CS 4204 Computer Graphics

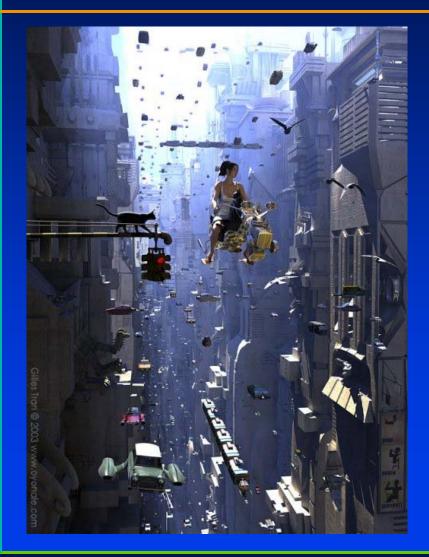
Introduction to Ray Tracing

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Reference: Ed Angle, Interactive Computer Graphics, University of New Mexico, class notes

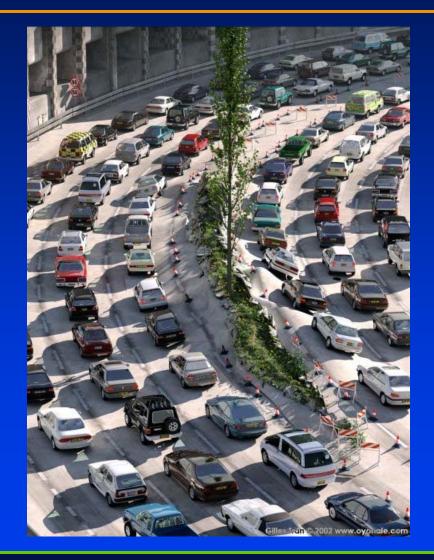










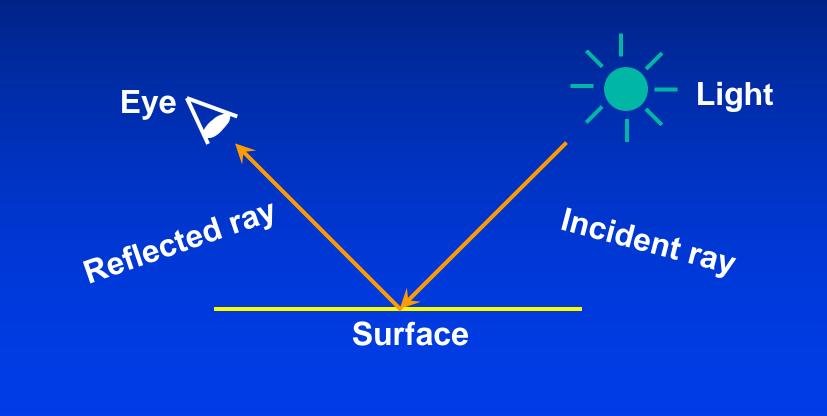






The Basic Idea

Simulate light rays from light source to eye



"Forward" Ray-Tracing

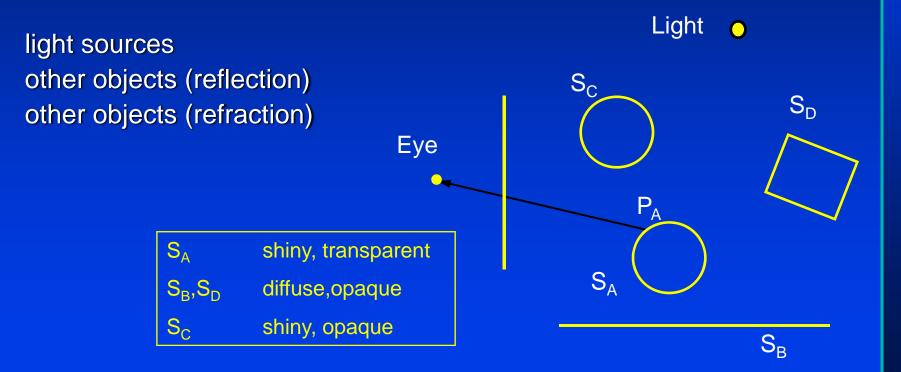
Trace rays from light Lots of work for little return \bigcirc Light Image Light Rays Plane Eye < **Object**

