

I. INTRODUCTION

This correspondence summarizes the results of an experimental study of the use of quadtree region representations in cartography. Quadtree encodings were constructed for the regions in three map overlays representing a small area of Northern California. Programs were then written to perform various analysis and manipulation tasks on the quadtree-encoded regions. This correspondence provides data on the compactness of the encodings and the efficiency of the programs. Further details about the study can be found in [1].

The purpose of the study was to evaluate quadtree encoding and processing techniques for cartographic data. In addition to providing empirical data on the sizes of the quadtrees involved, the study investigated the efficiency of the following specific processing tasks: connected component analysis; computation of area, perimeter, coordinates of centroid, and enclosing upright rectangle for components; determining whether a given point lies in a given region; constructing a quadtree containing a subsection of a region (i.e., a windowing operation); and constructing the quadtree of the union or intersection of two regions.

The quadtree representation of regions, first proposed by Klinger [2], has been the subject of numerous papers over the past few years [3]–[21]. Numerous algorithms have been developed for constructing compact quadtree representations, converting between them and other region representations, computing region properties from them, and computing the quadtree representations of Boolean combinations of regions from those of the given regions. For recent overviews of this literature see [22]–[23]. In particular, for most of the specific tasks mentioned in the previous paragraph, algorithms can be found in [6], [7], [14], [15]. In the study of connected component analysis, several different algorithms were compared, including methods using explicit links (“ropes”) between quadtree nodes representing adjacent image blocks; see [6], [14], [20] for further discussion.

II. DATABASE

The database used in the study was supplied by the U.S. Army Engineer Topographic Laboratory, Ft. Belvoir, VA. It consisted of three map overlays (Figs. 1–3) representing land use classes, terrain elevation contours, and floodplain boundaries. In the case of the elevation contours, only those at multiples of 100 feet were used; and in all cases, only the portions of the overlays bounded by the fiducial marks were used. The data were hand-digitized to 400×450 pixels, and labels were associated with the pixels in each of the resulting regions, specifying the particular land use class or elevation range. The regions were then quadtree-encoded using a 512×512 grid.

Tables I–III show quadtree statistics for the 35 land use classes and 11 elevation ranges, as well as the three regions in the floodplain map. In each table, the column “nodes created” refers to the maximum number of nodes existing at any step in the process of building the quadtree. Building was done “bottom up,” by scanning the image and merging nodes when all the nodes in a 2×2 block are found to be of the same type, as described in [9]. We see that the numbers of “nodes created” ranged from about 1700 to about 14500 (still only a small fraction of the 2^{18} potential pixels in the 512×512 grid), and the numbers in the final quadtrees ranged from about 130 to about 13000. “Black nodes” are leaf nodes representing blocks of pixels belonging to the given region; “white nodes” are leaf nodes representing blocks of background pixels; and “gray nodes” are nonleaf nodes.

These quadtrees were stored on disk in files that contained lists of the node types met in a preorder traversal of the quadtree. Some of the simpler algorithms can manipulate these files di-

Quadtree Region Representation in Cartography: Experimental Results

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Abstract—Results of a study are summarized in which quadtrees were used to encode the regions in three map overlays representing a small area in northern California. Programs were then written to perform various analysis and manipulation tasks on the quadtree-encoded regions. Data is provided on the compactness of the encodings and the efficiency of the programs.

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Fig. 2. Elevation contours.

and building the output tree in accordance with the following rules:

if current nodes are	union	intersection
both black	return black	return black
both white	return white	return white
both gray	recurse	recurse
one black	return other subtree	return black
one white	return white	return other subtree

The second program constructs the quadtree of the intersection between a given region (defined by a quadtree) and a given square window (of size a power of two). This is done by finding the smallest subtree of the given quadtree that contains the

window. If it coincides with the window, return the subtree; if not, split the window into quadrants and process each of them analogously with respect to the current subtree. In both programs, on returning from each recursive call, it is necessary to check if the four leaves in a 2×2 block are all of the same color, and if so, to replace their father by a leaf of that color.

