subsets of data that afford multiple descriptions. We highlight the importance of this problem in domains such as bioinformatics, which exhibit an underlying richness and diversity of data descriptors (e.g., genes can be studied in a variety of ways). CARTwheels exploits the duality between class partitions and path partitions in an induced classification tree to model and mine redescriptions. It helps integrate multiple forms of characterizing datasets, situates the knowledge gained from one dataset in the context of others, and harnesses high-level abstractions for uncovering cryptic and subtle features of data. Algorithm design decisions, implementation details, and experimental results are presented.

**Categories and Subject Descriptors:** H.2.8 [Database Management]: Database Applications - Data Mining; I.2.6 [Artificial Intelligence]: Learning

**General Terms:** Algorithms.

**Keywords:** Classification trees, redescriptions, data mining in biological domains.

## 1. INTRODUCTION

Classification and regression trees (CART) were among the earliest proposed approaches for pattern classification and data mining [3]. While being powerful in terms of accuracy and efficiency of induction, their results are also simple to understand as they mimic the decision-making logic of human experts. The renewed emphasis on data mining propagated by the KDD community in the 1990s has fueled

a resurgence of interest in tree-based methods [7, 9].

In this paper we introduce a new data mining task—*redescription mining*—and also propose a novel tree-based algorithm (CARTwheels) for mining redescriptions. A redescription is a shift-of-vocabulary, or a different way of communicating information about a given subset of data; the goal of redescription mining is to find subsets of data that afford multiple descriptions.

Consider the set of all countries in the world. The elements of this set can be described in various ways, e.g., geographical location, political status, scientific capabilities, and economic prosperity. Such features allow us to define various subsets of the given (universal) set, called *descriptors*. Examples of these are shown in Fig. 1.

Redescriptions are equivalences describing a subset in two ways, for instance:

‘Countries with > 200 Nobel prize winners’  $\Leftrightarrow$   
‘Countries with > 150 billionaires’

Both sides of this redescription refer to the singleton set {US}. Such relationships can be mined using techniques from the association rules literature [1], but our view of redescriptions is broader in scope and also includes set-theoretic expressions involving descriptors:

‘Countries with defense budget > \$30 billion’  $\cap$   
‘Countries with declared nuclear arsenals’  $\Leftrightarrow$   
‘Permanent members of U.N. Security Council’  $-$   
‘Countries with history of communism’

Here, we have constructed a set intersection on the left and a set difference on the right, from the given descriptors, and obtained a redescription for the 3-element set: {US, UK, France}. A typical approach to mining such patterns would be to first fix the form of the set-theoretic expressions and then search within the space of possible instantiations. The goal of this paper is to present an algorithmic framework that *simultaneously* constructs set-theoretic expressions and searches in the space of possible redescriptions.

Formally, the inputs to redescription mining are the universal set of objects  $O$  (e.g., countries) and two sets ( $X$  and  $Y$ ) of subsets of  $O$ . The elements of  $X$  are the descriptors  $X_i$ , and are assumed to form a covering of  $O$  ( $\bigcup_i X_i = O$ ). Similarly  $\bigcup_i Y_i = O$ . The only requirement of a descriptor is that it be a proper subset of  $O$  and denote some logical grouping of the underlying objects (for ease of interpretation). The goal of redescription mining is to find equivalence relationships of the form  $E \Leftrightarrow F$  that hold at or above a given Jaccard’s coefficient  $\theta$  (i.e.,  $\frac{|E \cap F|}{|E \cup F|} \geq \theta$ ), where  $E$  and

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$$\begin{aligned}
X_1 &= \{ o_2, o_3 \} & Y_1 &= \{ o_1, o_2, \} \\
X_2 &= \{ o_3, o_4 \} & Y_2 &= \{ o_2, o_3, o_4 \} \\
X_3 &= \{ o_2, o_4 \} & Y_3 &= \{ o_3, o_5 \} \\
X_4 &= \{ o_1, o_5 \} & Y_4 &= \{ o_1, o_2, o_5 \}
\end{aligned}$$

Figure 2: Example data for illustrating operation of CARTwheels algorithm.

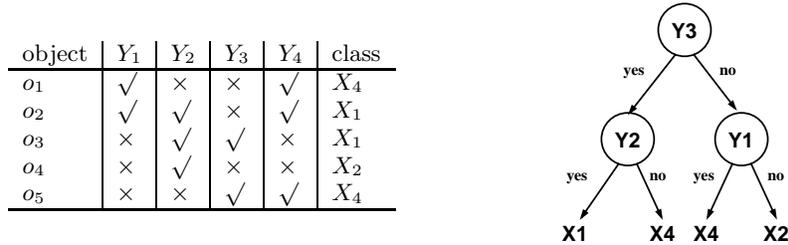


Figure 3: (left) Dataset to initialize CARTwheels algorithm. (right) induced classification tree.