Scene

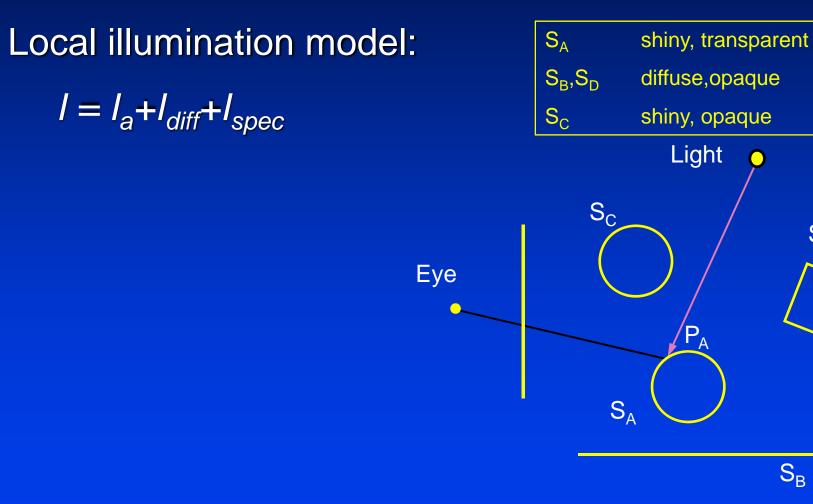
 S_A shiny, transparent S_B, S_D diffuse, opaque Light 0 S_{C} shiny, S_{C} opaque S_{D} Eye 0 \mathbf{S}_{A} **Image Plane** S_B

Three sources of light

The light that point P_A emits to the eye comes from:



Directly from light source



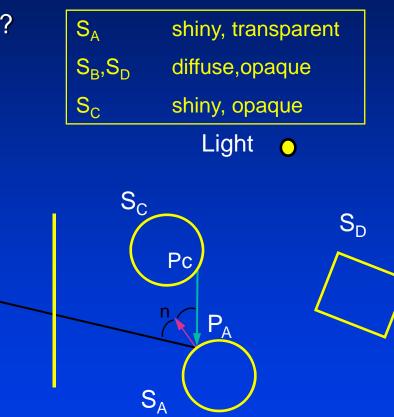
 S_{D}

 S_B

Reflection

What is the color that is reflected to P_A ? *The color of* P_C . What is the color of P_C ?

Eye





Reflection

What is the light that is reflected to P_A ? S_A shiny, transparent S_B, S_D diffuse,opaque The color of P_{C} as viewed by P_{A} S_{C} shiny, opaque What is the color of P_{C} reflected towards P_{A} ? Light \bigcirc Just like P_A : S_C S_{D} raytrace P_c i.e compute the Eye three contributions from P_A Light sources 1. Reflection 2. S_A refraction 3. S_B

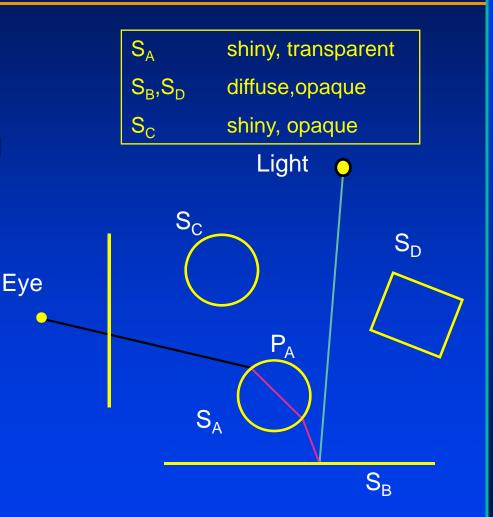
Refraction

Transparent materials

How do you compute the refracted contribution?

You raytrace the refracted ray.

- 1. Lights
- 2. Reflection
- 3. Refraction



What are we missing?

 Diffuse objects do not receive light from other objects.