When a region is displayed using its quadtree representation [11], we can generate approximations to the region by truncating the tree at a given level. Fig. 4 shows the results of displaying the central region of the floodplain map using 10, 9, 8, 7, and 6 levels of its quadtree, respectively. Table VII shows the number of nodes at each level (level 1 is the root) for each of the three map overlays when their regions are represented by quadtrees. These approximations show the utility of constructing a breadth-first traversal of a quadtree for purposes of skimming a database.

In general, it should be noted that displaying quadtree files is much faster than pixel-based files on many common CRT devices

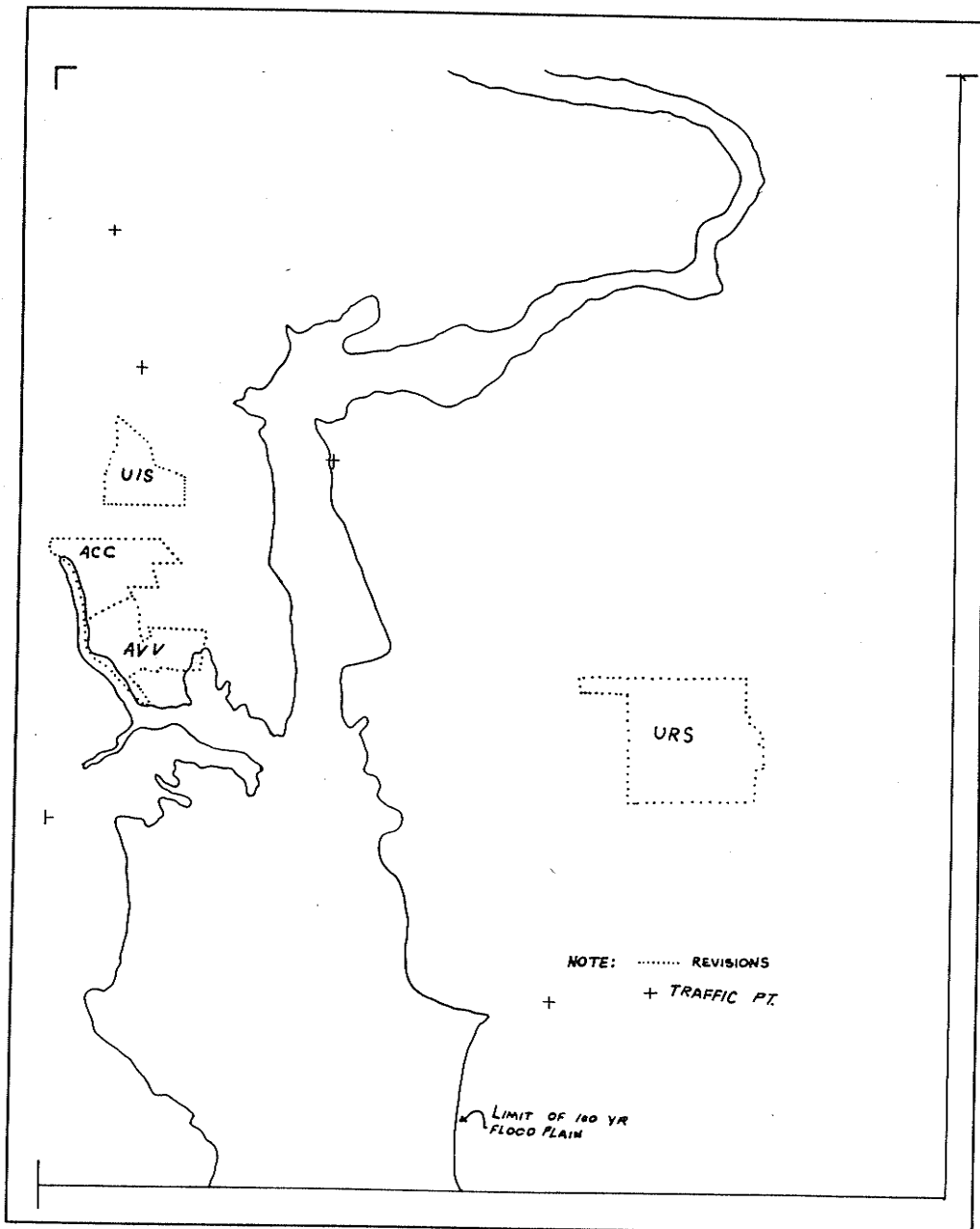


Fig. 3. Floodplain boundaries.

that allow specification of an entire block to be of one color. The leaves of the quadtree indicate a convenient partitioning of a map into monochrome blocks. Since it is not necessary to store the quadtree in core in order to display it, simple hardware could be designed that displayed quadtree files directly.