obj.	X <sub>1</sub>	X <sub>2</sub>	X <sub>3</sub>	X <sub>4</sub>	class
o <sub>1</sub>	×	×	×	✓	(Y <sub>3</sub> - Y <sub>2</sub> ) ∪ (Y <sub>1</sub> - Y <sub>3</sub> )
o <sub>2</sub>	✓	×	✓	×	(Y <sub>3</sub> - Y <sub>2</sub> ) ∪ (Y <sub>1</sub> - Y <sub>3</sub> )
o <sub>3</sub>	✓	✓	×	×	Y <sub>3</sub> ∩ Y <sub>2</sub>
o <sub>4</sub>	×	✓	✓	×	O - Y <sub>3</sub> - Y <sub>1</sub>
o <sub>5</sub>	×	×	×	✓	(Y <sub>3</sub> - Y <sub>2</sub> ) ∪ (Y <sub>1</sub> - Y <sub>3</sub> )

obj.	Y <sub>1</sub>	Y <sub>2</sub>	Y <sub>3</sub>	Y <sub>4</sub>	class
o <sub>1</sub>	✓	×	×	✓	(X <sub>3</sub> ∩ X <sub>1</sub> ) ∪ (X <sub>4</sub> - X <sub>3</sub> )
o <sub>2</sub>	✓	✓	×	✓	(X <sub>3</sub> ∩ X <sub>1</sub> ) ∪ (X <sub>4</sub> - X <sub>3</sub> )
o <sub>3</sub>	×	✓	✓	×	(O - X <sub>3</sub> - X <sub>4</sub> )
o <sub>4</sub>	×	✓	×	×	(X <sub>3</sub> - X <sub>1</sub> )
o <sub>5</sub>	×	×	✓	✓	(X <sub>3</sub> ∩ X <sub>1</sub> ) ∪ (X <sub>4</sub> - X <sub>3</sub> )

Figure 4: (left) Dataset for second iteration of CARTwheels algorithm. Notice that class labels are now set-theoretic expressions involving  $Y_i$ 's. (right) Dataset for third iteration of CARTwheels algorithm.

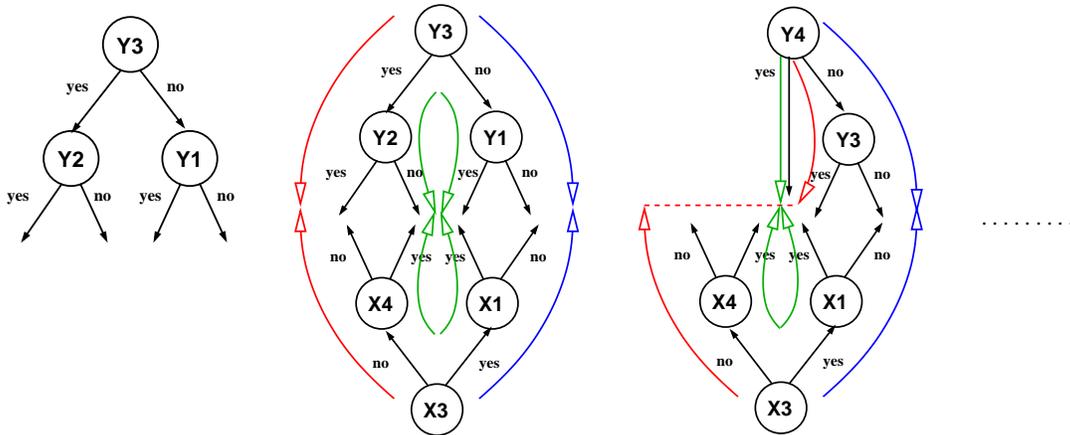


Figure 5: Alternating tree growing in the CARTwheels algorithm. The alternation begins with a tree (first frame) defining set-theoretic expressions to be matched. The bottom tree is then grown to match the top tree (second frame), which is then fixed, and the top tree is re-grown (third frame). Colored arrows indicate the matching paths. Redescriptions corresponding to matching paths at every stage are read off and subjected to evaluation by Jaccard's coefficient.

corresponds to  $O - Y_3 - Y_1$ , and the union of the two middle paths gives  $(Y_3 - Y_2) \cup (Y_1 - Y_3)$ . The reader can verify that these regions do not have a one-to-one correspondence with the regions  $X_1$ ,  $X_2$ , and  $X_4$  in the original partition. For instance, only  $X_2$  enjoys such a correspondence, with  $O - Y_3 - Y_1$ . In ‘reading off’ a partition from a tree in this manner, a conjunction thus results from a path of length  $> 1$ , a disjunction results from multiple paths predicting the same class, with negations corresponding to following the ‘no’ branch from a given node. This partition is used as the starting point for the alternation (Fig. 5, first frame).

We now prepare a dataset with entries from  $X$  as the features and the regions thus formed (involving  $Y_i$ ’s) as the classes, as shown in Fig. 4 (left). Inducing a classification tree from this dataset really corresponds to growing a second tree to match the first tree at the leaves, as depicted in Fig. 5 (second frame). In this case, the second tree also learns a 3-partition and we can evaluate each of these matchings using the Jaccard’s measure. This produces three redescription:

$$\begin{aligned} (X_3 \cap X_1) \cup (X_4 - X_3) &\Leftrightarrow (Y_3 - Y_2) \cup (Y_1 - Y_3) \\ (X_3 - X_1) &\Leftrightarrow (O - Y_3 - Y_1) \\ (O - X_3 - X_4) &\Leftrightarrow (Y_3 \cap Y_2) \end{aligned}$$

all of which hold at Jaccard’s coefficient 1. This need not be the case in general. The bottom tree might be able to match only some paths in the top tree, or the matches might not pass our Jaccard’s cutoff. This process is then continued, now with  $Y_i$ ’s as features and the partitions derived from the bottom tree as classes (see right of Fig. 4). The new matchings yield the redescriptions:

$$\begin{aligned} (X_3 \cap X_1) \cup (X_4 - X_3) &\Leftrightarrow Y_4 \\ (O - X_3 - X_4) &\Leftrightarrow (Y_3 - Y_4) \\ (X_3 - X_1) &\Leftrightarrow (O - Y_3 - Y_4) \end{aligned}$$

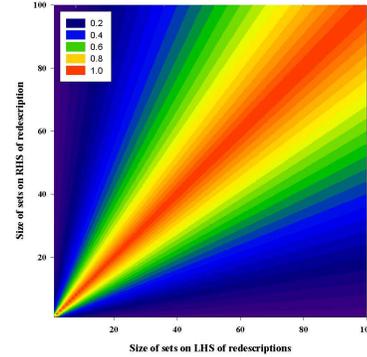
which, fortuitously, also have a Jaccard’s coefficient of 1. Notice that, this time, the root decision node that has been picked is  $Y_4$  (see third frame of Fig. 5) and the tree actually resembles a *decision list* (a tree where every internal node has a leaf on its ‘yes’ branch). The alternation can be continued (see Sec. 2.4 for ways to configure the search).