Three sources of light together

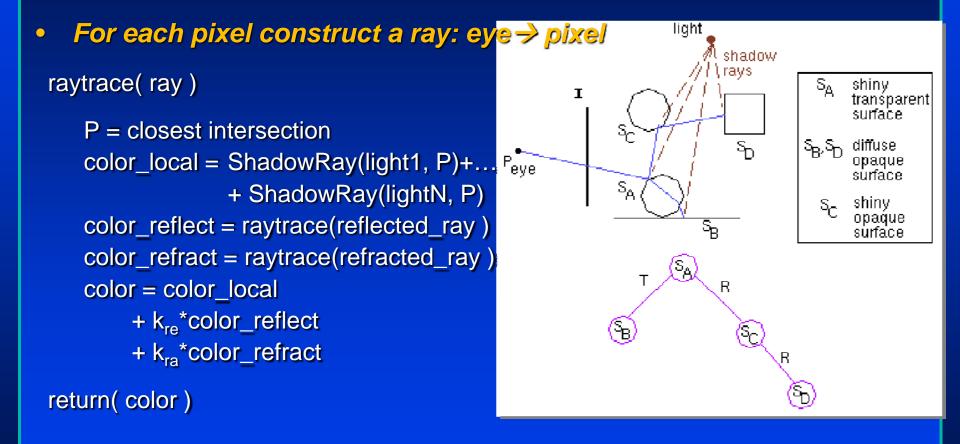
Eye

The color that the pixel is assigned comes

from: light sources other objects (reflection) other objects (refraction)

It is more convenient to trace the rays from the eye to the scene (backwards) S_A shiny, transparent S_B, S_D diffuse,opaque S_c shiny, opaque Light S_C SD PΔ S_A S_B

Backwards Raytracing Algoritm



How many levels of recursion do we use?

- The more the better.
- Infinite reflections at the limit.

Stages of raytracing

- Setting the camera and the image plane
- Computing a ray from the eye to every pixel and trace it in the scene
- Object-ray intersections
- Shadow, reflected and refracted ray at each intersection

Setting up the camera

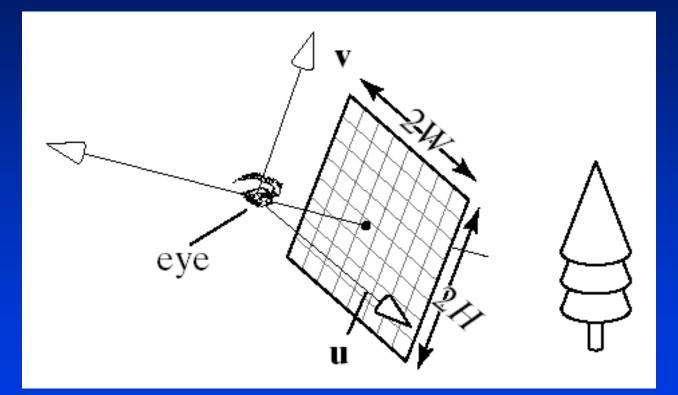
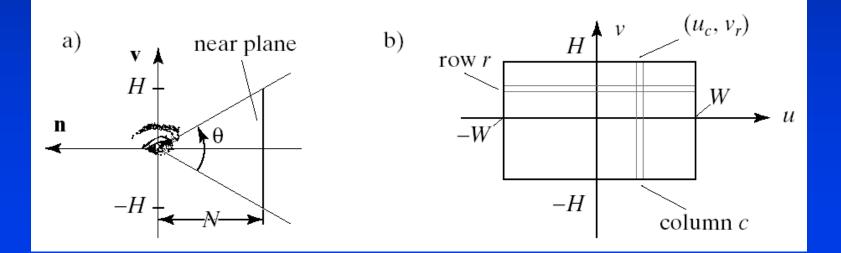


Image parameters

- Width 2W, Height 2H
 Number of pixels nCols x nRows
- Camera coordinate system (eye, u,v,n)
- Image plane at -N

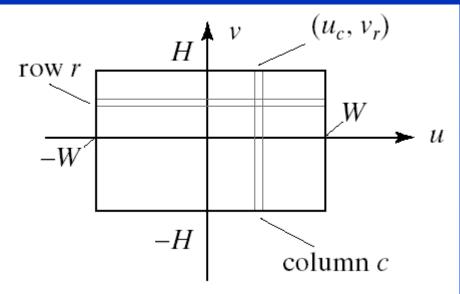


Pixel coordinates in camera coordinate system

• Pixel P(r,c) has coordinates in camera space:

$$u_c = -W + W rac{2c}{nCols}, \quad c = 0, 1, \dots, nCols - 1,$$

 $v_r = -H + H rac{2r}{nRows}, \quad r = 0, 1, \dots, nRows - 1$



Ray through pixel

Pixel location

Camera coordinates : $P(r,c) = (u_c, v_r, -N)$ Wolrd coordinates : $P(r,c) = eye - N\mathbf{n} + u_c\mathbf{u} + v_r\mathbf{v}$