IV. CONCLUDING REMARKS

The experiments described in this paper provide a quantitative assessment of the efficiency of quadtrees as a means of representing regions in a cartographic database. The quadtree representation is significantly more compact than the binary array representation. Efficient algorithms exist for region property computation and manipulation using the quadtree representation; the expected time required by these algorithms is proportional to the sizes of quadtrees involved as established

on theoretical grounds in [9], [11], [14], [15], [20]. The point-in-polygon and set-theoretic operations on regions are especially efficient. Truncation of quadtrees can be used to generate approximations to regions that are even more compact. We have not given timing results in this correspondence (see [1]) because of their dependence on the operating system and on the available memory. The quadtree algorithms are easy to implement using structured programming languages; in our experiments, the C language was used. In conclusion, our experiments confirm that quadtrees constitute a viable method of region representation which is quite suitable for use in geographic information systems.

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TABLE I
QUADTREE BUILDING STATISTICS FOR LANDUSE MAP

Class	Nodes in Tree	Nodes Created	% Used in Tree	Gray Nodes	White Nodes	Black Nodes
acc	4337	5925	73.2	1084	1847	1406
acp	7725	8981	86.0	1931	3048	2746
ar	1145	2697	42.5	286	499	360
are	129	1725	7.5	32	71	26
avf	11937	13341	89.5	2984	4776	4177
avv	13193	14445	91.3	3298	5359	4536
bbr	537	2109	25.5	134	250	153
beq	353	1873	18.8	88	168	97
bes	193	1825	10.6	48	94	51
bt	2293	3841	59.7	573	951	769
fo	5485	7109	77.2	1371	2121	1993
lr	1481	3045	48.6	370	670	441
r	7001	8609	81.3	1750	2792	2459
ucb	249	1881	13.2	62	118	69
ucc	817	2433	33.6	204	381	232
ucr	1069	2701	39.6	267	457	345
ucw	449	2081	21.6	112	197	140
ues	1113	2737	40.7	278	506	329
uil	345	1977	17.5	86	158	101
uis	1037	2649	39.1	259	453	325
uiw	293	1917	15.3	73	139	81
unk	1121	2681	41.8	280	540	301
uoc	173	1805	9.6	43	79	51
uog	377	2009	18.8	94	149	134
uoo	429	2061	20.8	107	201	121
uop	269	1901	14.2	67	186	66
uov	229	1861	12.3	57	99	73
urn	237	1861	12.7	59	125	53
urs	9921	11313	87.7	2480	3993	3448
uus	297	1921	15.5	74	142	81
uut	3069	4621	66.4	767	1379	923
vv	153	1785	8.6	38	76	39
wo	485	2029	23.9	121	225	139
ws	4677	6245	74.9	1169	2025	1483
wwp	457	2049	22.3	114	101	242

TABLE IV
LANDUSE CONNECTED COMPONENT RESULTS

Class	Number of Neighbors Sought	Findnbr Avg Cost	Ropes Avg Cost	Args Avg Cost
acc	2812	3.55	1.40	3.08
acp	5492	3.58	1.40	2.81
ar	720	3.48	1.33	3.18
are	52	5.63	1.98	4.96
avf	8354	3.53	1.40	2.86
avv	9072	3.55	1.39	2.91
bbr	306	3.59	1.35	3.51
beq	194	3.82	1.31	3.64
bes	102	3.30	1.38	2.80
bt	1538	3.53	1.35	2.98
fo	3986	3.54	1.45	2.75
lr	882	3.71	1.25	3.36
r	4918	3.63	1.46	2.85
ucb	138	3.31	1.20	3.61
ucc	464	3.64	1.37	3.52
ucr	690	3.60	1.42	3.10
ucw	280	3.58	1.36	3.21
ues	658	3.81	1.38	3.38
uil	202	3.75	1.55	3.42
uis	650	3.53	1.39	3.19
uiw	162	3.84	1.35	3.62
unk	602	3.45	1.35	3.72
uoc	102	3.59	1.49	3.39
uog	268	3.66	1.40	2.81
uoo	242	3.22	1.35	3.55
uop	132	3.64	1.42	4.08
uov	146	3.42	1.29	3.14
urn	106	3.89	1.28	4.47
urs	6896	3.54	1.40	2.88
uus	162	3.55	1.35	3.67
uut	1846	3.62	1.38	3.33
vv	78	3.33	1.28	3.92
wo	278	3.97	1.38	3.49
ws	2966	3.70	1.28	3.15
wwp	202	3.62	1.38	4.52