If we limit the size of the trees at every iteration, it is easy to see that the set-expressions constructed cannot get arbitrarily long. In our running example, we use a depth limit of 2 so that all expressions on either side of a mined redescription can involve at most three descriptors. The longest expressions result from unions of two paths involving different subtrees.

## 2.2 Why does CARTwheels work?

The use of trees to mine one-directional implications (rules) is well understood and is the idea behind algorithms such as C4.5 [15]. In CARTwheels, we exploit the duality between *class partitions* and *path partitions* to posit the stronger notion of equivalence. In fact, if a tree reduces the entropy to zero, it is clear that there must be a one-to-one correspondence between its path partitions and class partitions, which are really path partitions from the other tree. Keep in mind that different paths are union-ed when they predict the same class, and this property is crucial to establishing the duality.

The search for redescriptions in CARTwheels can be viewed as a problem of identifying (and creating) correlated random



**Figure 6: Contour plot depicting best attainable Jaccard’s coefficient, for different set sizes.**

variables. We present a simple analysis in the case of one-level tree (the extension to more levels is beyond the scope of this paper). A descriptor, e.g.,  $D$ , can be considered to be a discrete random variable that takes on values from  $O$ . Every object in  $D$  occurs with probability  $\frac{1}{|D|}$  and other objects occur with probability zero, to yield total probability mass of 1. Notice that this makes the self entropy of such a random variable to be the logarithm of the size of the descriptor. Now consider running a CARTwheels alternation with a depth limit of 1 for the classification trees. Mining a redescription with Jaccard’s coefficient of 1 is equivalent to identifying a random variable  $D'$  whose *entropy distance* from  $D$  is zero. The entropy distance is given by:

$$H(D, D') - I(D; D')$$

where  $H(D, D')$  is the joint entropy function of  $\{D, D'\}$  and  $I$  qualifies the mutual information, in turn given by:

$$I(D; D') = H(D) - H(D|D')$$

where  $H(D)$  is the self-entropy of  $D$  and  $H(D|D')$  is the conditional entropy of  $D$  given  $D'$ . In other words, the average reduction in uncertainty about  $D$  due to knowing  $D'$  is exactly the self entropy of  $D$ , causing an entropy distance of 0. Entropy distance is a true distance measure, unlike measures such as the Kullback-Leibler (KL) divergence. Smaller values of entropy distance hence imply higher values of Jaccard’s coefficient.

## 2.3 Configuring Alternations in CARTwheels

CARTwheels provides a general framework to explore a space of redescriptions; to configure its alternation, there are several issues to be considered.

We will begin by observing that the continuation of CARTwheels alternation, after mining a redescription, is really an attempt to explore and stay within a relatively small region of high Jaccard’s coefficient. Fig. 6 shows an idealized scenario where descriptors (or expressions derived from them) occur in all possible sizes, with the best possible overlaps. In a realistic dataset, the regions of high Jaccard’s coefficient might be disjoint, and a good exploration policy must try to visit all potential regions.

In contrast to traditional classification tree induction which is motivated at *reducing* entropy, CARTwheels must actually *maintain* entropy in some form, since impurity drives exploration. However, if the impurity in the underlying datasets remains constant, some redescriptions are bound to be found over and over again. The tradeoff here is clearly between ex-

<p><b>Input:</b> objects <math>O</math>, descriptor sets <math>\{X_i\}, \{Y_i\}</math>  <b>Output:</b> redescriptions <math>\mathcal{R}</math>  <b>Parameters:</b>  <math>\theta</math> (Jaccard’s coefficient),  <math>d</math> (depth of trees),  <math>\rho</math> (# of class participations allowed/descriptor), and  <math>\eta</math> (max. # of consecutive unsuccessful alternations).  <b>Initialization:</b>  set answer set <math>\mathcal{R} = \{\}</math>  set class participation counts for all <math>\{X_i\}, \{Y_i\} = 0</math>  set feature set <math>\mathcal{F} = \{Y_i\}</math>  set classes <math>\mathcal{C} = \{X_i\}</math>  set dataset <math>\mathcal{D} = \text{construct\_dataset}(O, \mathcal{F}, \mathcal{C})</math>  set tree <math>t = \text{construct\_tree}(\mathcal{D}, d)</math>  if (all leaves in <math>t</math> have same class <math>c \in \mathcal{C}</math>)    set <math>l =</math> random leaf in <math>t</math> having non-zero entropy    <math>\text{impurify}(t, l)</math>  <math>\mathcal{C} = \text{paths\_to\_classes}(t)</math>  flag = false; count = 0  <b>Alternation:</b>  <math>\mathcal{G} = \{X_i\}</math>  while (count &lt; <math>\eta</math>)    <math>\mathcal{F} = \mathcal{G}</math>    if (flag = false)    { <math>\{X_i\} = \mathcal{G}; \mathcal{G} = \{Y_i\}</math>    else    { <math>\{Y_i\} = \mathcal{G}; \mathcal{G} = \{X_i\}</math>    endif    <math>\mathcal{D} = \text{construct\_dataset}(O, \mathcal{F}, \mathcal{C})</math>    <math>t = \text{construct\_tree}(\mathcal{D}, d)</math>    if (all leaves in <math>t</math> have same class <math>c \in \mathcal{C}</math>)    set <math>l =</math> random leaf in <math>t</math> having non-zero entropy    <math>\text{impurify}(t, l)</math>    endif    <math>\mathcal{R}_{new} = \text{eval}(t, \theta)</math>    if (<math>\mathcal{R}_{new} = \{\}</math>)    count = count + 1    else    count = 0    foreach <math>c \in \mathcal{C}</math>    if <math>c</math> is involved in some <math>r \in \mathcal{R}_{new}</math>    <math>\mathcal{H} = \text{descriptors}(c)</math>    foreach descriptor <math>g \in \mathcal{G} \cap \mathcal{H}</math>    increase <math>g</math>’s class participation count    if <math>g</math>’s class participation count &gt; <math>\rho</math>    remove <math>g</math> from <math>\mathcal{G}</math>    endif    endif    endif    end if    <math>\mathcal{R} = \mathcal{R} \cup \mathcal{R}_{new};</math> flag = not(flag)    <math>\mathcal{C} = \text{paths\_to\_classes}(t)</math>  end while</p>
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**Table 1: CARTwheels algorithmic framework.**