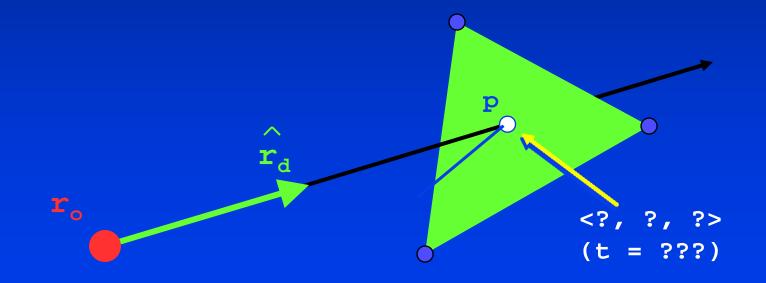
Ray through pixel:

$$ray(r,c,t) = eye + t(P(r,c) - eye)$$

$$ray(r,c,t) = eye + t(-Nn + w(\frac{2c}{nCols} - 1)u + H(\frac{2r}{nRows} - 1)v)$$

Triangle Intersection

- Want to know: at what point (p) does ray intersect triangle?
- Compute lighting, reflected rays, shadowing from that point



Triangle Intersection

• Step 1 : Intersect with plane

(Ax + By + Cz + D = 0)

r_o

 $\mathbf{p} = -(\hat{\mathbf{n}} \cdot \mathbf{r}_{o} + \mathbf{D}) / (\hat{\mathbf{n}} \cdot \hat{\mathbf{r}}_{d})$

 \mathbf{r}_{d}

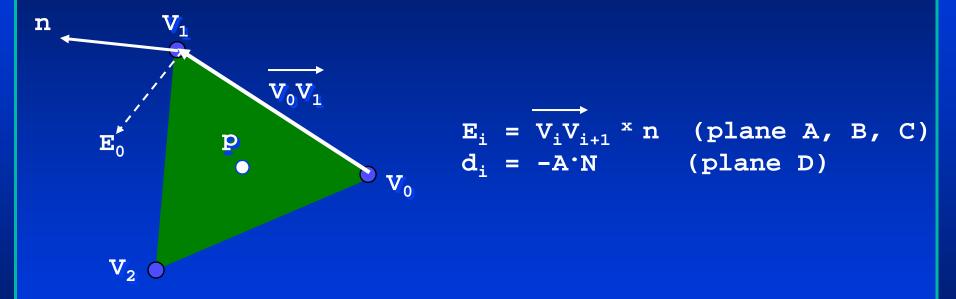
Plane normal

p

 $n = \langle A, B, C \rangle$

Triangle Intersection

Step 2 : Check against triangle edges

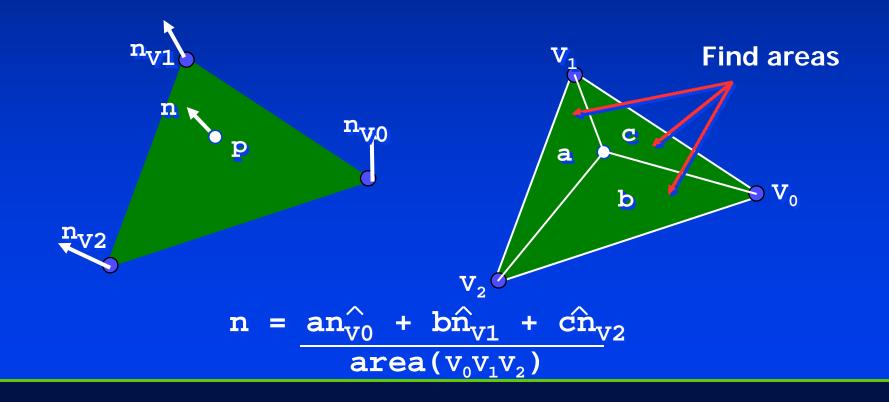


Plug p into $(p \cdot E_i + d_i)$ for each edge

if signs are all positive or negative, point is inside triangle!