TABLE II
QUADTREE BUILDING STATISTICS FOR TOPOGRAPHY MAP

Elevation	Nodes in Tree	Nodes Created	% Used in Tree	Gray Nodes	White Nodes	Black Nodes
0- 100	6809	8161	83.4	1702	2577	2530
100- 200	13853	14913	92.9	3463	5295	5095
200- 300	11813	13381	88.3	2953	4713	4147
300- 400	8845	10469	84.5	2211	3596	3038
400- 500	7121	8745	81.4	1780	2917	2424
500- 600	6005	7629	78.7	1501	2534	1970
600- 700	5341	6973	76.6	1335	2140	1866
700- 800	4725	6357	74.3	1181	1955	1589
800- 900	3121	4753	65.7	780	1292	1049
900-1000	1277	2909	43.9	319	516	442
1000-1100	161	1793	9.0	40	88	33

TABLE V
TOPOGRAPHY CONNECTED COMPONENT RESULTS

Elevation	Number of Neighbors Sought	Findnbr Avg Cost	Ropes Avg Cost	Args Avg Cost
0- 100	5060	3.48	1.41	2.69
100- 200	10190	3.51	1.41	2.72
200- 300	8294	3.53	1.41	2.85
300- 400	6076	3.57	1.36	2.91
400- 500	4848	3.62	1.36	2.94
500- 600	3940	3.64	1.36	3.05
600- 700	3732	3.62	1.36	2.86
700- 800	3178	3.69	1.38	2.97
800- 900	2098	3.57	1.37	2.98
900-1000	884	3.54	1.41	2.89
1000-1100	66	3.56	1.41	4.88

TABLE III
QUADTREE BUILDING STATISTICS FOR FLOODPLAIN MAP

Area	Nodes in Tree	Nodes Created	% Used in Tree	Gray Nodes	White Nodes	Black Nodes
left bank	4021	5473	73.5	1005	1491	1525
floodplain	6257	7645	81.8	1564	2485	2208
right bank	2885	4009	72.0	721	1133	1031

TABLE VI
FLOODPLAIN CONNECTED COMPONENT RESULTS

Region	Number of Neighbors Sought	Findnbr Avg Cost	Ropes Avg Cost	Args Avg Cost
left bank	3050	3.25	1.35	2.64
floodplain	4416	3.50	1.46	2.83
right bank	2062	3.62	1.66	2.80