ploration and redundancy: to support sufficient exploration, we must accept redundancy, and conversely if we desire to reduce redundancy, we must settle for insufficient coverage of the redescription space. This tradeoff suggests that a tunable parameter for CARTwheels alternation is the number of times that a descriptor is allowed to participate in redescriptions.

## 2.4 The CARTwheels Algorithmic Framework

Table 1 describes the CARTwheels algorithmic framework in detail. The outline follows the example shown previously: *construct\_dataset* prepares a dataset suitable for CART induction as in Fig. 3; *construct\_tree* creates the decision tree of depth  $d$ ; and *paths\_to\_classes* reads expressions off an induced tree, to be used as classes in the next step for each

object in  $O$ . Notice the use of an *impurify* function in both the initialization and the alternation steps, which typically assigns the second-best class label to the chosen leaf  $l$ . Additional impurification steps, to aid exploration, are included in our implementations of *construct\_tree* (e.g., we do not always branch on the attribute with the best entropy gain and sometimes perform randomized moves at the root level).

The *eval* function returns redescriptions satisfying the Jaccard’s threshold  $\theta$ . Our implementation of *eval* requires redescriptions to hold in both the mined and complementary forms, e.g., for the equivalence  $E_1 \cup E_2 \Leftrightarrow F$  to be considered as a redescription, it must hold with Jaccard’s coefficient at least  $\theta$ , as must its complement:  $\neg E_1 \cap \neg E_2 \Leftrightarrow \neg F$ . This ensures that every redescription truly induces a partition of  $O \times O$  space. *descriptors* is a function that analyzes a set-theoretic expression and returns the set of descriptors participating in it.

The important tunable parameter in Table 1 is  $\rho$ , controlling the tradeoff between redundancy and exploration. A participation count is incremented each time a given descriptor appears in a redescription in its role as part of a class, and when this reaches  $\rho$ , the descriptor is removed from consideration. The parameter  $\eta$  specifies the maximum number of alternations that CARTwheels can go through without mining any redescriptions.

## 2.5 Assessing Significance of Mined Redescriptions

There are many ways to assess significance of redescriptions mined by CARTwheels. They vary in their formulation of the null hypothesis. For instance, given a redescription  $X \Leftrightarrow Y$  with Jaccard’s coefficient  $\theta$  we can ask ‘how likely is it that two descriptor expressions of size  $|X|$  and  $|Y|$  have  $\theta$  as their Jaccard’s coefficient?’ or ‘how significant is it that expressions having the same syntactic bias as  $X$  and  $Y$  have  $\theta$  as their Jaccard’s coefficient?’ The first approach focuses on the sizes of the descriptor expressions whereas the second is concerned with the way expressions are constructed, and must inherently utilize the distribution of descriptor sizes (and maybe second order information, such as commonality or differences). We adopt the first approach in this paper.

Specifically, we assess if the Jaccard’s coefficient ( $\theta$ ) can happen by chance if we had chosen sets  $X$  and  $Y$  randomly from the available universal set  $O$ , keeping  $|X|$  and  $|Y|$  fixed. This yields a simple statistical test giving a p-value based on the distribution of set overlaps for the given set sizes (details omitted for space considerations). Keep in mind that one way to get a strong p-value would be to have very small sizes for  $X$  and  $Y$  (which in turn, make the achievement of a respectable  $\theta$  difficult). On the other hand, if  $X$  and  $Y$  are large, the ease with which they could overlap increases, and hence even high Jaccard coefficients might not correspond to a strong p-value. Therefore, for interpretation purposes, it is important to not think of intersection size as a surrogate for significance of redescriptions. In the experiments reported here, we have found statistically significant redescriptions involving as few as 1 object to as large as 80 objects.

## 2.6 Implementation Details

CARTwheels is implemented in C++ atop a Postgres database providing access to the descriptors. We use an AD-tree data structure [13] for fast counting purposes and estimation of entropy (this is distinct from the classification tree

**Table 2: Summary of universal sets and descriptors.**

	$G_1$	$G_2$	$G_3$
# stresses	5	7	7
# expts	7	9	9
# ORFs	74	332	171
GO (biological process) descriptors	210	479	382
GO (cellular component) descriptors	42	112	97
GO (molecular function) descriptors	126	298	204
Expression level range descriptors	224	373	344
k-means clusters	70	270	0
Histone expression range descriptors	152	168	162
# descriptors	824	1700	1189

that combines the descriptors). The AD-tree provides access to the distributions of ‘class labels’ for every combination of ‘features’ and, since the definition of features and class labels change at every iteration, is rebuilt continually. Notice that the data structure is expected to provide both the sizes of descriptors as well as their negations (when we follow the ‘no’ branch) and hence, the depth of the AD-tree is set to just greater than the allowable depth of the classification trees. The CARTwheels algorithm consults the AD-tree whenever it must make a choice of a decision node (except when its move is exploratory). After evaluating matchings, set-expressions read off the trees are subjected to tabular minimization, in order to arrive at a canonical form.