Triangle Normals

- Could use plane normals (flat shading)
- Better to interpolate from vertices



Ray-object intersections

• Unit sphere at origin - ray intersection:

$$ray(t) = S + ct$$

Sphere(P) = |P| - 1 = 0

$$Sphere(ray(t)) = 0 \Rightarrow$$
$$|S + ct| - 1 = 0 \Rightarrow (S + ct)(S + ct) - 1 = 0 \Rightarrow$$
$$|c|^{2}t^{2} + 2(S \cdot c)t + |S|^{2} - 1 = 0$$

That's a quadratic equation

Solving a quadratic equation

$$|\mathbf{c}|^{2}t^{2} + 2(S \cdot \mathbf{c})t + |S|^{2} - 1 = 0$$

 $At^{2} + 2Bt + C = 0$

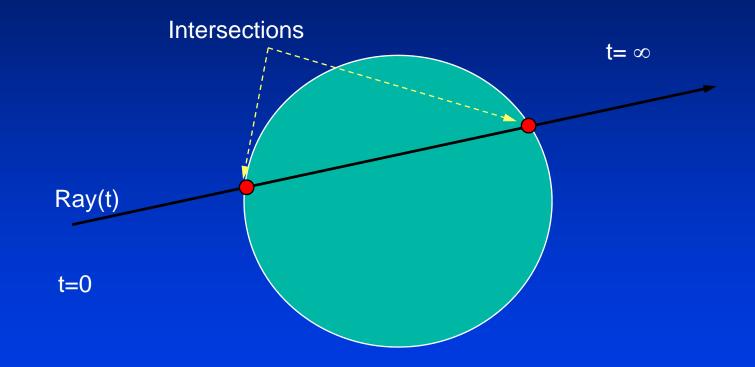
$$t_h = -\frac{B}{A} \pm \frac{\sqrt{B^2 - AC}}{A}$$
$$t_h = -\frac{S \cdot \mathbf{c}}{|\mathbf{c}|^2} \pm \frac{\sqrt{(S \cdot \mathbf{c})^2 - |\mathbf{c}|^2 (|S|^2 - 1)}}{|\mathbf{c}|^2}$$

If $(B^2 - AC) = 0$ one solution

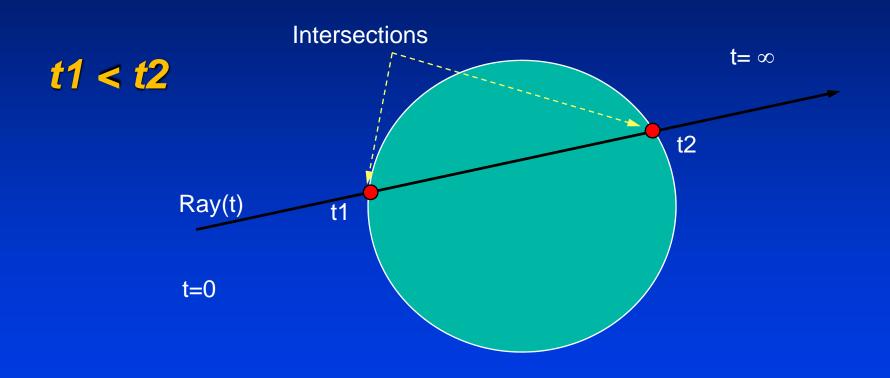
If $(B^2 - AC) < 0$ no solution

If $(B^2 - AC) > 0$ two solutions

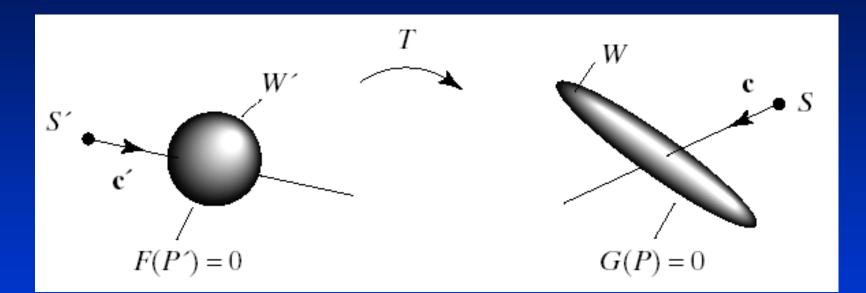
First intersection?



First intersection?