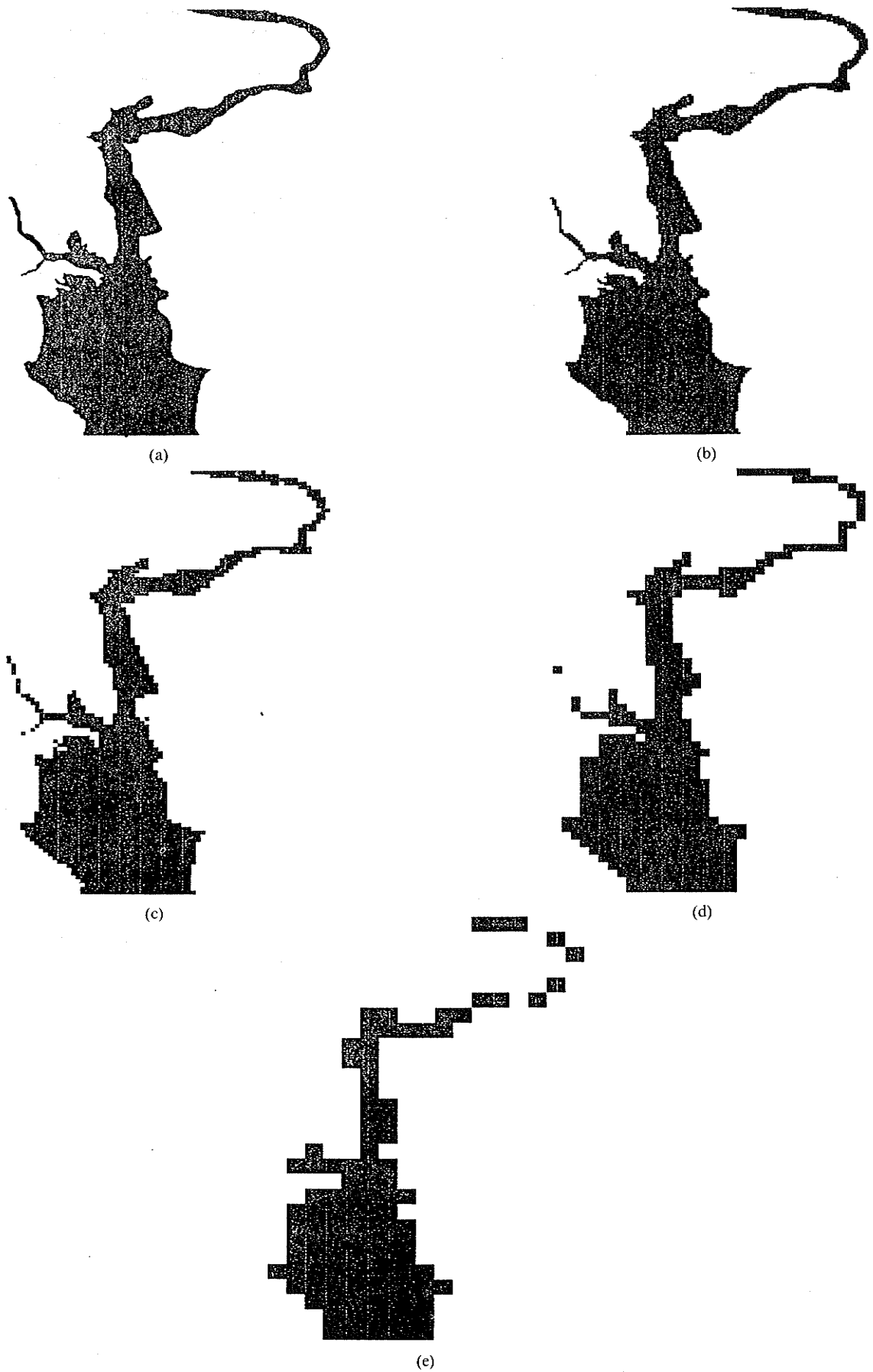


Fig. 4. (a) Result of executing QDISPLAY on flood center of the floodplain map using 10 levels. (b) Result of executing QDISPLAY on flood center of the floodplain map using 9 levels. (c) Result of executing QDISPLAY on flood center of the floodplain map using 8 levels. (d) Result of executing QDISPLAY on flood center of the floodplain map using 7 levels. (e) Result of executing QDISPLAY on flood center of the floodplain map using 6 levels.

TABLE VII
QUADTREE TRUNCATION STATISTICS FOR EACH MAP

Depth of Tree	Land use Map		Topography Map		Floodplain Map	
	# of Nodes	% Reduced	# of Nodes	% Reduced	# of Nodes	% Reduced
10	38233	00.00	33349	00.00	6941	00.00
9	22089	44.22	18517	44.47	4473	35.55
8	9489	75.18	7473	77.59	2297	66.91
7	3341	91.26	2537	92.39	1093	84.26
6	1057	97.23	833	97.50	529	92.38
5	309	99.19	296	99.19	213	96.94
4	85	99.78	77	99.77	77	98.89
3	21	99.95	21	99.94	21	99.70
2	5	99.99	5	99.99	5	99.93
1	1	99.99	1	99.99	1	99.99

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