The implementation allows for configuring the space of redescription that are explored. The depth limit for the top and bottom trees can be individually specified, and we can also preferentially include or exclude certain types of expressions in mined redescription. For instance, syntactic constraints on redescription (e.g., only conjunctions are allowed) can be incorporated as biases in the tree construction phase of CARTwheels.

### 3. APPLICATIONS IN BIOINFORMATICS

We now present an application of CARTwheels to studying gene expression datasets from microarray experiments conducted on the budding yeast *Saccharomyces cerevisiae*. Bioinformatics is fertile ground for application of CARTwheels and *S. cerevisiae* is arguably the most well studied (and documented) model organism through bioinformatics techniques. Practically every experimental methodology applied toward yeast can be viewed as a way to define descriptors. Even the results of other data analysis/mining algorithms can be used as a source of descriptors! The underlying universal set of objects could be initialized to the set of genes, proteins, or processes, in *S. cerevisiae*. CARTwheels hence brings many computational and experimental technologies to bear upon redescription mining. It supports the capture of both similarities and distinctions among descriptors derived from these diverse sources.

#### 3.1 Datasets

The redescription process begins by defining the universal set of genes (or open reading frames, ORFs)  $G$ , which is dependent on our biological goals. Here, we are interested in characterizing similarities and differences in yeast gene expression behavior across related families of stresses. Gasch et al. ([8]) is an important source for such a study since it provides results from more than 170 comparisons,

across a variety of environmental stresses. We use three different universal sets, to illustrate diverse ways of using the CARTwheels framework:

$G_1$ : the set of ORFs that show significant change in expression (more than 1-fold up- or down-regulation) in some time point in each of the five stresses from (heat shock from 25°C to 37°C, hyper-osmotic shock, hypo-osmotic shock,  $H_2O_2$  exposure, and mild heat shock at variable osmolarity).

$G_2$ : the set of ORFs that show more than 4-fold up- or down-regulation change in expression in some time point in each of the seven stresses from (heat shock from 25°C to 37°C, hyper-osmotic shock, hypo-osmotic shock,  $H_2O_2$  exposure, mild heat shock at variable osmolarity, heat shock from 37°C to 25°C, and heat shock from 29°C to 33°C). Notice that two additional stresses are included, from how  $G_1$  was constructed.

$G_3$ : the set of ORFs more than 4-fold up- or down-regulation change in expression in some time point in each of the seven stresses in  $G_2$  and that do not belong to the set of ESR (Environmental Stress Response) genes as characterized by Gasch et al. ([8]). The ESR dataset (comprising 868 ORFs) constitute a characterization of yeast ORFs that show a marked uniformity of expression across diverse stresses, and hence have been excluded by many researchers in their analyses – see for instance, ([17]).

The choice of the universal set can be viewed as a conditioning context and must be kept in mind when interpreting any mined redescription. It can be viewed as an implicit descriptor occurring on both sides of every mined redescription, e.g.,  $E \Leftrightarrow F$  in  $G_1$  can be viewed as  $E \cap G_1 \Leftrightarrow F \cap G_1$ .

#### 3.2 Descriptor Definition

We defined descriptors for the genes in the chosen universal sets in a variety of ways. One class of descriptors was derived from categories in the GO (Gene Ontology) biological process, GO cellular component, and GO molecular function taxonomies, that have representation among the chosen genes. The microarray results from the stresses of Gasch et al. (relevant to each universal set) were bucketed to yield range descriptors of the form ‘expression level  $\in$  [%x, 0] in time point %y of stress experiment %z’ (for negative %x) and ‘expression level  $\in$  [0, %x] in time point %y of stress experiment %z’ (for positive %x). Notice that we are not constrained to pick descriptors from only the stresses used to define the universal set, although we have made that choice here. Further, k-means clustering was performed using the Genesis software suite ([18]) on each of the stresses individually, with a setting of 10 clusters for  $G_1$  and 10 and 20 clusters for  $G_2$ . No descriptors based on k-means clustering were defined for  $G_3$ . Since heat shock and mild heat shock at variable osmolarity are actually pairs of experiments, this step yields  $(5+2) \times 10 = 70$  (for  $G_1$ ) and  $(7+2) \times (10 + 20) = 270$  (for  $G_2$ ) descriptors, depicting clusters of genes with similar temporal profiles. It must be kept in mind that each of these experiments in turn comprise of multiple time points, different for each stress. Finally, we included microarray results from a histone depletion experiment conducted by Wyrick et al. ([20]) and created range descriptors similar to the Gasch stresses; this is to allow us to relate the effect of histone depletion to that of environmental stresses.

Table 2 summarizes the number of descriptors of each type defined for each of the universal sets, and provides count statistics. Fig. 8 presents frequency plots for the sizes of the descriptors in each of the universal sets. As expected, a majority of descriptors in each case have very few number of ORFs.