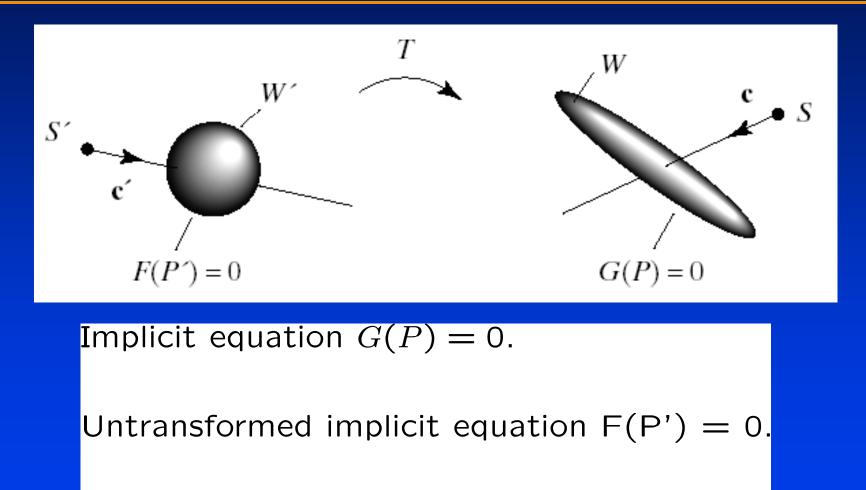


Transformed primitives?



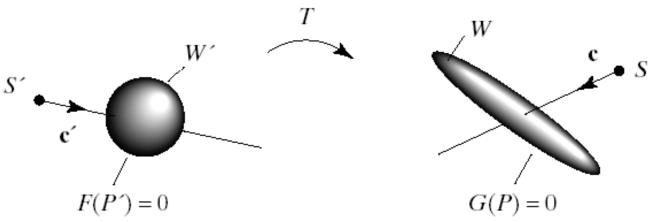
• Where does S+ct hit the transformed sphere G?

Linear transformation



$$P = MP' \Rightarrow P' = M^{-1}P$$

Linear transformation



$$P = MP' \Rightarrow P' = M^{-1}P$$

$$F(P') = F(T^{-1}(P)) = 0 \Rightarrow F(T^{-1}(P)) = 0$$

$$F(T^{-1}(S + ct)) = 0 \Rightarrow$$

$$F(T^{-1}(S) + T^{-1}(ct)) = 0$$

Which means that we can intersect the inverse transformed ray with the untransformed primitive.

Final Intersection

Inverse transformed ray

$$\tilde{r}(t) = M^{-1} \begin{pmatrix} S_x \\ S_y \\ S_z \\ 1 \end{pmatrix} + M^{-1} \begin{pmatrix} c_x \\ c_y \\ c_z \\ 0 \end{pmatrix} = \tilde{S}' + \tilde{c}'t$$

- Drop 1 and O to get S'+c't
- For each object
 - Inverse transform ray getting S'+c't
 - Find intersection t_h
 - Use t_h in the untransformed ray S+ct to find the intersection

Shadow ray

• For each light intersect shadow ray with all objects.

Lights

- If no intersection is found apply local illumination at intersection
- If in shadow no contribution