### 3.3 CARTwheels Configuration

To invoke CARTwheels for a particular universal set, we initialized  $X$  to be all descriptors derived from the Gasch et al. dataset (which includes the range descriptors as well as the k-means clusters). This ensures that all redescription will involve some aspect of the Gasch et al. experiment and prevents the possibility of, say, mining a redescription between two GO taxonomies.  $Y$  was initialized to the set of all descriptors; thus, there is some overlap between  $X$  and  $Y$ . In order to prevent obvious redescription arising from this overlap, the algorithm was precluded from utilizing descriptors in one tree if they are already present in the other tree.

We employed a Jaccard’s threshold  $\theta$  of 0.5 and a depth-limit  $d \leq 2$  in both the top and bottom tree induction alternations. The limit on the number of allowable alternations  $\eta$  is set to 10, and  $\rho$  was varied from 1 to 6. Redescriptions mined by CARTwheels are subjected to a ‘tightening’ step, akin to rule pruning in packages like C4.5 ([15]). This might involve attempting to drop terms from both sides of the redescription, or restricting range descriptors (if they occur in the redescription), and determining whether this causes significant degradation of Jaccard’s coefficient. If no degradation is observed, then the redescription can be tightened. A p-value cutoff of 0.001 for significance of redescription was utilized in this paper. We first describe the qualitative nature of biological results obtained through redescription and then assess the exploratory behavior of CARTwheels.

### 3.4 Example Redescriptions

Seven key mined redescription (R1–R7) are depicted in Fig. 7. R1–R3 are defined over universal set  $G_1$ , R4–R6 over  $G_2$ , and R7 over  $G_3$ . These redescription were selected for both their biological interest as well as for their feature construction novelties. The proteins encoded by genes in a redescription may interact with one another or, with other proteins not included in the redescription. Such analyses make it possible to uncover cryptic and subtle features of gene expression and regulation.

R1 is a redescription where both sides involve descriptors from gene expression bucketing. It relates negatively expressed ORFs in the histone depletion experiment with similarly expressed ORFs in a Gasch comparison (heat shock). This redescription can be read as ‘of the 74 ORFs in the first universal set, the ORFs negatively expressed in the histone depletion experiment (6 hours) are also those that are negatively expressed two-fold or more in the heat shock (10 minutes) experiment.’ This redescription holds with a Jaccard’s coefficient of 0.78. Since each side contains a single descriptor, this redescription does not present any set construction. R1 involves 7 ORFs, three of which are reported to be regulated by similar mechanisms, according to the work of Segal et al. ([17]). These ORFs comprise functions related to metabolism, catalytic activity, and are located in the cytoplasm. The Pearson coefficients for these ORFs in the histone depletion experiments match very strongly, showcasing the use of redescription in identifying a concerted

set of ORFs.

R2 relates a k-means cluster to a set difference of two related GO cellular component categories. While the 8 ORFs in R2 appear to be part of different response pathways, 5 of these 8 ORFs are similarly regulated according to the work of Segal et al.; these genes relate to the cellular hyperorganization and membrane dynamics in the regulation network.

R3 is actually a triangle of redescription relationships that illustrates the power of CARTwheels. Three different experimental comparisons are involved in this circular chain of redescription, with 10 ORFs being implicated in all three descriptors. From a biological standpoint, this is a very interesting result – the common genes indicate concerted participation across stress conditions; whereas the genes participating in, say, two of the descriptors, but not the third, suggest a careful diversification of functionality. 6 of the 10 ORFs are related to cell growth and maintenance. 5 of the 10 ORFs have binding motifs related to the DNA binding protein REB1. The importance of phosphate and ribosomes appears to be salient in this redescription. It is important to note that the circularity of R3 is not directly mined by CARTwheels, but inferred post-hoc from a linear chain.

The theme in R4 is ribosome assembly/biogenesis and RNA processing. R4 is a linear chain comprising two redescription, and uses a GO descriptor as an intermediary between two expression-based descriptors. It is also interesting that this redescription involves a set of 45 ORFs!

R5 is an even longer chain involving 41 ORFs that are common to all descriptors. Notice the rather complicated set construct involving a disjunction of a conjunction and a difference, involving three different GO biological categories. Incidentally, this is the most complicated set expression representable in a 2-level tree.

R6 is a relationship between two k-means clusters, between heat shock stresses. The ORFs participating in R6 demonstrate a clear focus on sugar or sugar phosphate metabolism.

R7 is a redescription relating a disjunction of descriptors to a GO cellular component category. It is also our first example of a redescription where a rectangular region is mined in a 2D space involving two different experimental comparisons. Usually such a region would require a 4-level tree, but since it is bounded by the extremal values specific to each experiment, it can be captured by a conjunction of merely two descriptors.

### 3.5 Effect of $\rho$ and $\eta$

If we view the alternation process as one of information retrieval, we can adapt traditional precision and recall metrics for algorithm assessment. Precision here refers to the number of unique redescription as a fraction of the total number of redescription mined. Recall refers to the number of unique redescription as a fraction of the total number of redescription possible. Unfortunately, the latter metric is nearly impossible to attain, even for our depth limit of 2. For even the smallest universal set considered here, the size of the space of possible redescription is  $O(10^{14})$ ! Our approach hence is to track precision and the total number of redescription, across various values of  $\rho$ .

Fig. 9 shows the monotonic decrease of precision as  $\rho$  is increased, and Fig. 10 depicts the steady increase in the total number of redescription mined. These graphs indicate that the tradeoff between redundancy and exploration holds

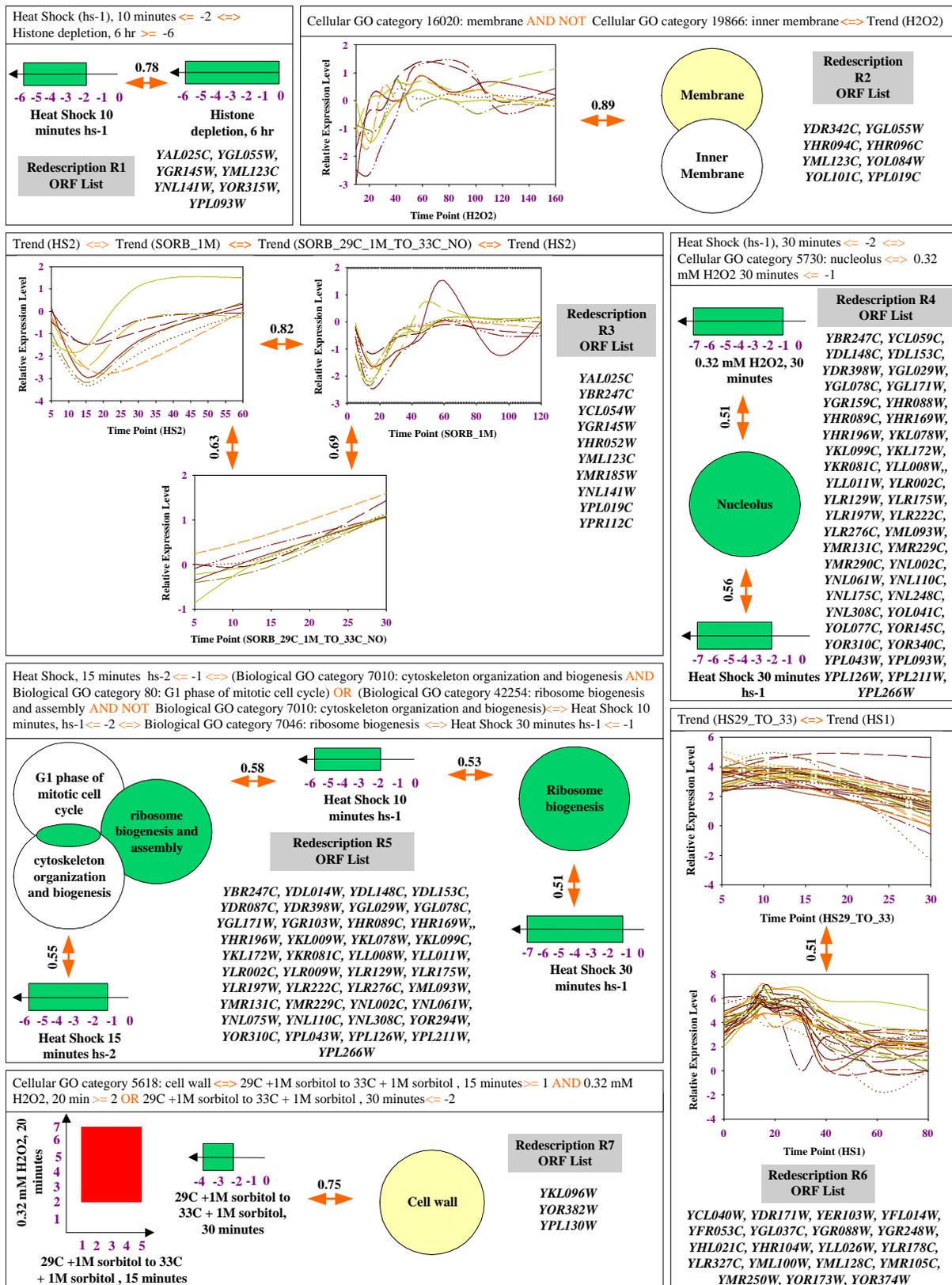


Figure 7: Seven redescrptions mined from gene expression studies on *Saccharomyces cerevisiae*. Each box gives a readable statement of the redescription, presents it in graphical form, and identifies the ORFs conforming to the redescription. R1-R3 are defined over universal set  $G_1$ , R4-R6 over  $G_2$  and R7 over  $G_3$ . The Jaccard's coefficient is displayed over the redescription arrow. Notice that some redescrptions (e.g., R7) involve few ORFs, whereas others such as R5 involve larger numbers.

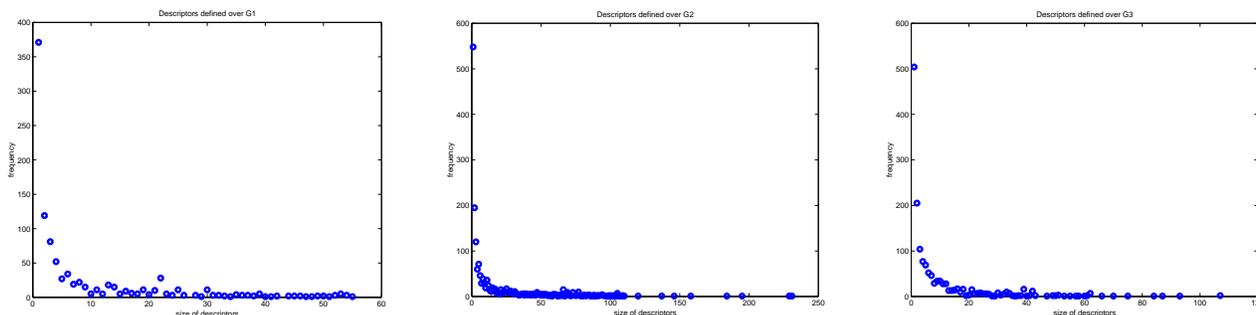


Figure 8: Frequency plot of descriptor sizes for universal set  $G_1$ ,  $G_2$ , and  $G_3$ , respectively.

across all the datasets considered here. A formal characterization is underway.

The effect of  $\eta$  parameter, that controls the number of unsuccessful consecutive alternations, is as expected: increasing  $\eta$  results in a greater number of (total and unique) redescription mined (not shown for space considerations).