Reflected ray

• Raytrace the reflected ray

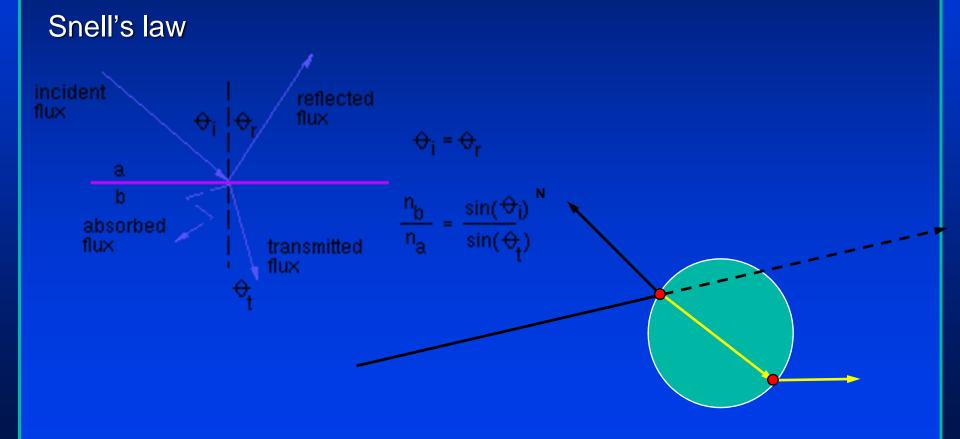
$$Ray(t) = A + ct$$

$$Ray_{rf}(t) = P + vt$$

$$v = -2(N \cdot c)N + c$$
Ray(t)
Ra

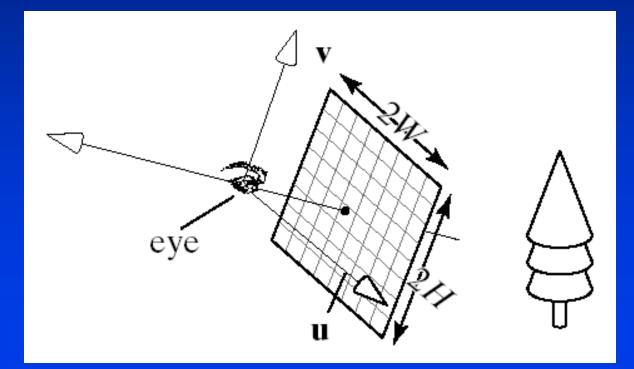
Refracted ray

• Raytrace the refracted ray



Add all together

color(r,c) = color_shadow_ray + Kf*color_rf + Kr*color_rfa



Raytracing

for each pixel on screen

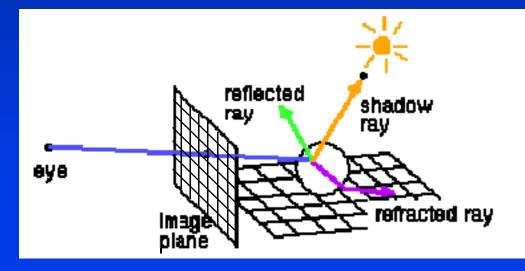
determine ray from eye through pixel

find closest intersection of ray with an object

cast off reflected and refracted ray, recursively

calculate pixel colour, draw pixel

end



Acceleration

- 1280x1024 image with 10 rays/pixel
- 1000 objects (triangle, CSG, NURBS)
- 3 levels recursion

39321600000 intersection tests

100000 tests/second -> 109 days!

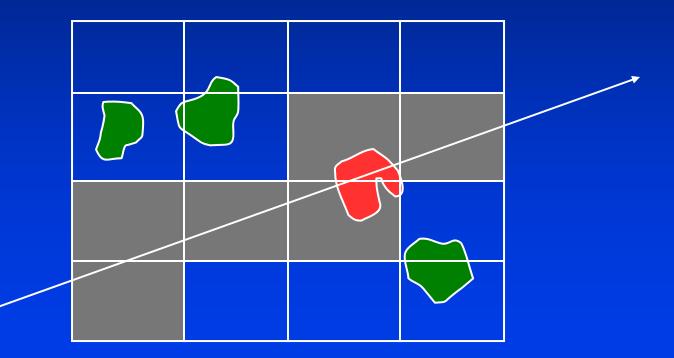
Must use an acceleration method!

Bounding volumes

• Use simple shape for quick test, keep a hierarchy

Space Subdivision

- Break your space into pieces
- Search the structure linearly



Parallel Processing

• You can always throw more processors at it.

Summary: Raytracing

Recursive algorithm

Function Main

for each pixel (c,r) on screen

determine ray r_{c,r} from eye through pixel

```
color(c,r) = raytrace(r_{c,r})
```

end for

end

```
function raytrace(r)
```

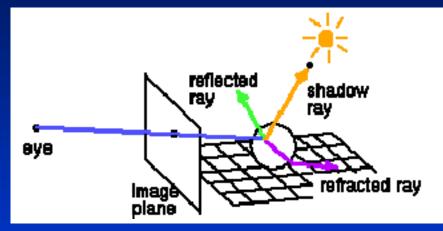
find closest intersection P of ray with objects

clocal = Sum(shadowRays(P,Lighti))

$$c_{re} = raytrace(r_{re})$$

 $c_{ra} = raytrace(r_{ra})$

```
return c = clocal+k_{re}^*c_{re} + k_{ra}^*c_{ra}
```



Advanced concepts

- Participating media
- Transculency
- Sub-surface scattering (e.g. Human skin)
- Photon mapping

Raytracing summary

- View dependent
- Computationally expensive
- Good for refraction and reflection effects