#### 4. DISCUSSION

This paper is a first exploration into the formulation of the redescription mining problem and has presented an approach for mining redescription automatically. Redescriptions can be thought of as generalizations of one-directional implications (e.g., association rules [1], rules in ILP [14]), where one descriptor is required to be a proper subset of the other. This generalization coupled with the automatic identification of set-theoretic constructions makes CARTwheels a very powerful approach to mining (approximate) equivalence relations. We have demonstrated the effectiveness of CARTwheels in a domain that exhibits a richness of descriptors, and shown how it captures patterns involving small as well as large sets of objects.

The work presented here has close connections with ideas pursued in the schema matching [16], clustering categorical data [6], and model management [2] literature. The relationships considered in schema matching research are primarily of the foreign key nature or otherwise operate at the instance level, whereas we consider more complex set-theoretic relationships. Clustering categorical data focuses on defining similarity measures in non-metric spaces and this research can be fruitfully integrated with our work. However, notice that we are not merely clustering data but also imposing describability constraints. Model management is a framework that recognizes the complex inter-relationships that would exist in multi-database enterprises and provides union, intersection, and difference operators for reconciliation, integration, and migration purposes. The relationships here are assumed to be user provided, and the emphasis is on actually ‘executing a redescription.’ CARTwheels can thus be usefully employed here as a driver for determining what these relationships should be.

We now outline some directions for future research. The connection between Jaccard’s coefficient and algorithmic driver parameters (such as entropy) deserves further study. Other ways of evaluating redescription [10, 11] are also pertinent here (e.g., Dice coefficient) and some of these could support more efficient tree-based algorithms than the Jaccard’s coefficient. Ideally, an evaluation metric would obey some closure properties in the space of redescription, which can be used to configure an exploration strategy. In addition, it is preferable that an evaluation metric lend itself to the

design of a statistical test of significance for redescription.

Thus far, we have assumed a ‘flat’ organization of the given descriptors and do not recognize any structural relationships between them. However, some descriptor vocabularies (e.g., derived from GO) enjoy a hierarchical structure, which can be exploited by the mining algorithm. Specialized redescription algorithms can thus be designed for targeted descriptor families.

There are various other formulations of the redescription mining problem, in particular the question of identifying a *generating set* of redescription is open. This will avoid having to find all redescription and instead allow us to exploit the algebraic structure of descriptors, akin to the strategy pursued by Zaki for mining a non-redundant set of association rules [21].

There is an intrinsic limit to a dataset’s potential to reveal redescription, which can be studied through statistical analysis of set size distributions and estimates of overlap potential. Of particular interest here is qualifying the ‘expected’ results from a CARTwheels alternation before actually performing the alternation, using notions such as the *entropy rate* of the stochastic process underlying the alternation [4].

Our current focus is on using redescription to automatically span multiple levels of abstraction (e.g., gene subsets  $\rightarrow$  pathways  $\rightarrow$  biological processes). This would firmly establish the importance of redescription in bridging the diverse levels at which information is created and characterized.

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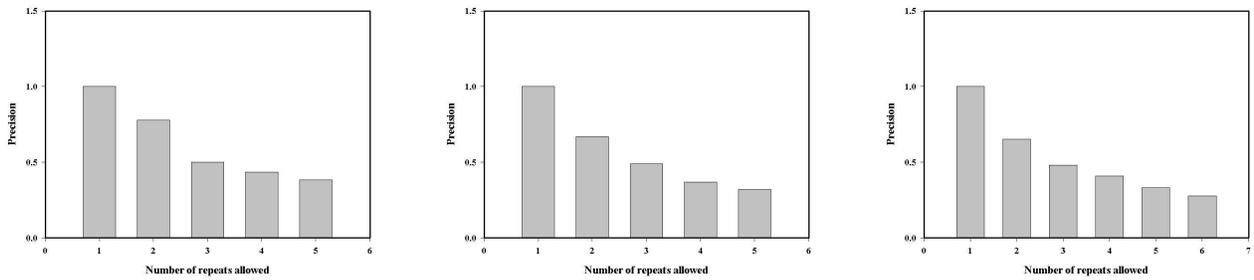


Figure 9: Precision for redescrptions mined vs.  $\rho$  for universal set  $G_1$ ,  $G_2$ , and  $G_3$ , respectively.

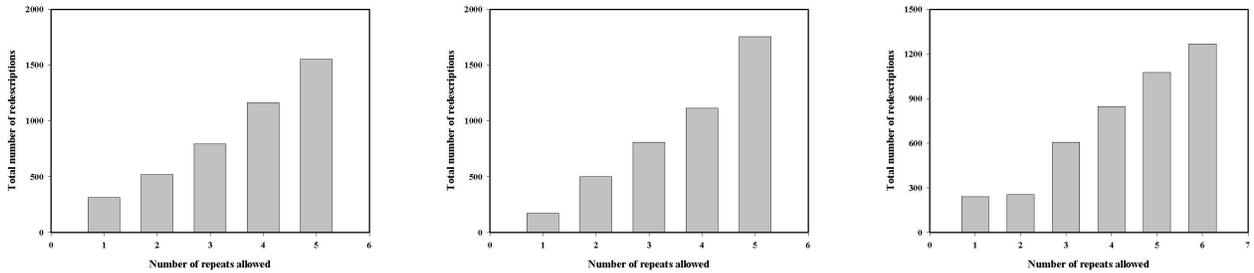


Figure 10: Total number of redescrptions mined vs.  $\rho$  for universal set  $G_1$ ,  $G_2$ , and  $G_3$ , respectively.

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